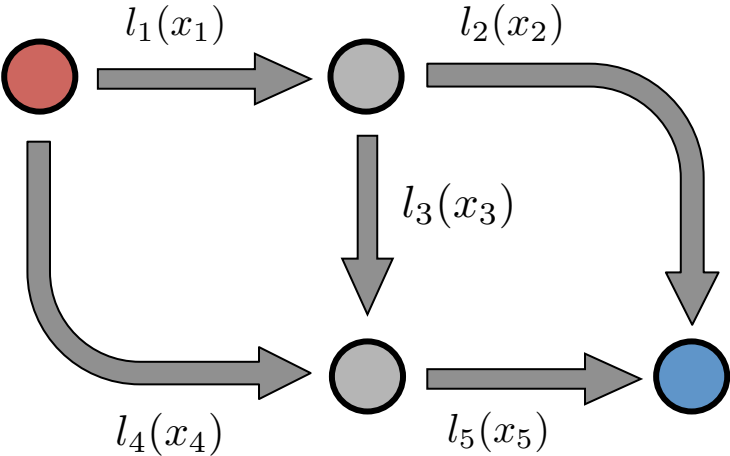


Queue-Routing Game

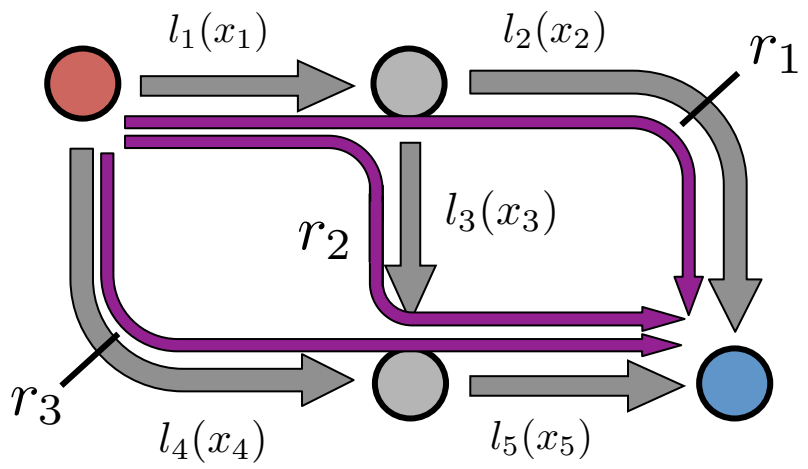
Dan, Eric, Lillian

UC Berkeley
April 8th, 2016

Routing Game Tutorial

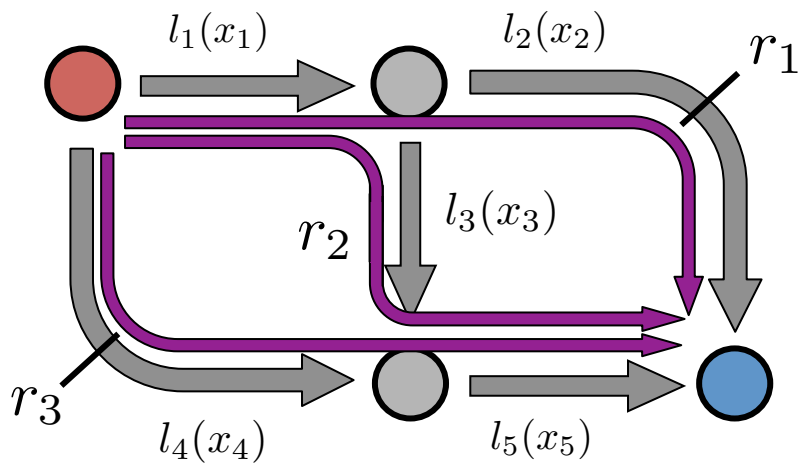


Edge & Route Flows



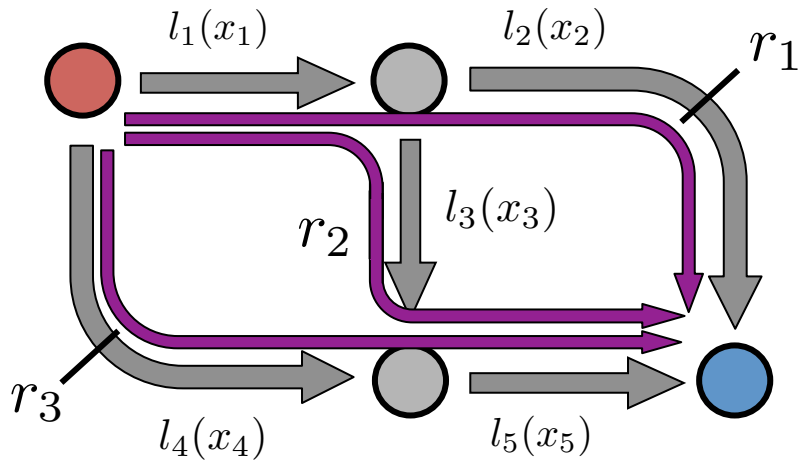
	Paths		
Edges	1	1	0
	1	0	0
	0	1	0
	0	0	1
	0	1	1
Routing Matrix	\mathbb{R}		

Edge & Route Flows



$$\begin{array}{c}
 \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} \\
 \text{Edge} \\
 \text{Flows}
 \end{array}
 \begin{array}{c}
 = \\
 \text{Edges}
 \end{array}
 \begin{array}{c}
 \text{Routes} \\
 \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \\
 \text{Routing} \\
 \text{Matrix} \quad \mathbb{R}
 \end{array}
 \times
 \begin{array}{c}
 \begin{bmatrix} x_1^R \\ x_2^R \\ x_3^R \end{bmatrix} \\
 \text{Route} \\
 \text{Flows}
 \end{array}
 \end{array}$$

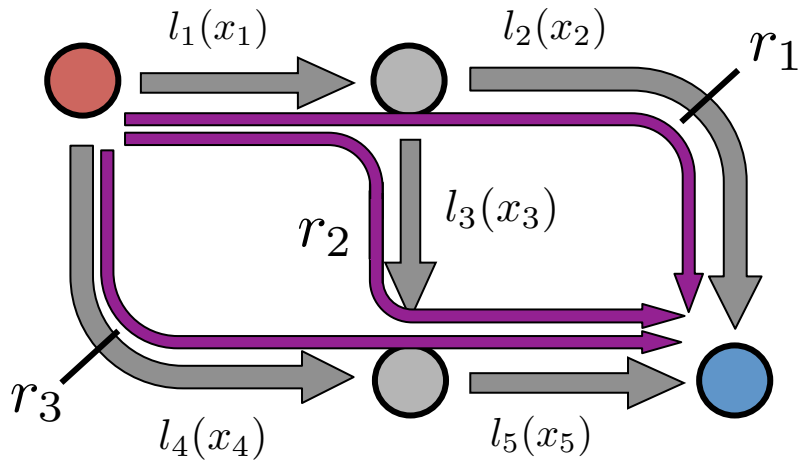
Edge & Route Flows



$$\begin{array}{c} \text{Edge} \\ \text{Flows} \end{array} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{array}{c} \text{Edges} \\ \text{Routing} \\ \text{Matrix} \end{array} \begin{array}{c} \text{Routes} \\ \mathbb{R} \end{array} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \times \begin{array}{c} \text{Route} \\ \text{Flows} \end{array} \begin{bmatrix} x_1^R \\ x_2^R \\ x_3^R \end{bmatrix}$$

$$x = \mathbb{R} \times x^R$$

Edge & Route Latencies



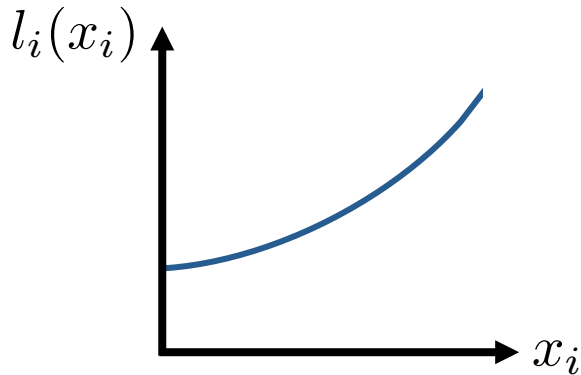
$$\begin{array}{c} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} \\ \text{Edge} \\ \text{Flows} \end{array} = \begin{array}{c} \text{Edges} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \\ \text{Routing} \\ \text{Matrix } \mathbb{R} \end{array} \times \begin{array}{c} \text{Routes} \\ \begin{bmatrix} x_1^R \\ x_2^R \\ x_3^R \end{bmatrix} \\ \text{Route} \\ \text{Flows} \end{array}$$

$$x = \mathbb{R} \times x^R$$

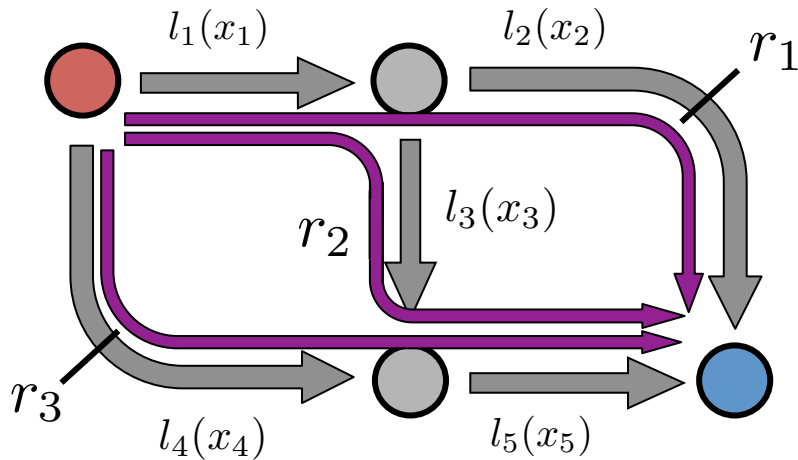
Latencies

$$\begin{array}{l} \text{Edge} \\ \text{Path} \end{array} \quad l(x) = \begin{bmatrix} l_1 & l_2 & l_3 & l_4 & l_5 \end{bmatrix}$$

$$\begin{array}{l} \text{Edge} \\ \text{Path} \end{array} \quad l^R(x) = \begin{bmatrix} l_1^R & l_2^R & l_3^R \end{bmatrix}$$



Edge & Route Latencies



$$\begin{array}{c} \text{Edge} \\ \text{Flows} \end{array} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{array}{c} \text{Edges} \\ \text{Routing} \\ \text{Matrix} \end{array} \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \times \begin{array}{c} \text{Routes} \\ \text{Route} \\ \text{Flows} \end{array} \begin{bmatrix} x_1^R \\ x_2^R \\ x_3^R \end{bmatrix}$$

\mathbb{R}

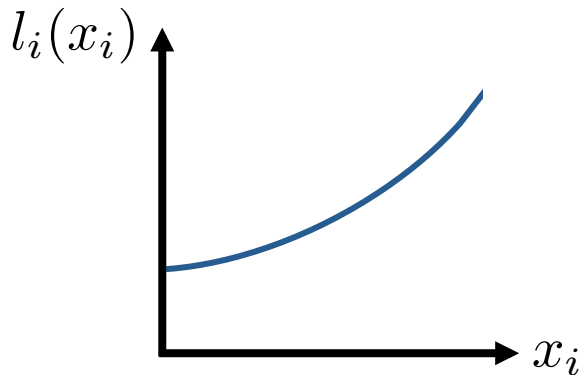
$$x = \mathbb{R} \times x^R$$

Latencies

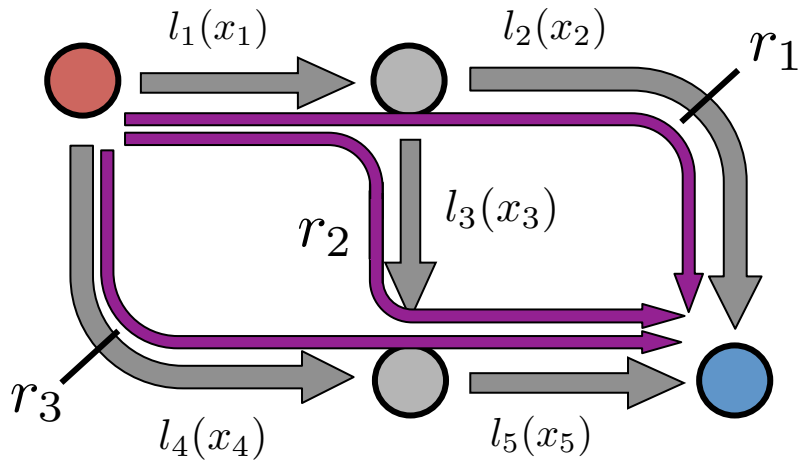
$$\text{Edge} \quad l(x) = \begin{bmatrix} l_1 & l_2 & l_3 & l_4 & l_5 \end{bmatrix}$$

$$\text{Path} \quad l^R(x) = \begin{bmatrix} l_1^R & l_2^R & l_3^R \end{bmatrix}$$

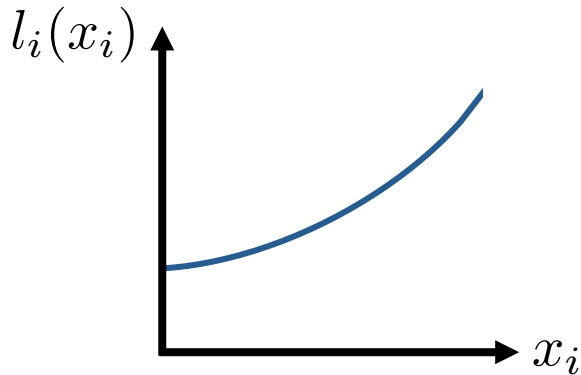
$$l \times \mathbb{R} = l^R$$



Potential Function



Potential Function $P(x) = \sum_e \int_0^{x_e} l_e(u) du$



$$\begin{matrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} \\ \text{Edge Flows} \end{matrix} = \begin{matrix} \text{Edges} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \\ \text{Routing Matrix } \mathbb{R} \end{matrix} \times \begin{matrix} \text{Routes} \\ \begin{bmatrix} x_1^R \\ x_2^R \\ x_3^R \end{bmatrix} \\ \text{Route Flows} \end{matrix}$$

$$x = \mathbb{R} \times x^R$$

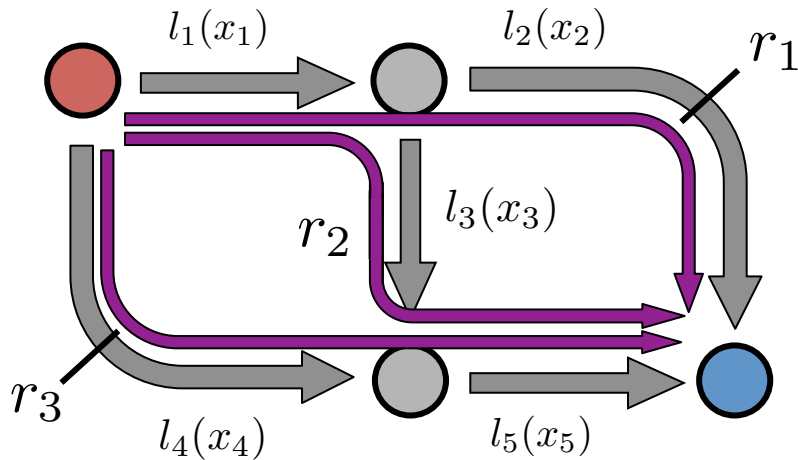
Latencies

Edge $l(x) = [l_1 \ l_2 \ l_3 \ l_4 \ l_5]$

Path $l^R(x) = [l_1^R \ l_2^R \ l_3^R]$

$$l \times \mathbb{R} = l^R$$

Potential Function



Potential
Function

$$P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\nabla_x P(x) = l(x)$$

$$\begin{matrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} \\ \text{Edge} \\ \text{Flows} \end{matrix} = \begin{matrix} \text{Edges} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \\ \text{Routing} \\ \text{Matrix } \mathbb{R} \end{matrix} \times \begin{matrix} \text{Routes} \\ \begin{bmatrix} x_1^R \\ x_2^R \\ x_3^R \end{bmatrix} \\ \text{Route} \\ \text{Flows} \end{matrix}$$

$$x = \mathbb{R} \times x^R$$

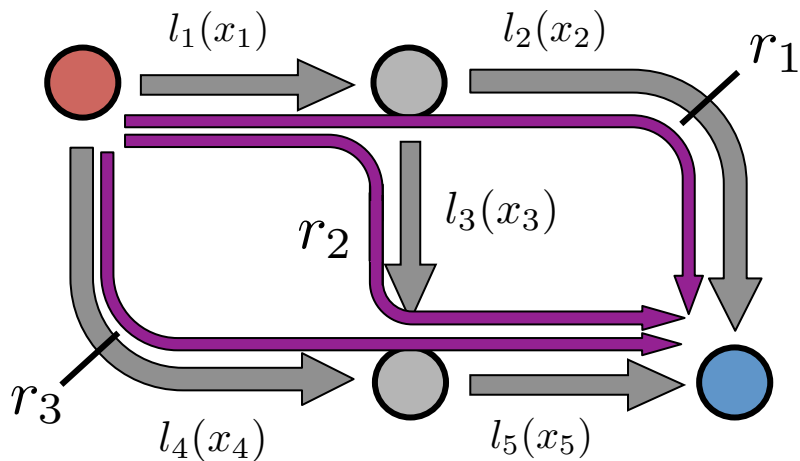
Latencies

$$\text{Edge} \quad l(x) = \begin{bmatrix} l_1 & l_2 & l_3 & l_4 & l_5 \end{bmatrix}$$

$$\text{Path} \quad l^R(x) = \begin{bmatrix} l_1^R & l_2^R & l_3^R \end{bmatrix}$$

$$l \times \mathbb{R} = l^R$$

Routing Game Formulations



Routing Matrix

$$\mathbb{R} = \begin{matrix} & \text{Routes} \\ \text{Edges} & \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \end{matrix}$$

Flows

$$x = \mathbb{R} \times x^R$$

Latencies

$$l \times \mathbb{R} = l^R$$

Potential Function

$$P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\min_{x^R} P(x)$$

$$\text{s.t. } x^R \geq 0, x = \mathbb{R}x^R,$$

$$\sum_r x_r^R = s$$

Path Formulation

OR

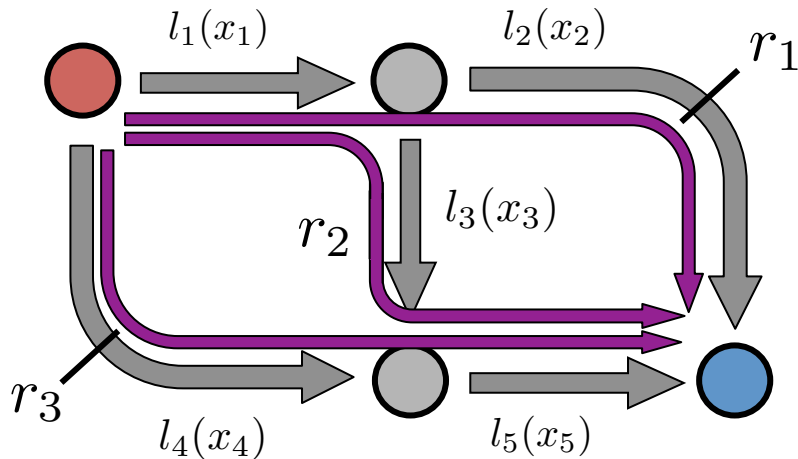
$$\min_x P(x)$$

$$\text{s.t. } x \geq 0,$$

$$Gx = S$$

Edge Formulation

Routing Game Formulations



Routing Matrix

$$\mathbb{R} = \begin{matrix} & \text{Edges} & \begin{matrix} \text{Routes} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \end{matrix} \end{matrix}$$

Flows

$$x = \mathbb{R} \times x^R$$

Latencies

$$l \times \mathbb{R} = l^R$$

Potential Function

$$P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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Path Formulation

OR

$$\min_x P(x)$$

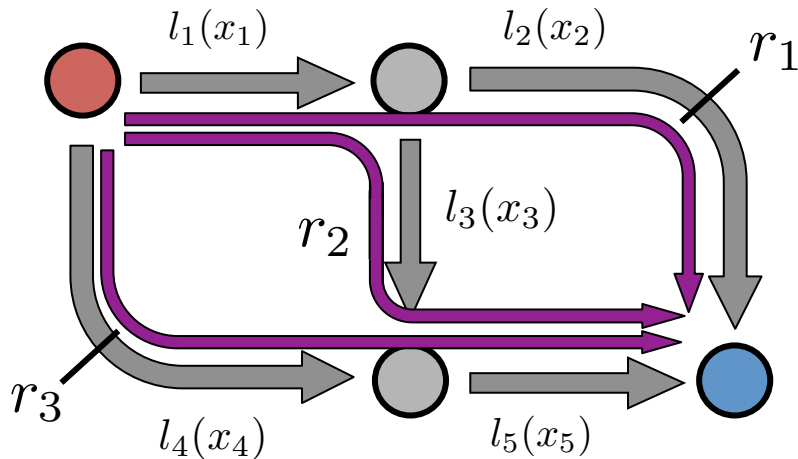
$$\text{s.t. } x \geq 0,$$

$$Gx = S$$

Edge Formulation

KEY ARGUMENTS

Routing Game Formulations



Routing Matrix

$$\mathbb{R} = \begin{matrix} & \text{Edges} & \begin{matrix} \text{Routes} \\ \begin{matrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{matrix} \end{matrix} \end{matrix}$$

Flows

$$x = \mathbb{R} \times x^R$$

Latencies

$$l \times \mathbb{R} = l^R$$

Potential Function

$$P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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$$\text{s.t. } x^R \geq 0, x = \mathbb{R}x^R,$$

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Path Formulation

OR

$$\min_x P(x)$$

$$\text{s.t. } x \geq 0,$$

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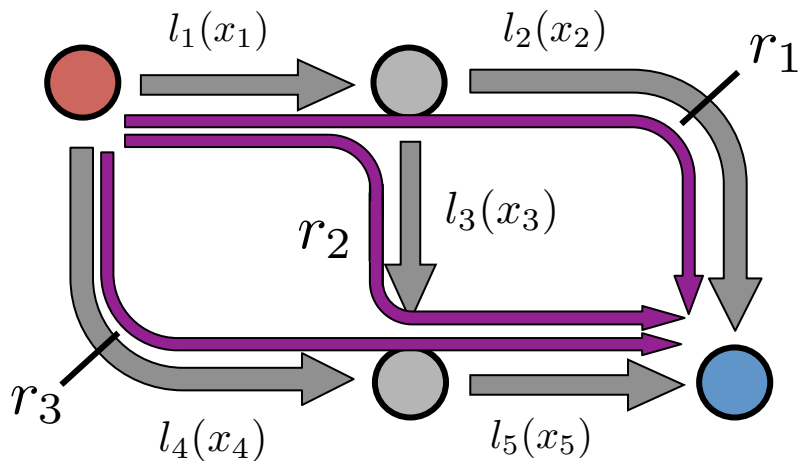
Edge Formulation

KEY ARGUMENTS

First Order Optimality

$$\underbrace{\nabla P(x)}_{l(x)} + \lambda \cdot \text{CONST} - \underbrace{\mu}_{\geq 0} = 0$$

Routing Game Formulations



Routing Matrix

$$\mathbb{R} = \begin{matrix} & \text{Edges} & \begin{matrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{matrix} \end{matrix}$$

Flows

$$x = \mathbb{R} \times x^R$$

Latencies

$$l \times \mathbb{R} = l^R$$

Potential Function

$$P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\min_{x^R} P(x)$$

$$\text{s.t. } x^R \geq 0, x = \mathbb{R}x^R,$$

$$\sum_r x_r^R = s$$

Path Formulation

OR

$$\min_x P(x)$$

$$\text{s.t. } x \geq 0,$$

$$Gx = S$$

Edge Formulation

KEY ARGUMENTS

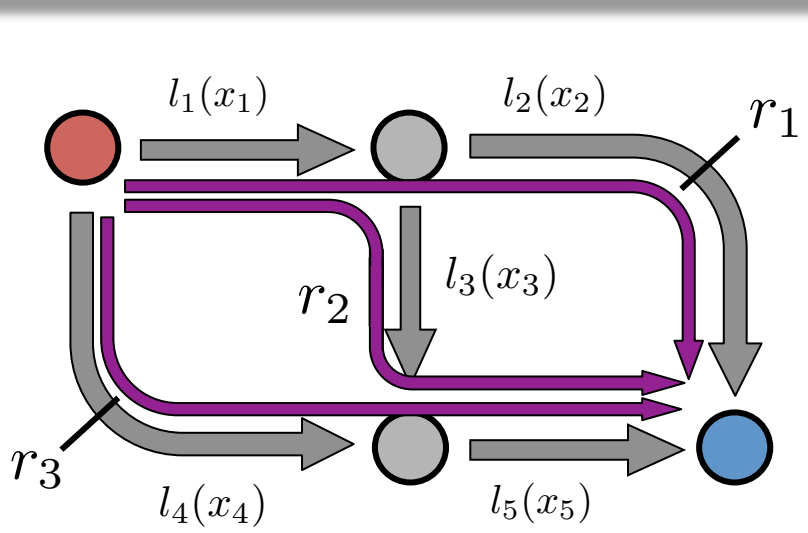
First Order Optimality

$$\underbrace{\nabla P(x)}_{l(x)} + \lambda \cdot \text{CONST} - \underbrace{\mu}_{\geq 0} = 0$$



Wardrop Equilibrium

Wardrop Equilibrium



Routing Matrix $\mathbb{R} =$ Edges $\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$ Routes

Flows $x = \mathbb{R} \times x^R$

Latencies $l \times \mathbb{R} = l^R$

Potential Function $P(x) = \sum_e \int_0^{x_e} l_e(u) du$

$\min_{x^R} P(x)$
 s.t. $x^R \geq 0, x = \mathbb{R}x^R,$
 $\sum_r x_r^R = s$
Path Formulation

OR

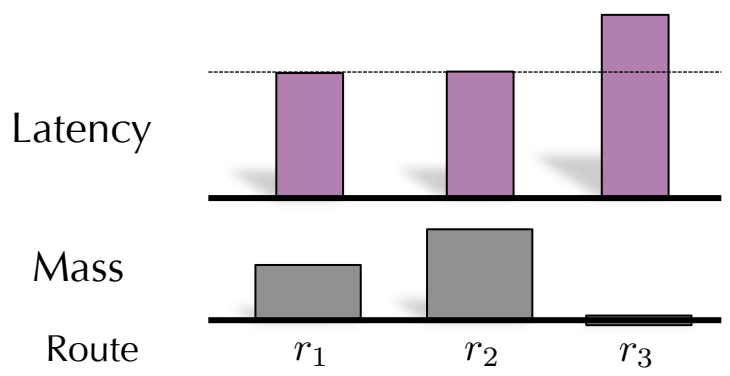
$\min_x P(x)$
 s.t. $x \geq 0,$
 $Gx = S$
Edge Formulation

KEY ARGUMENTS

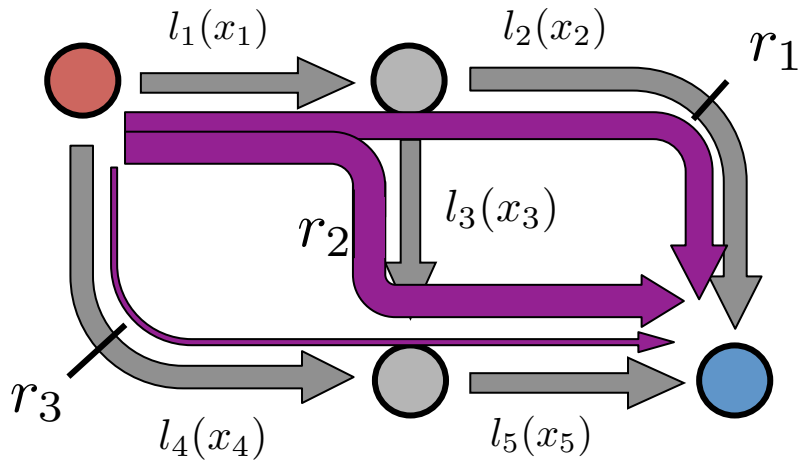
First Order Optimality

$\underbrace{\nabla P(x)}_{l(x)} + \lambda \cdot \text{CONST} - \underbrace{\mu}_{\geq 0} = 0$

Wardrop Equilibrium



Path Formulation



Routing Matrix

$$\mathbb{R} = \begin{matrix} & \text{Edges} & \begin{matrix} \text{Routes} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \end{matrix} \end{matrix}$$

Flows

$$x = \mathbb{R} \times x^R$$

Latencies

$$l \times \mathbb{R} = l^R$$

Path Formulation

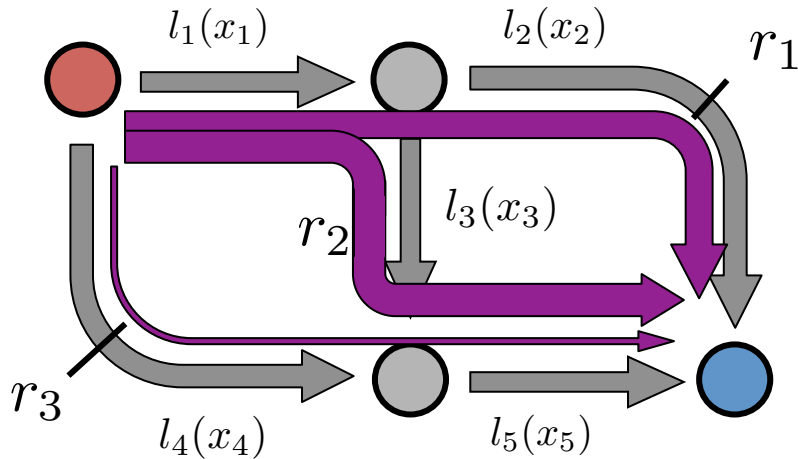
$$\min_{x^R} P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x^R \geq 0, \quad x = \mathbb{R}x^R,$$

$$\sum_r x_r^R = s$$

First Order Optimality...

Path Formulation



Routing Matrix $\mathbb{R} =$ Edges $\begin{matrix} \text{Routes} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \end{matrix}$

Flows $x = \mathbb{R} \times x^R$
Latencies $l \times \mathbb{R} = l^R$

Path Formulation

$$\min_{x^R} P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

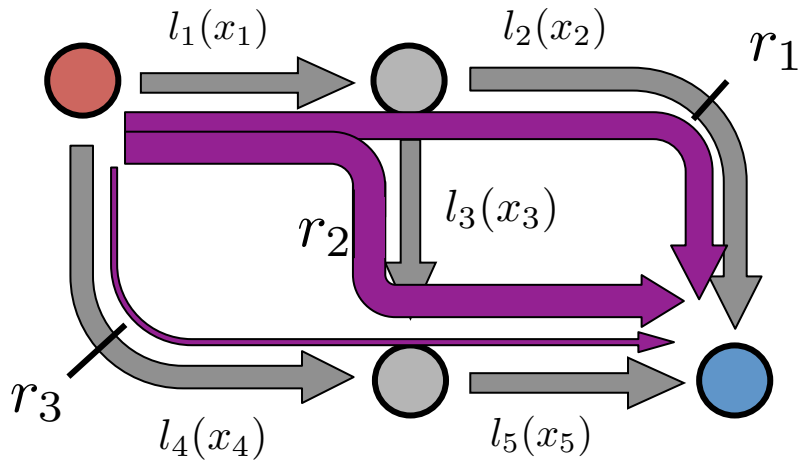
$$\text{s.t. } x^R \geq 0, \quad x = \mathbb{R}x^R,$$

$$\sum_r x_r^R = s$$

First Order Optimality...

Gradient... $\nabla_{x^R} P = l(x)\mathbb{R} = l^R(x)$

Path Formulation



Path Formulation

$$\min_{x^R} P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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$$\text{Routing Matrix } \mathbb{R} = \begin{matrix} & \text{Edges} & \begin{matrix} \text{Routes} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \end{matrix} \end{matrix}$$

$$\text{Flows } x = \mathbb{R} \times x^R$$

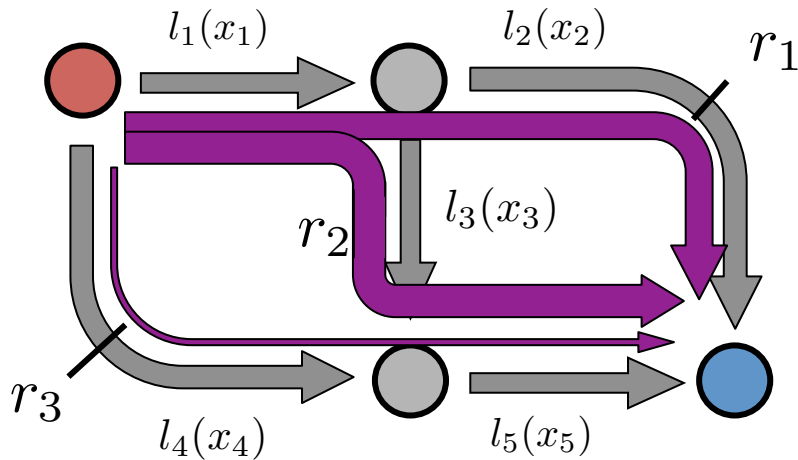
$$\text{Latencies } l \times \mathbb{R} = l^R$$

First Order Optimality...

Gradient... $\nabla_{x^R} P = l(x)\mathbb{R} = l^R(x)$

$$\mathcal{L}(x, \lambda, \mu) = P(x) - \lambda(\mathbf{1}^T x^R - s) - \mu^T x^R$$

Path Formulation



		Routes
Routing Matrix	$\mathbb{R} =$	Edges $\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$
Flows	$x = \mathbb{R} \times x^R$	
Latencies	$l \times \mathbb{R} = l^R$	

Path Formulation

$$\min_{x^R} P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x^R \geq 0, \quad x = \mathbb{R}x^R,$$

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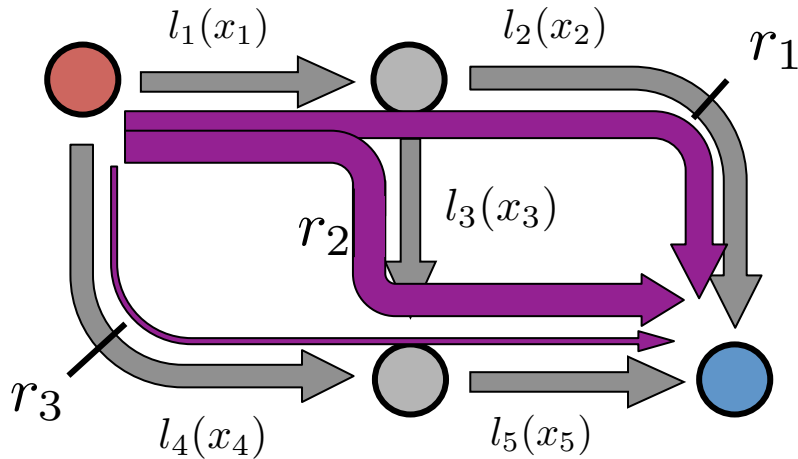
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$$\frac{\partial \mathcal{L}}{\partial x^R} : \quad l^R(x) = \lambda \mathbf{1}^T + \mu^T$$

Path Formulation



Path Formulation

$$\min_{x^R} P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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Routing Matrix $\mathbb{R} =$ Edges $\begin{matrix} \text{Routes} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \end{matrix}$

Flows $x = \mathbb{R} \times x^R$

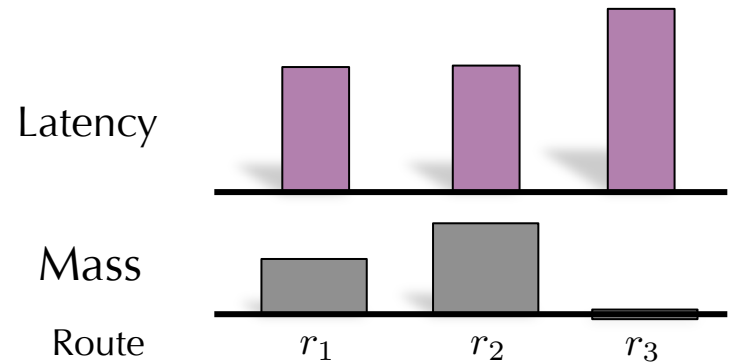
Latencies $l \times \mathbb{R} = l^R$

First Order Optimality...

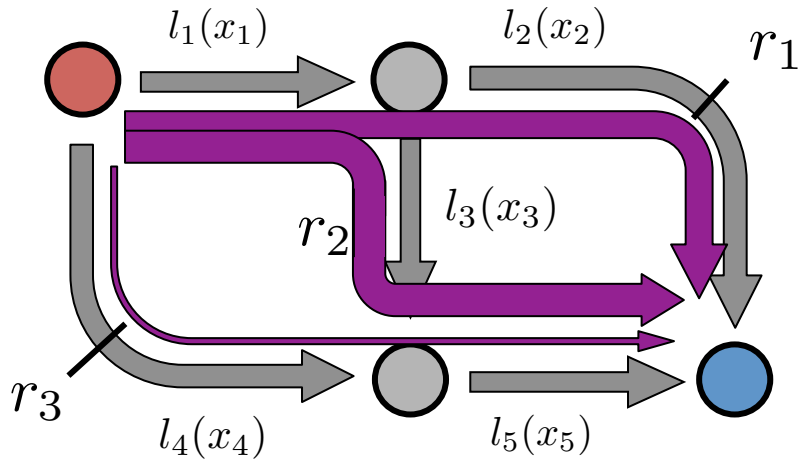
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Path Formulation



Path Formulation

$$\min_{x^R} P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x^R \geq 0, \quad x = \mathbb{R}x^R,$$

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Routing Matrix $\mathbb{R} =$ Edges $\begin{matrix} \text{Routes} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \end{matrix}$

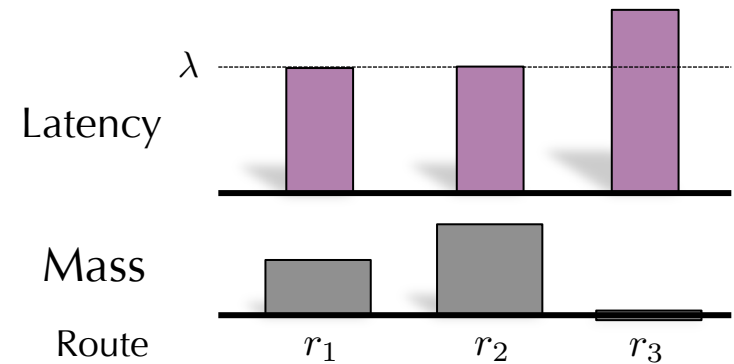
Flows $x = \mathbb{R} \times x^R$
 Latencies $l \times \mathbb{R} = l^R$

First Order Optimality...

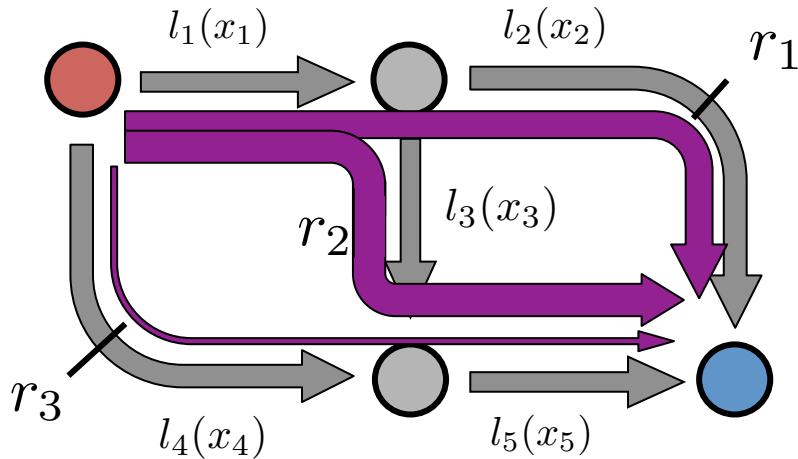
Gradient... $\nabla_{x^R} P = l(x)\mathbb{R} = l^R(x)$

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Path Formulation



Routing Matrix $\mathbb{R} =$ Edges $\begin{matrix} \text{Routes} \\ \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} \end{matrix}$

Flows $x = \mathbb{R} \times x^R$
 Latencies $l \times \mathbb{R} = l^R$

Path Formulation

$$\min_{x^R} P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x^R \geq 0, \quad x = \mathbb{R}x^R,$$

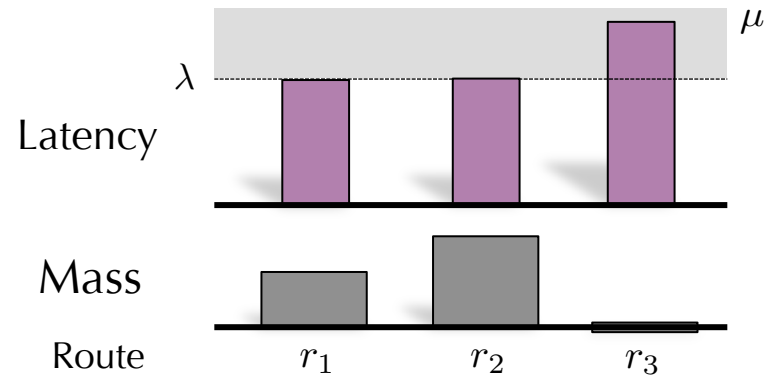
$$\sum_r x_r^R = s$$

First Order Optimality...

Gradient... $\nabla_{x^R} P = l(x)\mathbb{R} = l^R(x)$

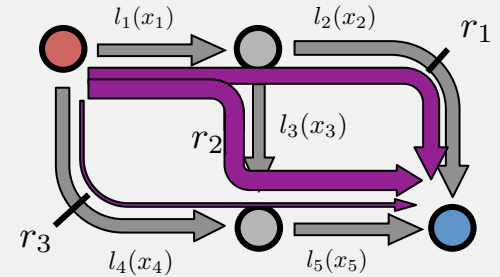
$$\mathcal{L}(x, \lambda, \mu) = P(x) - \lambda(\mathbf{1}^T x^R - s) - \mu^T x^R$$

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Path Formulation

Path Formulation

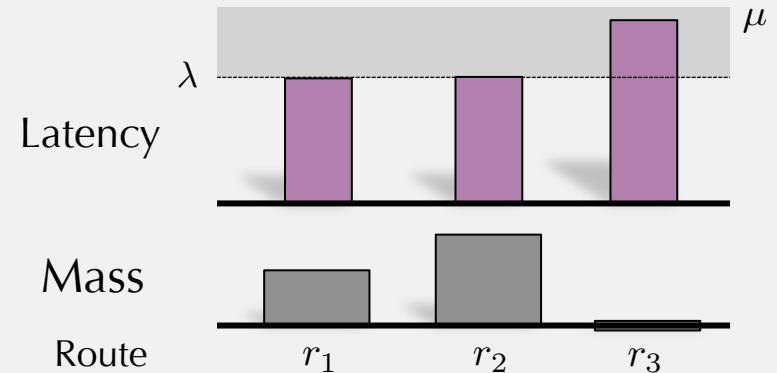


$$\min_{x^R} P(x) \quad \text{s.t.} \quad x^R \geq 0, \quad x = \mathbb{R}x^R, \quad \sum_r x_r^R = s$$

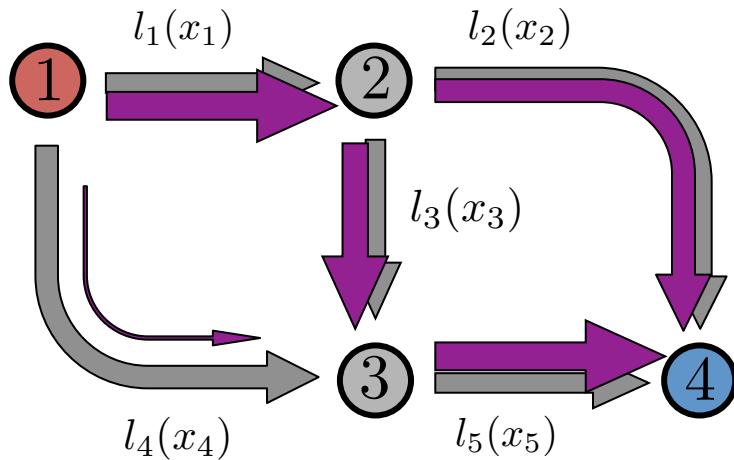
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Path Formulation

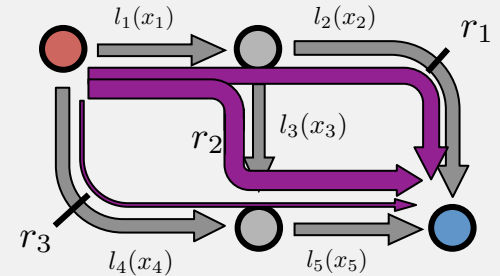


Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

Path Formulation

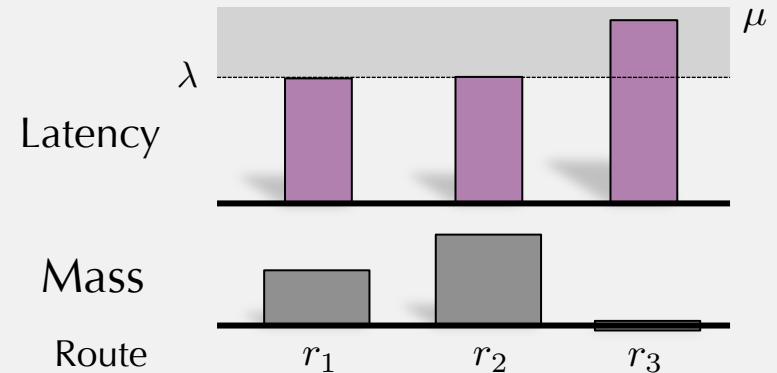


$$\min_{x^R} P(x) \quad \text{s.t. } x^R \geq 0, \quad x = \mathbb{R}x^R, \quad \sum_r x_r^R = s$$

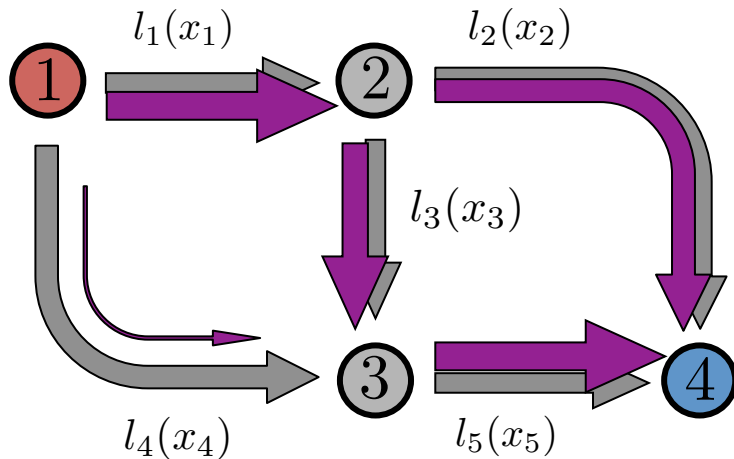
$$\text{Gradient...} \quad \nabla_{x^R} P = l(x)\mathbb{R} = l^R(x)$$

$$\mathcal{L}(x, \lambda, \mu) = P(x) - \lambda(\mathbf{1}^T x^R - s) - \mu^T x^R$$

$$\frac{\partial \mathcal{L}}{\partial x^R} : \quad l^R(x) = \lambda \mathbf{1}^T + \mu^T$$



Path Formulation



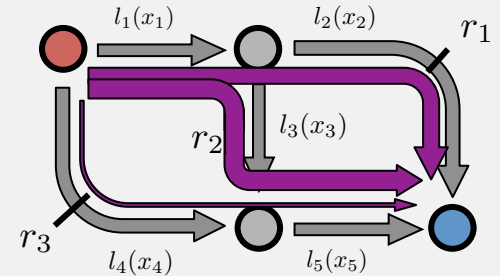
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Path Formulation

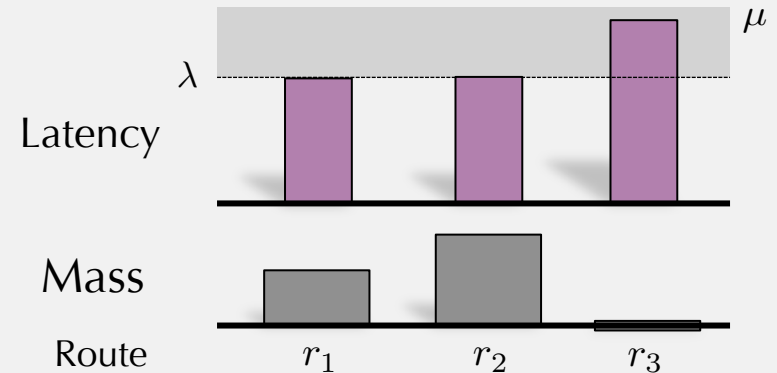


$$\min_{x^R} P(x) \text{ s.t. } x^R \geq 0, x = \mathbb{R}x^R, \sum_r x_r^R = s$$

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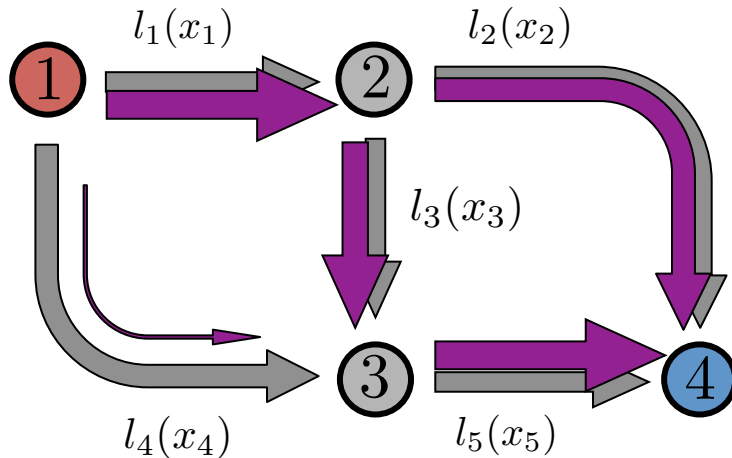
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Edge Formulation

First Order Optimality...



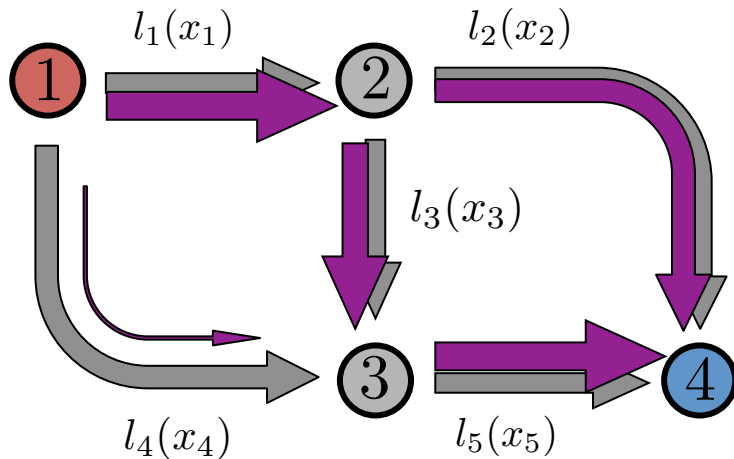
Edge Formulation

$$\min_x \quad P(x) = \sum_e \int_0^{x_e} l_e(u) \, du$$

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Edge Formulation



First Order Optimality...

Gradient... $\nabla_x P = l(x)$

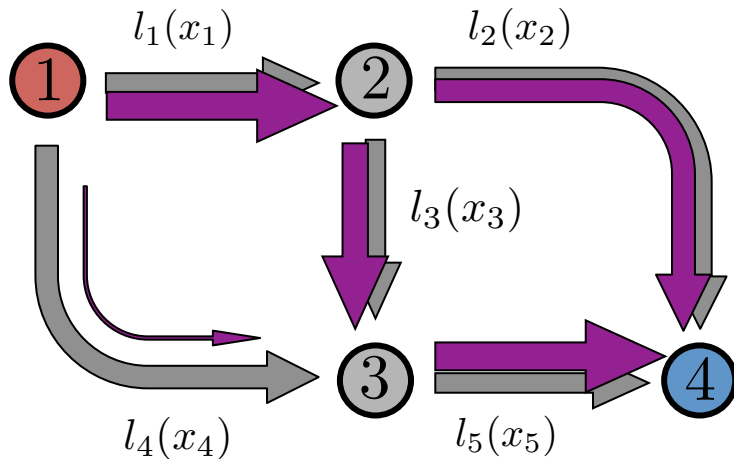
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Edge Formulation



Edge Formulation

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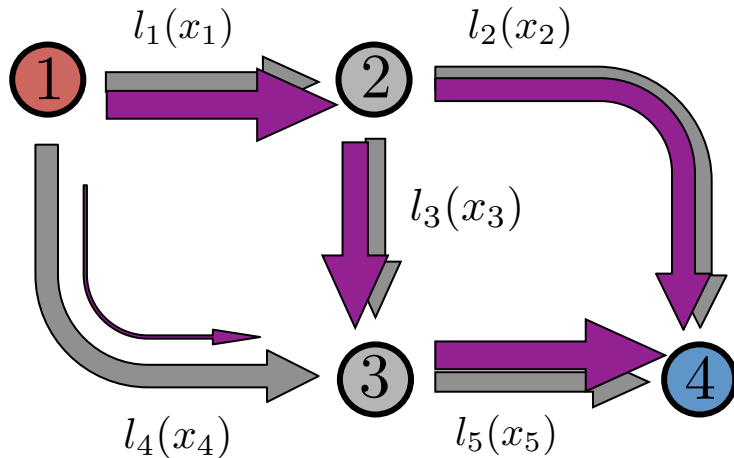
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

Edge Formulation



Edge Formulation

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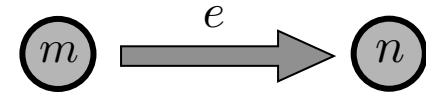
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First Order Optimality...

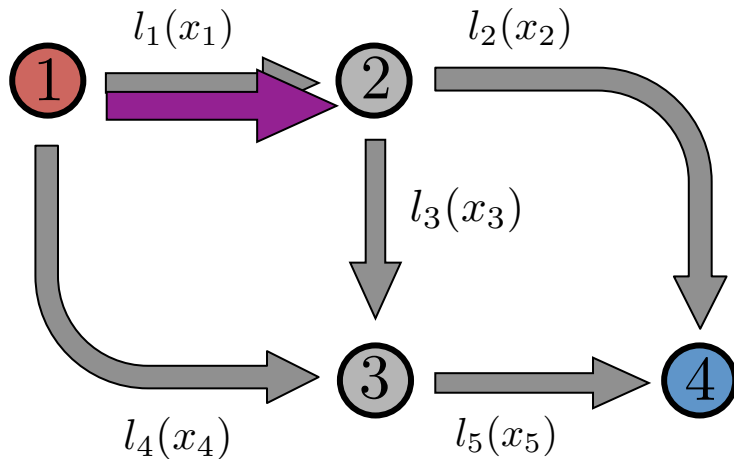
Gradient... $\nabla_x P = l(x)$

$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

$$\frac{\partial \mathcal{L}}{\partial x_e} : l_e(x_e) = (\pi_n - \pi_m) + \nu_e$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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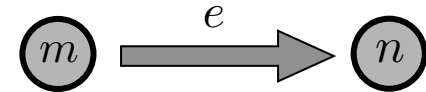
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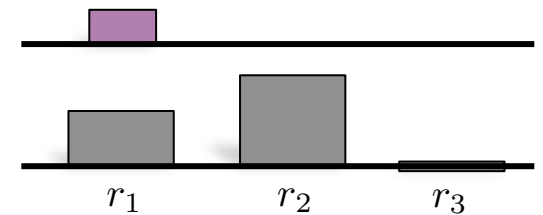


$$r_1 : \quad l_1 = \pi_2 - \pi_1 + \nu_1$$

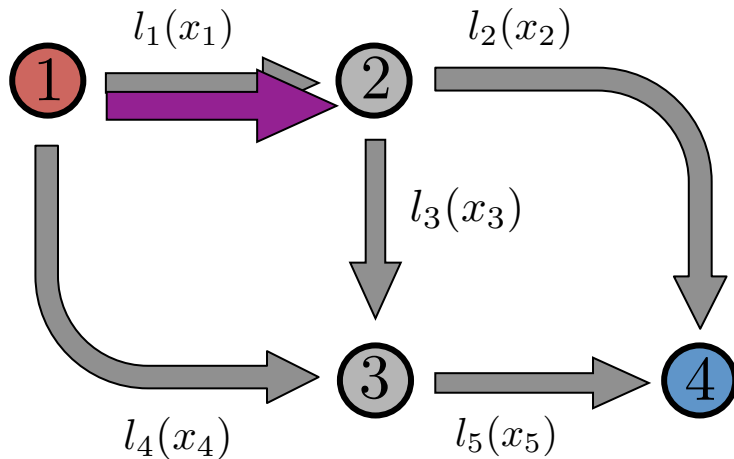
Latency

Mass

Route



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

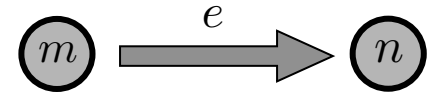
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

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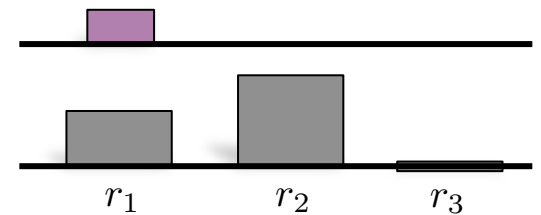


$$r_1 : \quad l_1 = \pi_2 - \pi_1 + \cancel{\nu_1}^0$$

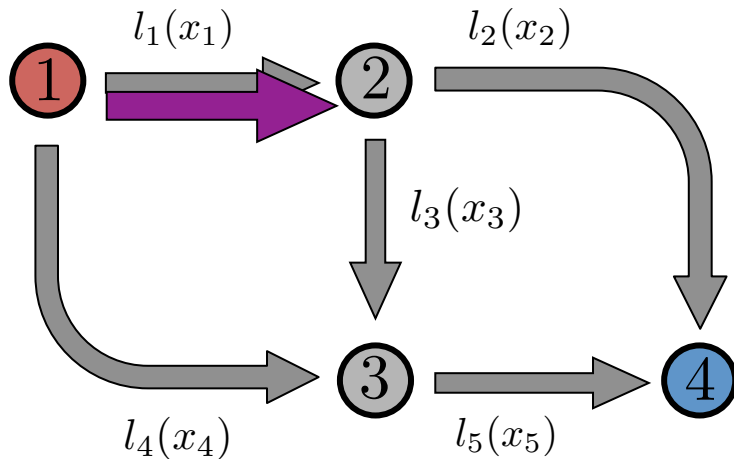
Latency

Mass

Route



Edge Formulation



Edge Formulation

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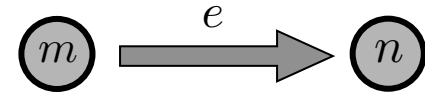
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

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$$r_1 : \quad l_1 = \pi_2 - \pi_1$$

Latency



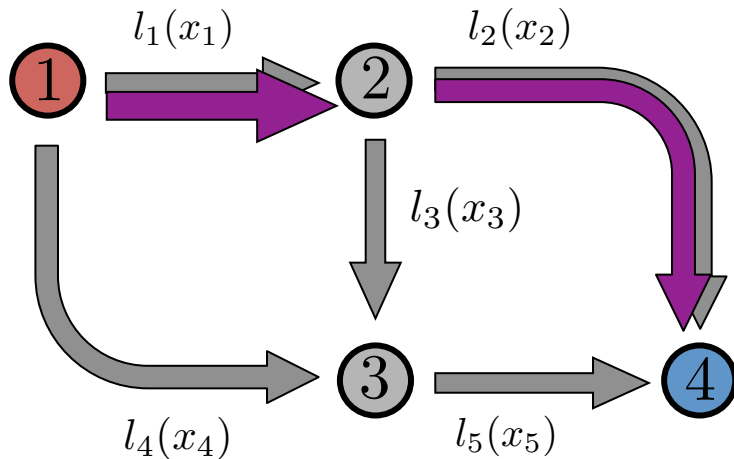
Mass



Route

r_1 r_2 r_3

Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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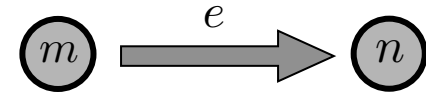
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

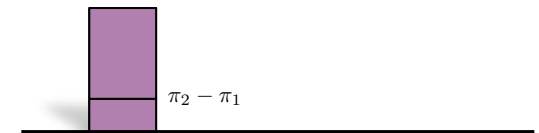
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$$r_1 : \quad l_2 + l_1 = \pi_4 - \pi_2 + \pi_2 - \pi_1 + \nu_2$$

Latency



Mass



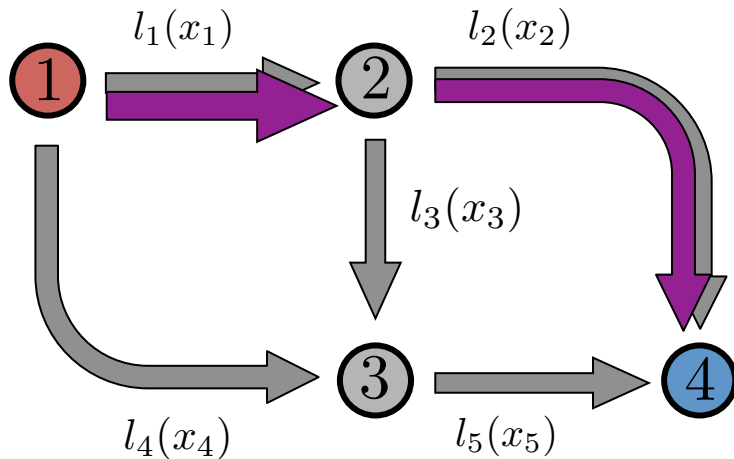
Route

r_1

r_2

r_3

Edge Formulation



Edge Formulation

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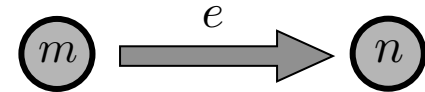
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

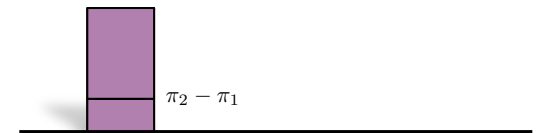
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$$r_1 : \quad l_2 + l_1 = \pi_4 - \pi_2 + \cancel{\pi_2} - \pi_1 + \cancel{\nu_2}^0$$

Latency



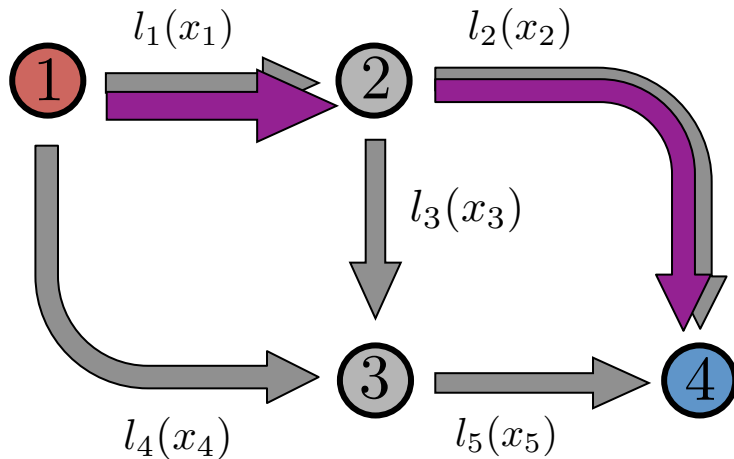
Mass



Route

r_1 r_2 r_3

Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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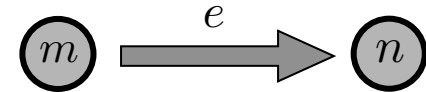
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First Order Optimality...

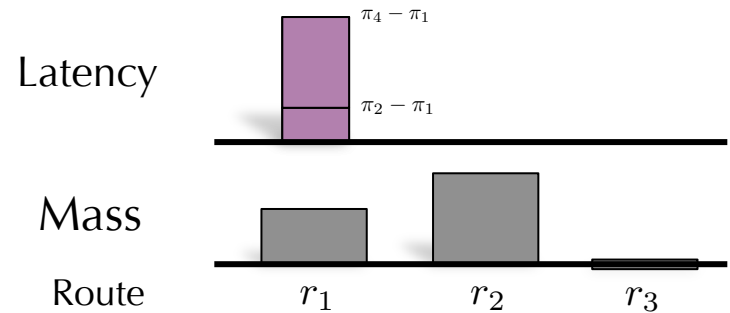
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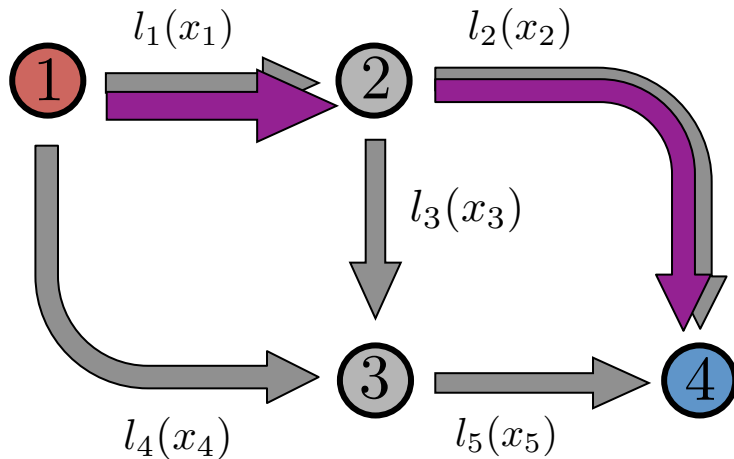
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$$r_1 : \quad l_2 + l_1 = \pi_4 - \pi_1$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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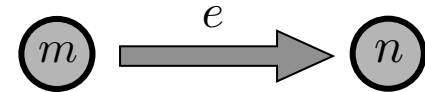
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First Order Optimality...

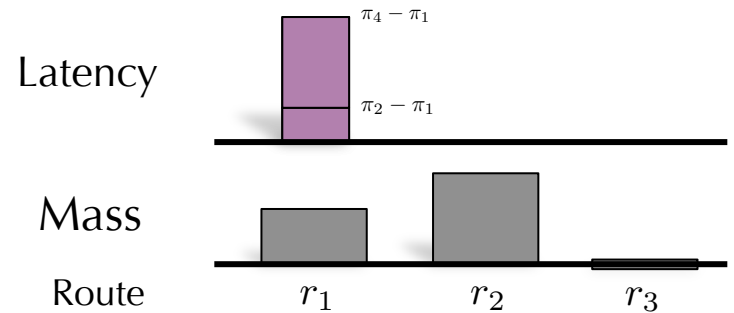
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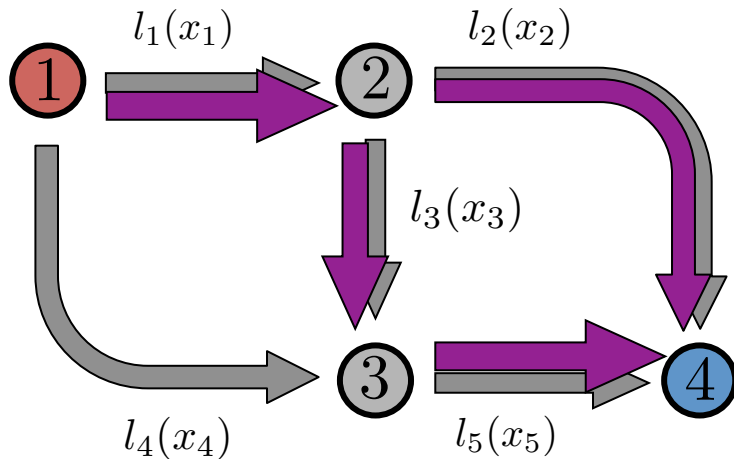
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$$r_1 : \quad l_1^R = \pi_4 - \pi_1$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

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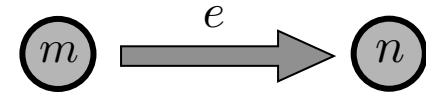
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

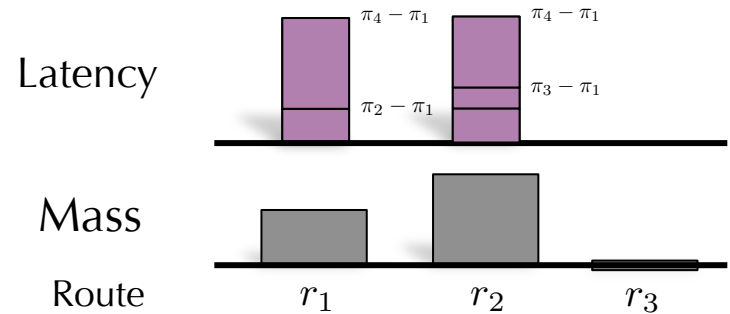
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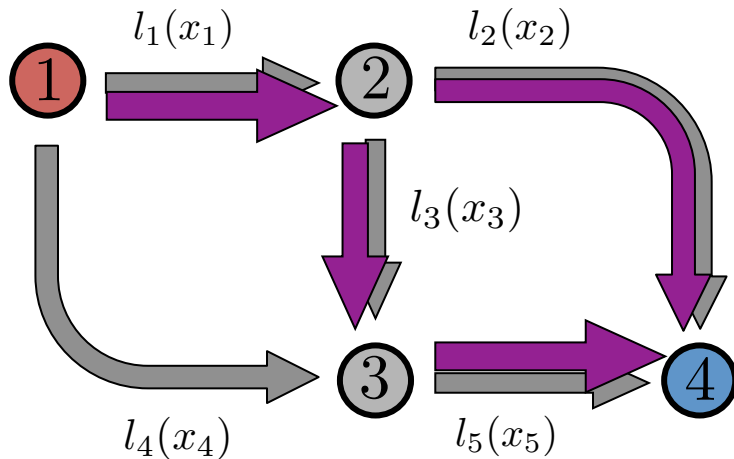


$$r_1 : \quad l_1^R = \pi_4 - \pi_1$$

$$r_2 : l_1 + l_3 + l_5 = \pi_4 - \pi_1 + \nu_1 + \nu_3 + \nu_5$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

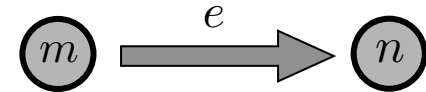
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

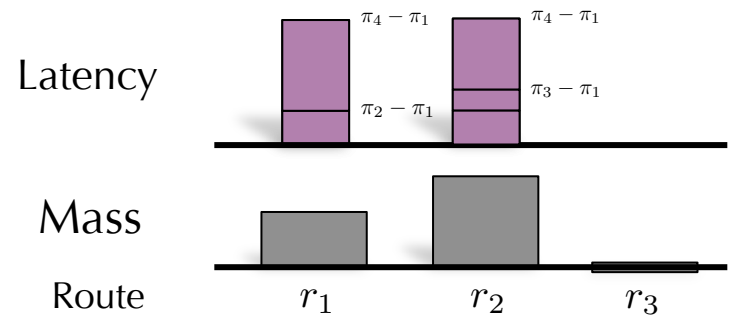
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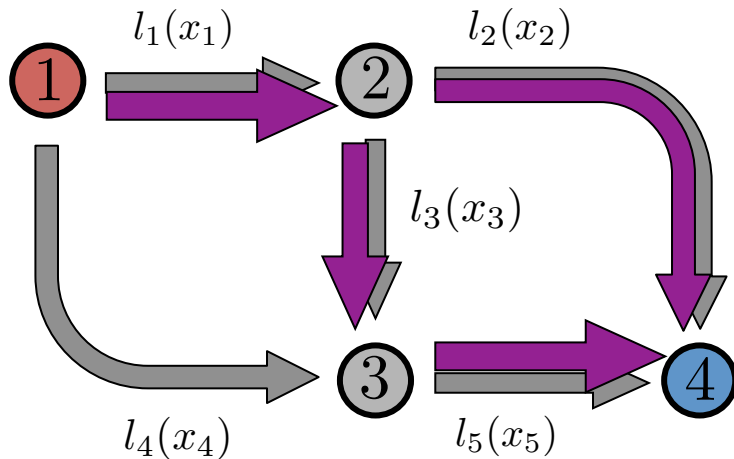


$$r_1 : \quad l_1^R = \pi_4 - \pi_1$$

$$r_2 : l_1 + l_3 + l_5 = \pi_4 - \pi_1 + \cancel{\nu_1} + \cancel{\nu_3} + \cancel{\nu_5} = 0$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

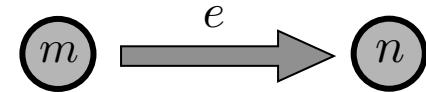
$$G \left\{ \begin{array}{l} \text{edges} \\ \text{nodes} \end{array} \right. \left[\begin{array}{ccccc} 1 & 0 & 0 & 1 & 0 \\ -1 & 1 & 1 & 0 & 0 \\ 0 & 0 & -1 & -1 & 1 \\ 0 & -1 & 0 & 0 & -1 \end{array} \right] \left[\begin{array}{c} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{array} \right] = \left[\begin{array}{c} s \\ 0 \\ 0 \\ 0 \\ -s \end{array} \right] \right\} S$$

First Order Optimality...

Gradient... $\nabla_x P = l(x)$

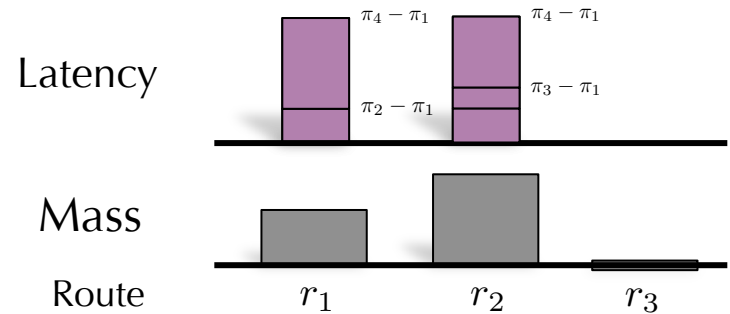
$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

$$\frac{\partial \mathcal{L}}{\partial x_e} : l_e(x_e) = (\pi_n - \pi_m) + \nu_e$$

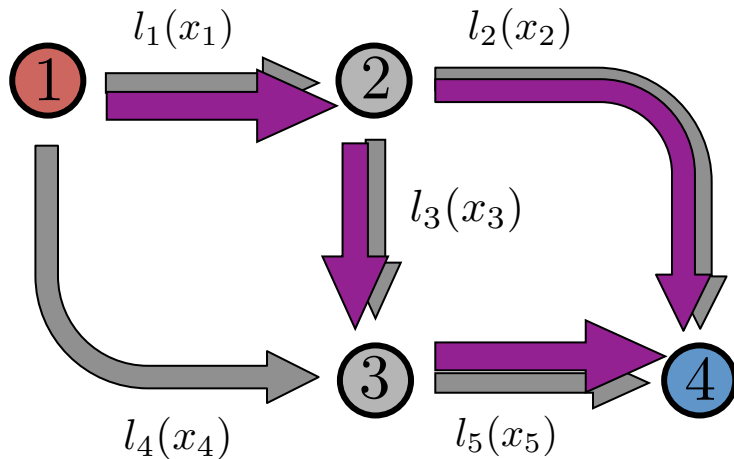


$$r_1 : \quad l_1^R = \pi_4 - \pi_1$$

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Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

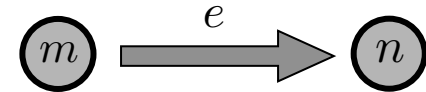
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First Order Optimality...

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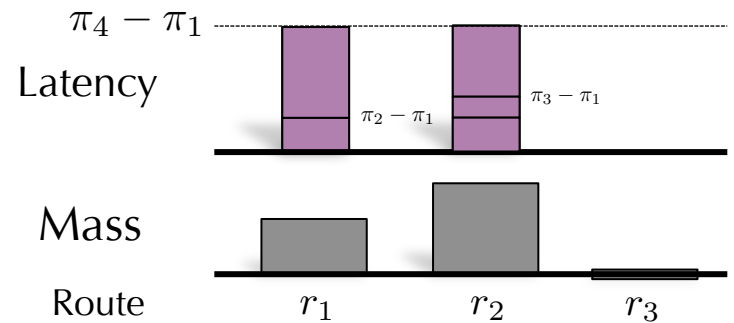
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$$\frac{\partial \mathcal{L}}{\partial x_e} : l_e(x_e) = (\pi_n - \pi_m) + \nu_e$$

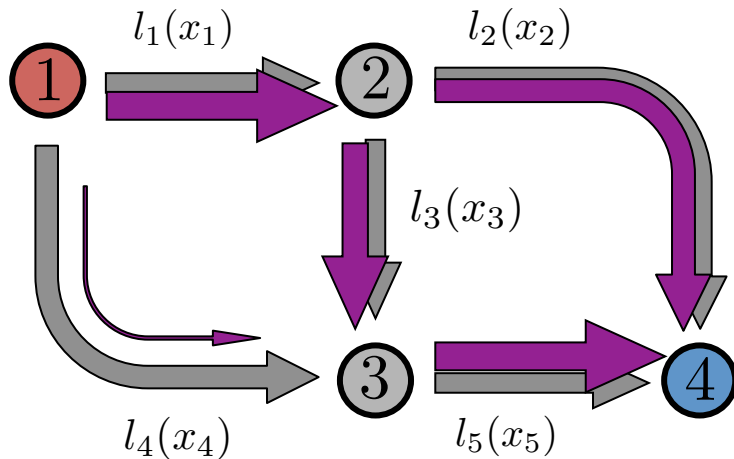


$$r_1 : \quad l_1^R = \pi_4 - \pi_1$$

$$r_2 : \quad l_2^R = \pi_4 - \pi_1$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

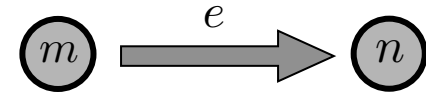
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

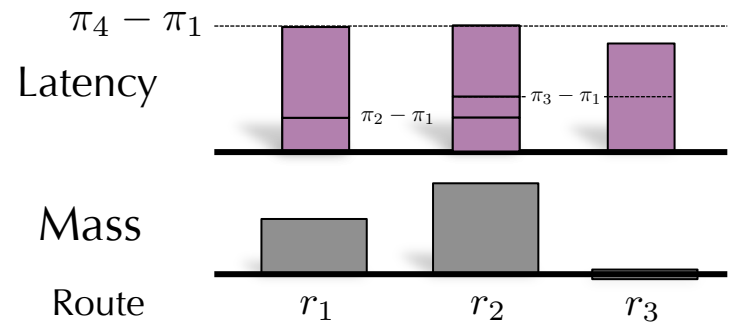
$$\frac{\partial \mathcal{L}}{\partial x_e} : l_e(x_e) = (\pi_n - \pi_m) + \nu_e$$



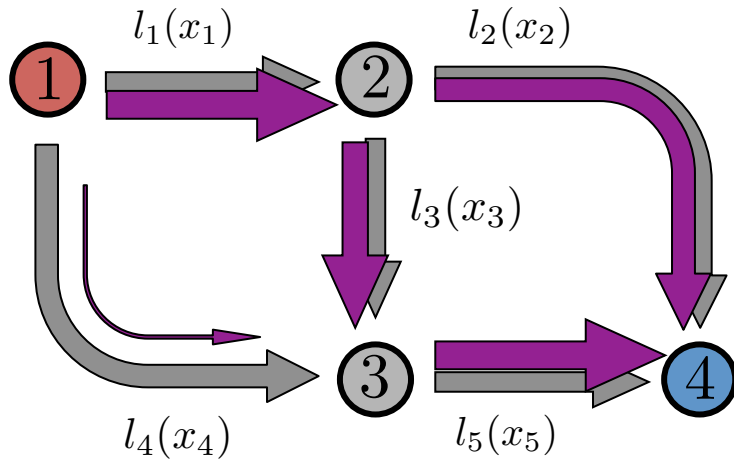
$$r_1 : \quad l_1^R = \pi_4 - \pi_1$$

$$r_2 : \quad l_2^R = \pi_4 - \pi_1$$

$$r_3 : \quad l_4 = \pi_3 - \pi_1 + \nu_4$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

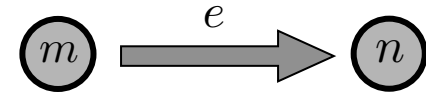
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First Order Optimality...

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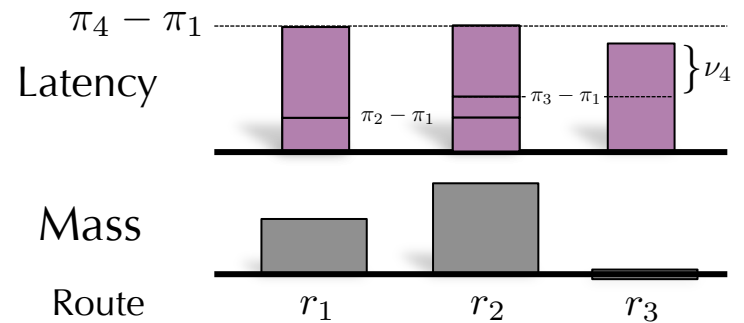
$$\frac{\partial \mathcal{L}}{\partial x_e} : l_e(x_e) = (\pi_n - \pi_m) + \nu_e$$



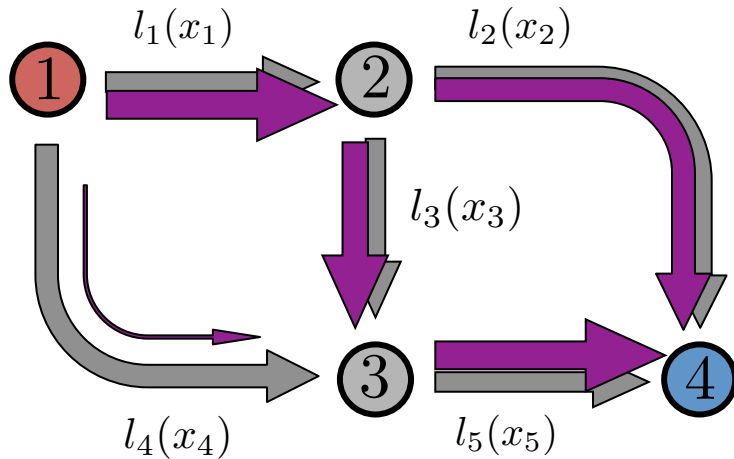
$$r_1 : \quad l_1^R = \pi_4 - \pi_1$$

$$r_2 : \quad l_2^R = \pi_4 - \pi_1$$

$$r_3 : \quad l_4 = \pi_3 - \pi_1 + \nu_4 \neq 0$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

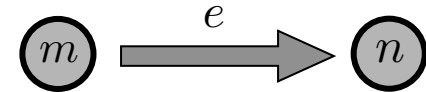
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

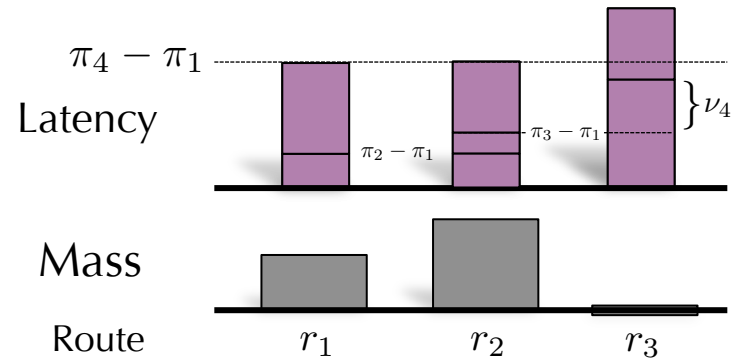
$$\frac{\partial \mathcal{L}}{\partial x_e} : l_e(x_e) = (\pi_n - \pi_m) + \nu_e$$



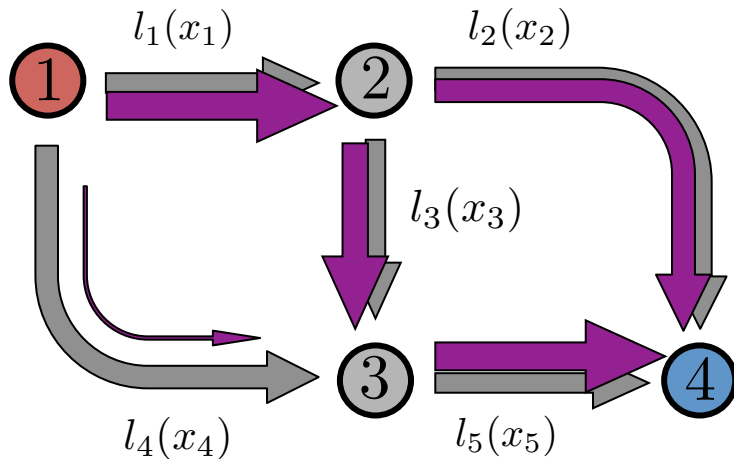
$$r_1 : \quad l_1^R = \pi_4 - \pi_1$$

$$r_2 : \quad l_2^R = \pi_4 - \pi_1$$

$$r_3 : \quad l_5 + l_4 = \pi_4 - \pi_1 + \underbrace{\nu_4}_{\neq 0} + \cancel{\nu_5}^0$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

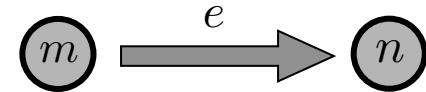
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

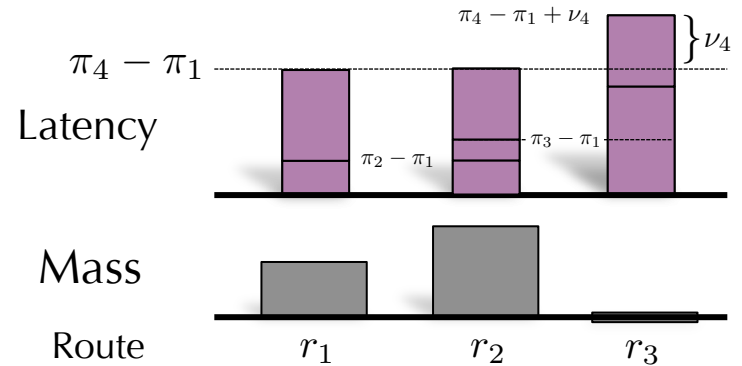
$$\frac{\partial \mathcal{L}}{\partial x_e} : l_e(x_e) = (\pi_n - \pi_m) + \nu_e$$



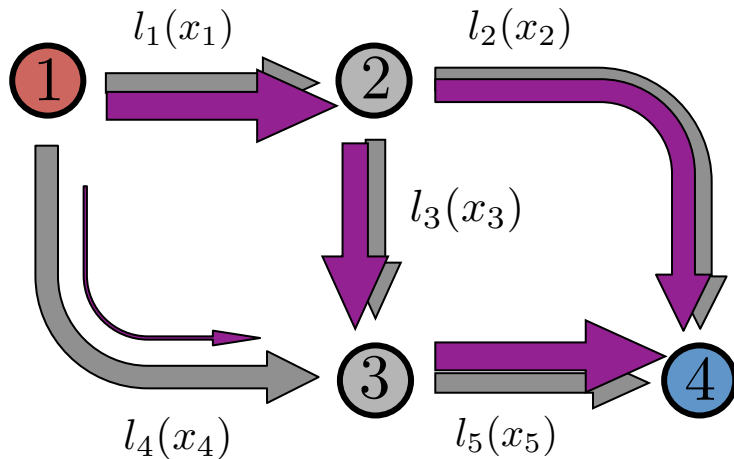
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$$r_3 : \quad l_5 + l_4 = \pi_4 - \pi_1 + \nu_4$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

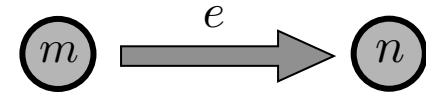
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First Order Optimality...

Gradient... $\nabla_x P = l(x)$

$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

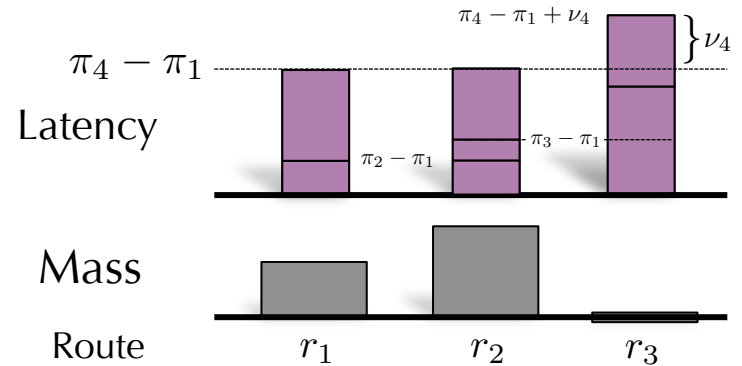
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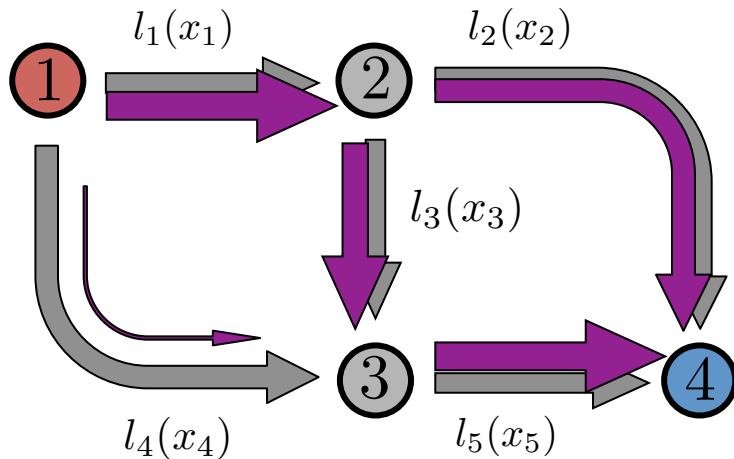
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$$r_2 : \quad l_2^R = \pi_4 - \pi_1$$

$$r_3 : \quad l_3^R = \pi_4 - \pi_1 + \nu_4$$



Edge Formulation



Edge Formulation

$$\min_x P(x) = \sum_e \int_0^{x_e} l_e(u) du$$

$$\text{s.t. } x \geq 0, \quad Gx = S$$

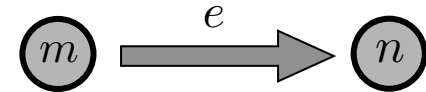
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First Order Optimality...

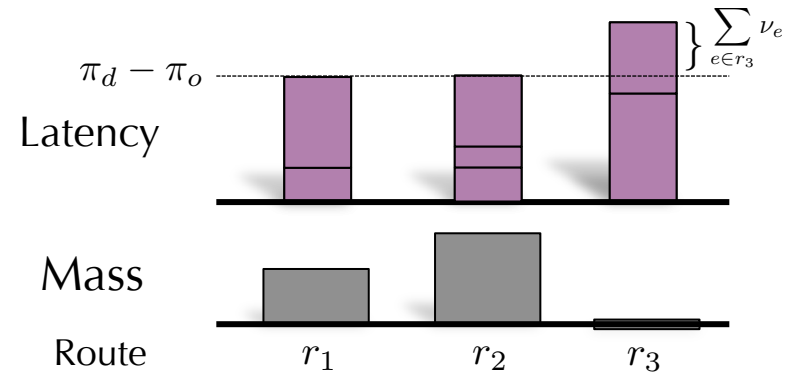
Gradient... $\nabla_x P = l(x)$

$$\mathcal{L}(x, \pi, \nu) = P(x) - \pi^T (Gx - S) - \nu^T x$$

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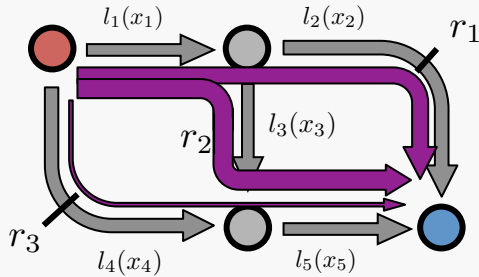


$$\begin{aligned} l_r^R &= \sum_{e \in r} l_e(x_e) \\ &= \pi_d - \pi_o + \sum_{e \in r} \nu_e \end{aligned}$$



Summary

Path Formulation

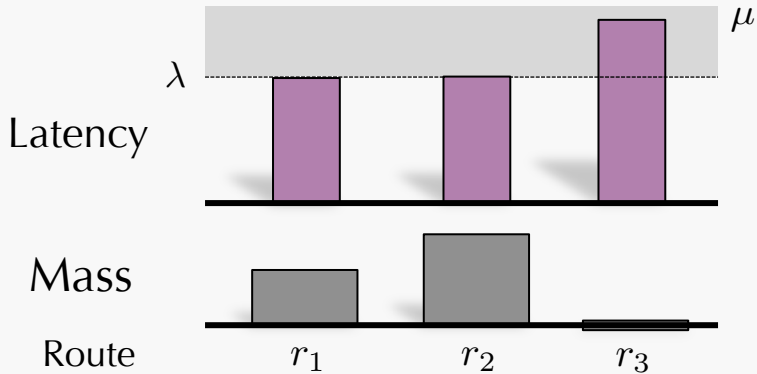


$$\min_{x^R} P(x) \text{ s.t. } x^R \geq 0, x = \mathbb{R}x^R, \sum_r x_r^R = s$$

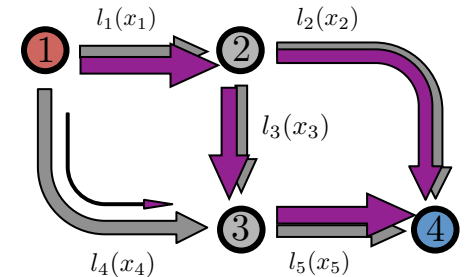
Gradient... $\nabla_{x^R} P = l(x)\mathbb{R} = l^R(x)$

$$\mathcal{L}(x, \lambda, \mu) = P(x) - \lambda(\mathbf{1}^T x^R - s) - \mu^T x^R$$

$$\frac{\partial \mathcal{L}}{\partial x^R} : l^R(x) = \lambda \mathbf{1}^T + \mu^T$$



Edge Formulation

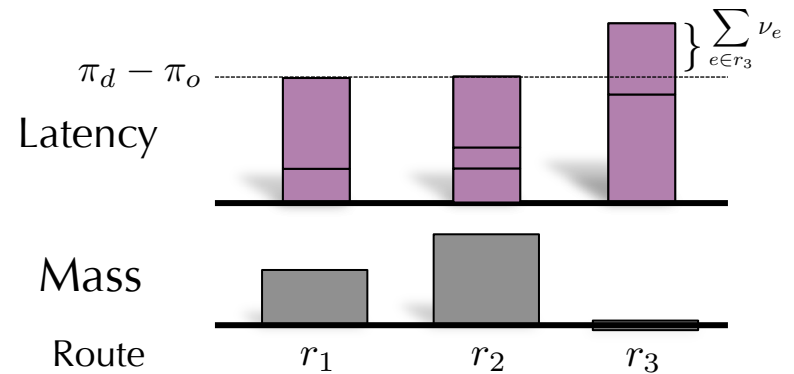


$$\min_x P(x) \text{ s.t. } x \geq 0, Gx = S$$

Gradient... $\nabla_x P = l(x)$

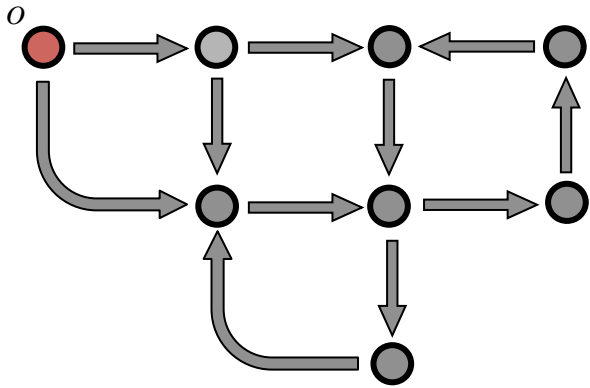
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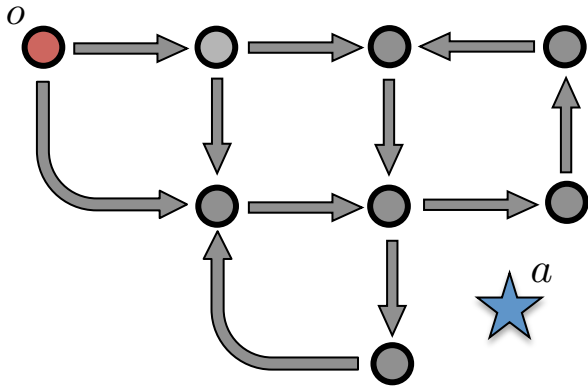


Parking Traffic Problem

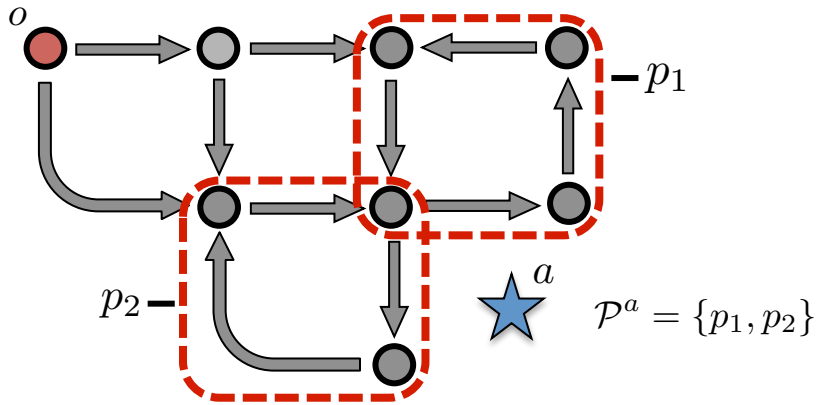
Edge Formulation



Edge Formulation



Edge Formulation



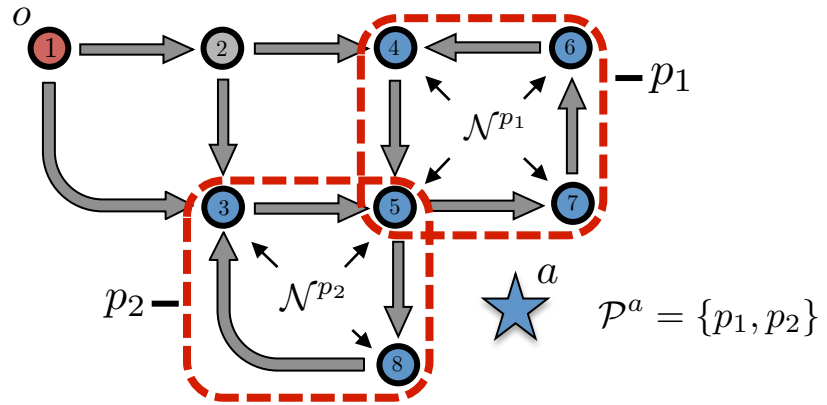
Strategy

Parking Area

Area 1

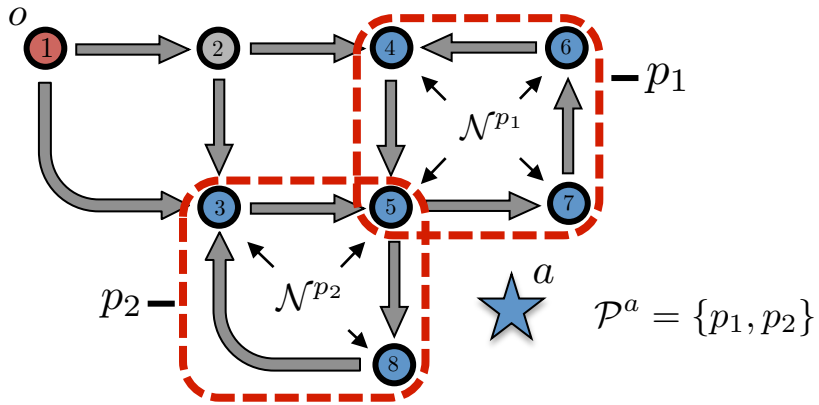
Area 2

Edge Formulation



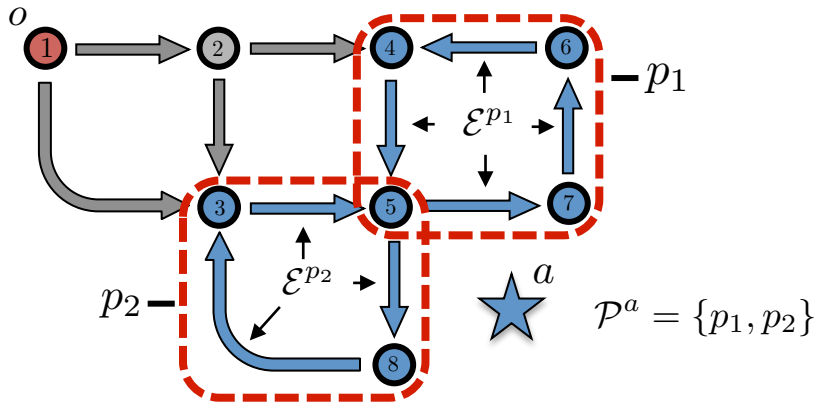
Strategy	Node	4 5 6 7	3 5 8
	Parking Area	Area 1	Area 2

Edge Formulation



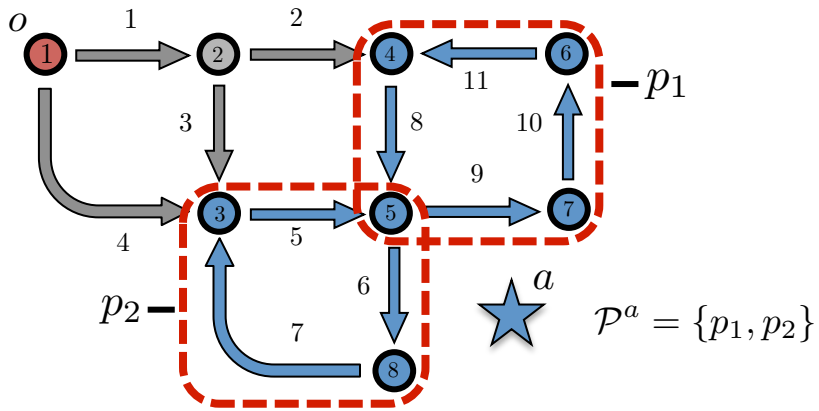
Strategy	Node	4	5	5	3
	Parking Area	Area 1		Area 2	

Edge Formulation



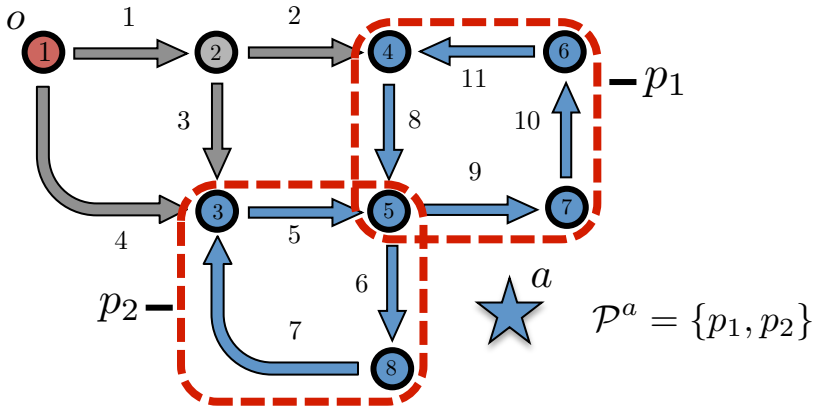
Strategy	Node	4	5	5	3
	Parking Area	Area 1		Area 2	

Edge Formulation



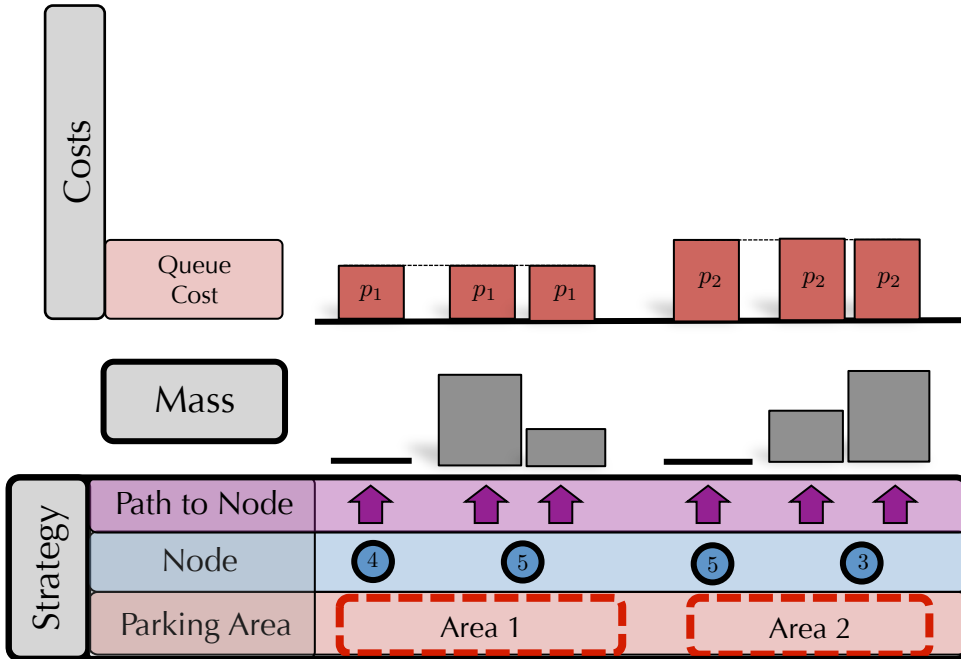
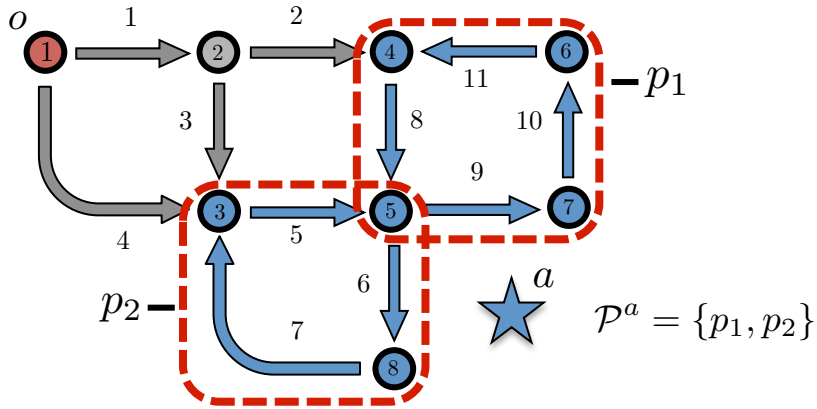
Strategy	Path to Node	↑	↑	↑	↑	↑	↑
	Node	4	5	5	5	3	
	Parking Area	Area 1			Area 2		

Edge Formulation

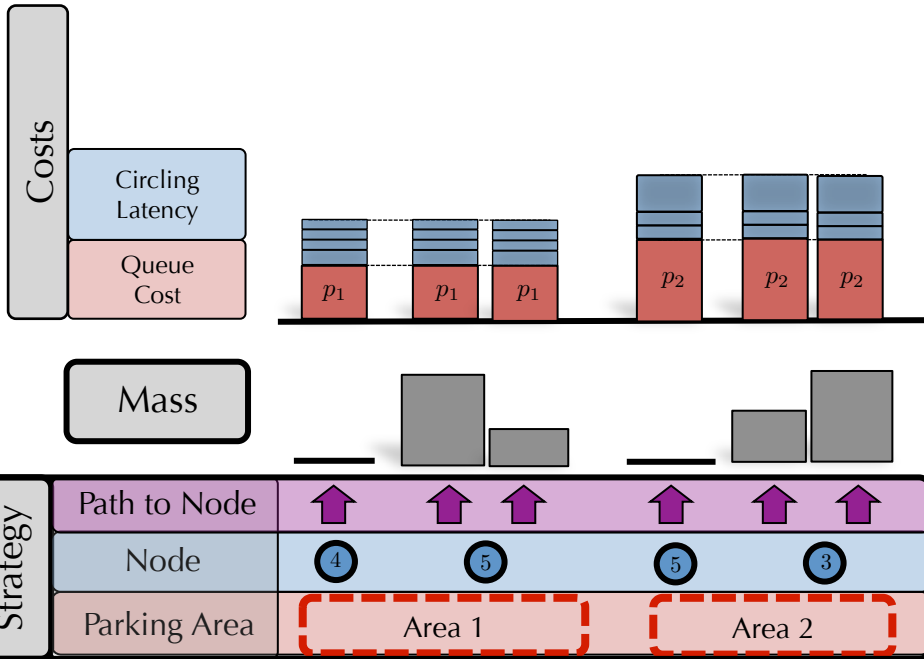
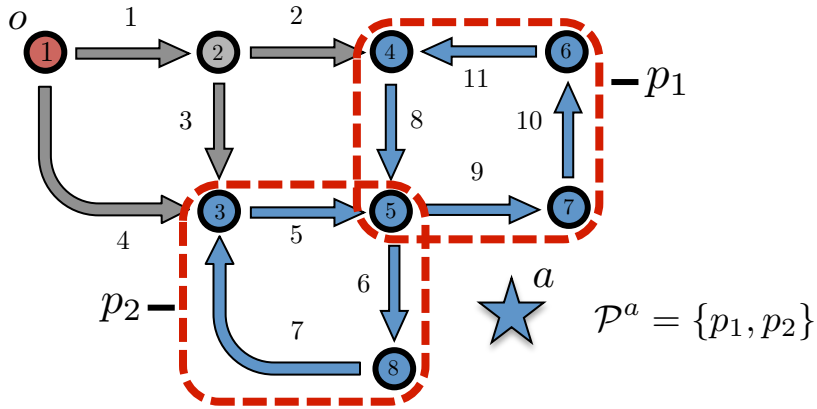


Mass		Bar chart showing mass distribution at nodes 4, 5, 5, 3					
Strategy	Path to Node	↑	↑	↑	↑	↑	↑
	Node	4	5	5	3		
	Parking Area	Area 1			Area 2		

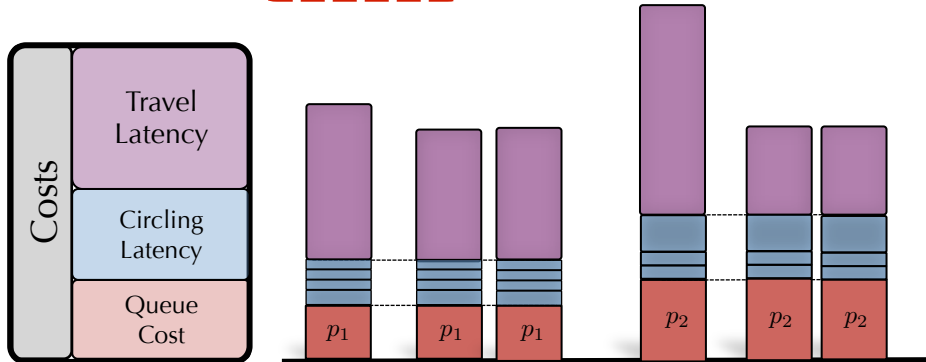
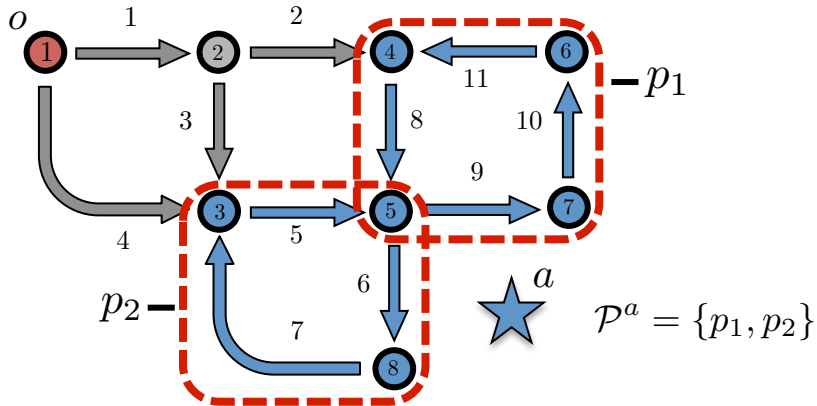
Edge Formulation



Edge Formulation

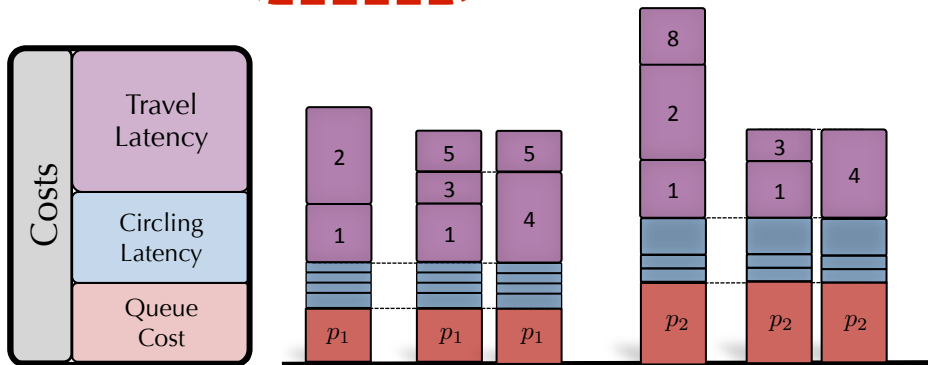
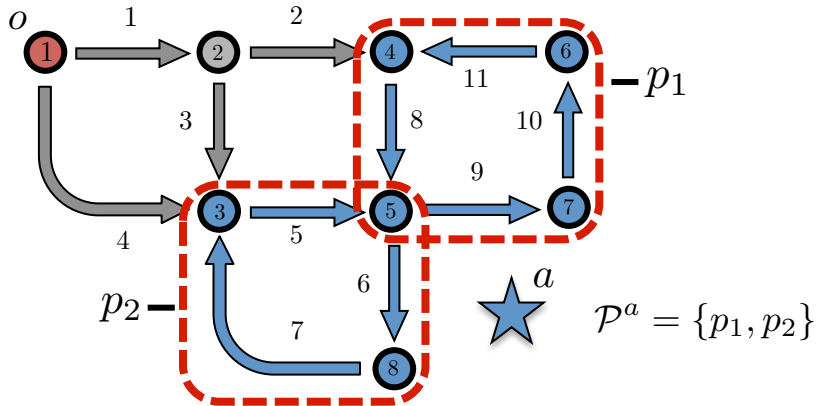


Edge Formulation



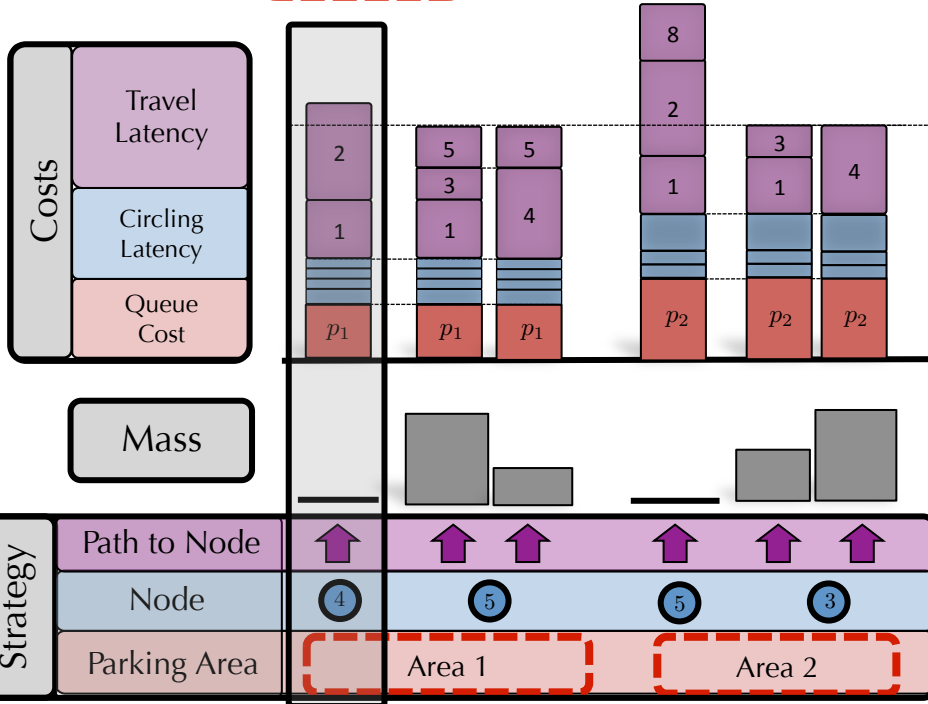
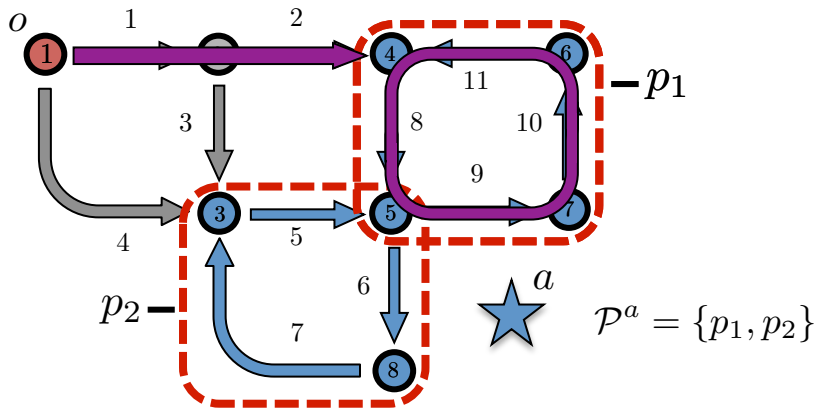
Strategy	Path to Node	↑	↑	↑	↑	↑	↑
	Node	4	5	5	5	3	3
	Parking Area	Area 1			Area 2		

Edge Formulation

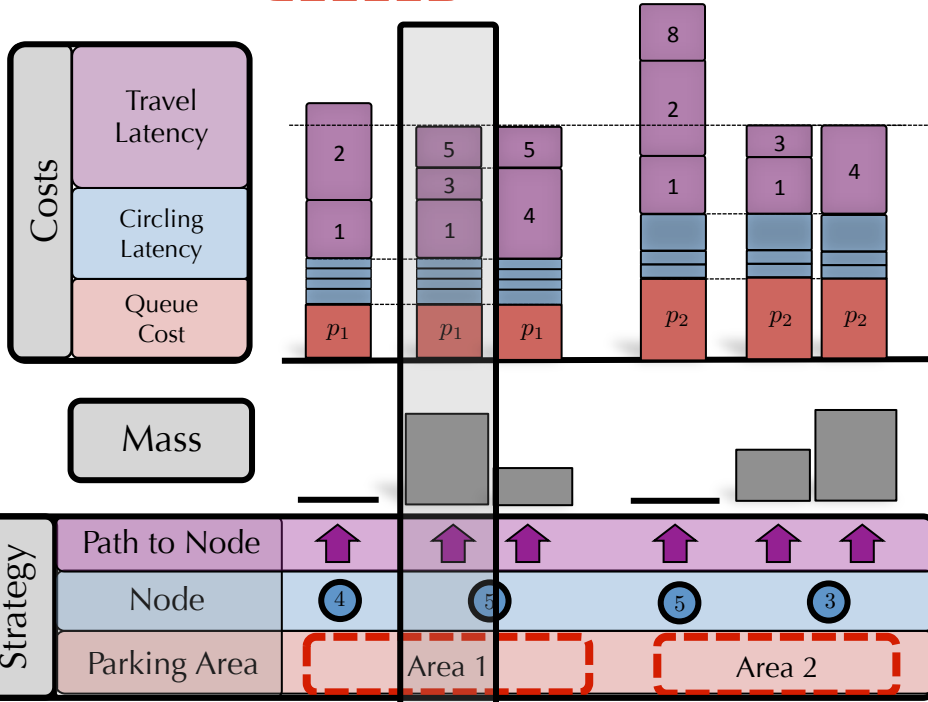
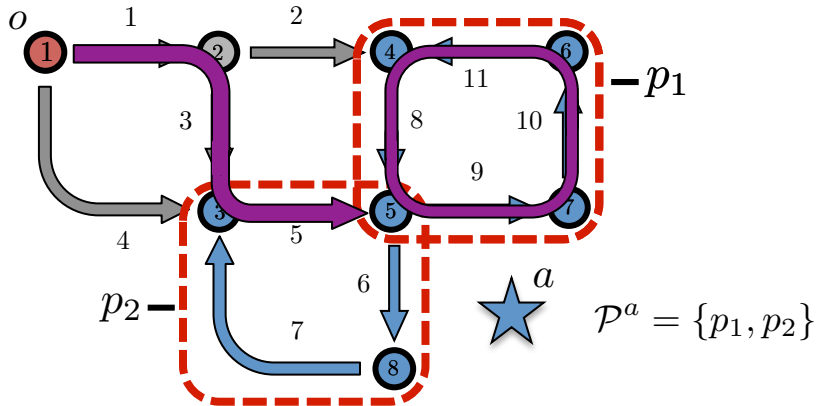


Strategy	Path to Node	↑	↑	↑	↑	↑	↑
	Node	4	5	5	5	3	3
	Parking Area	Area 1			Area 2		

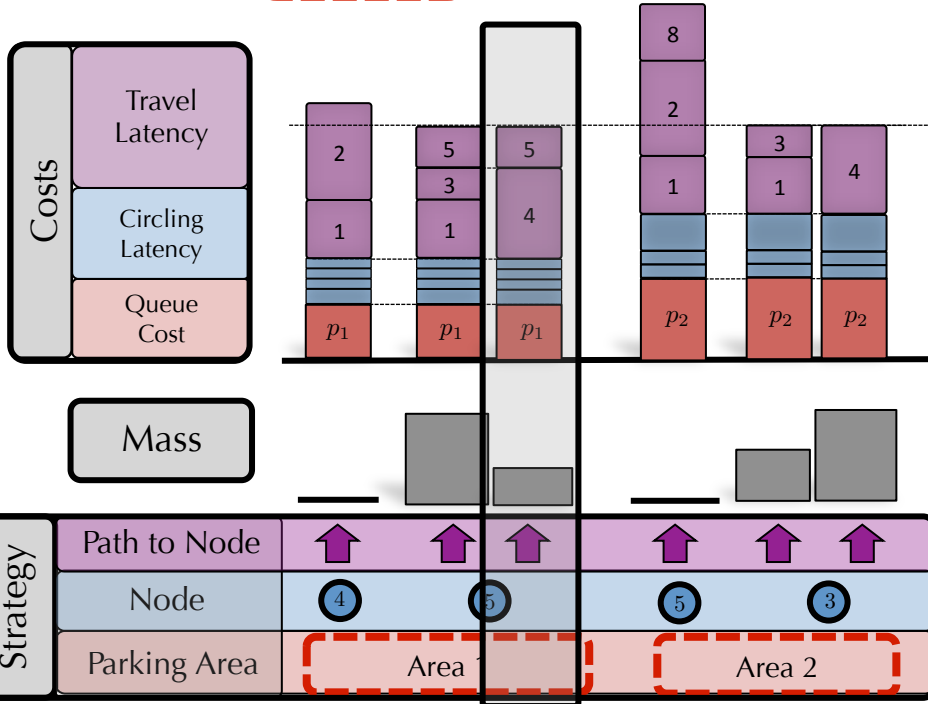
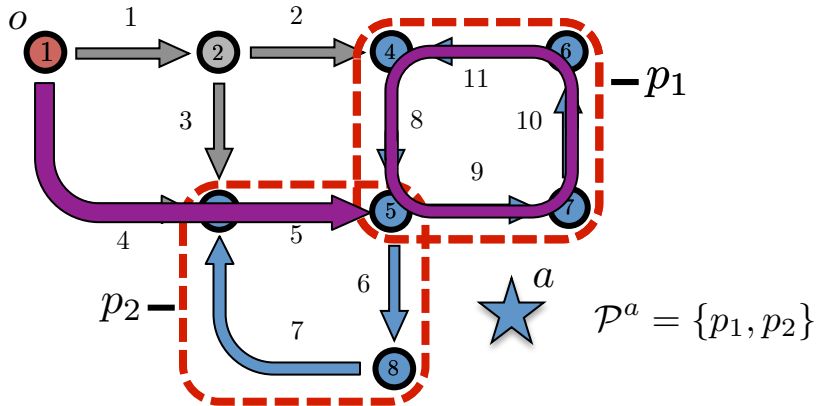
Edge Formulation



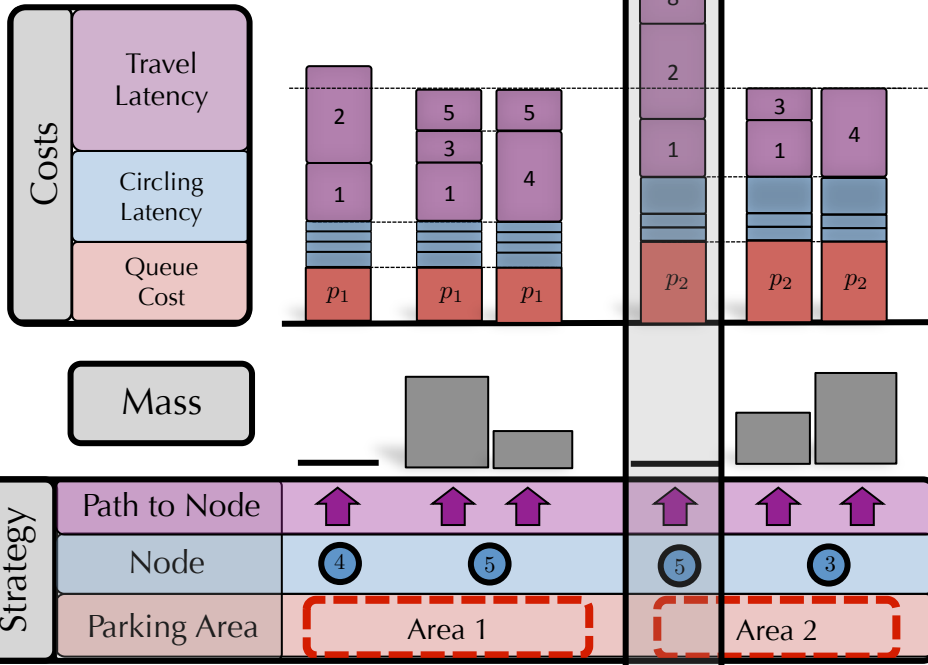
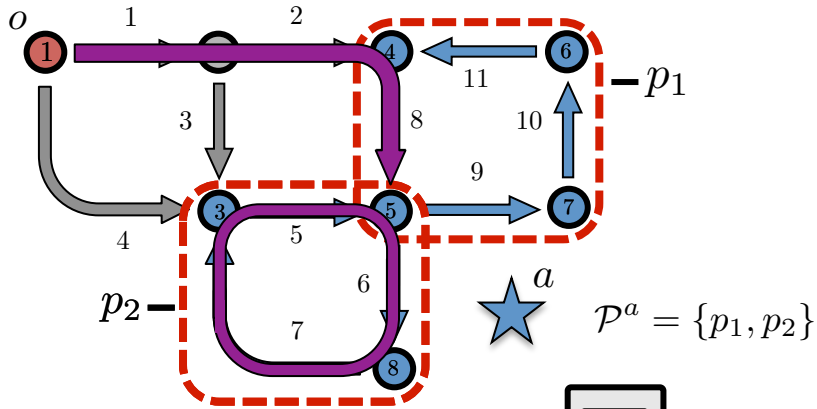
Edge Formulation



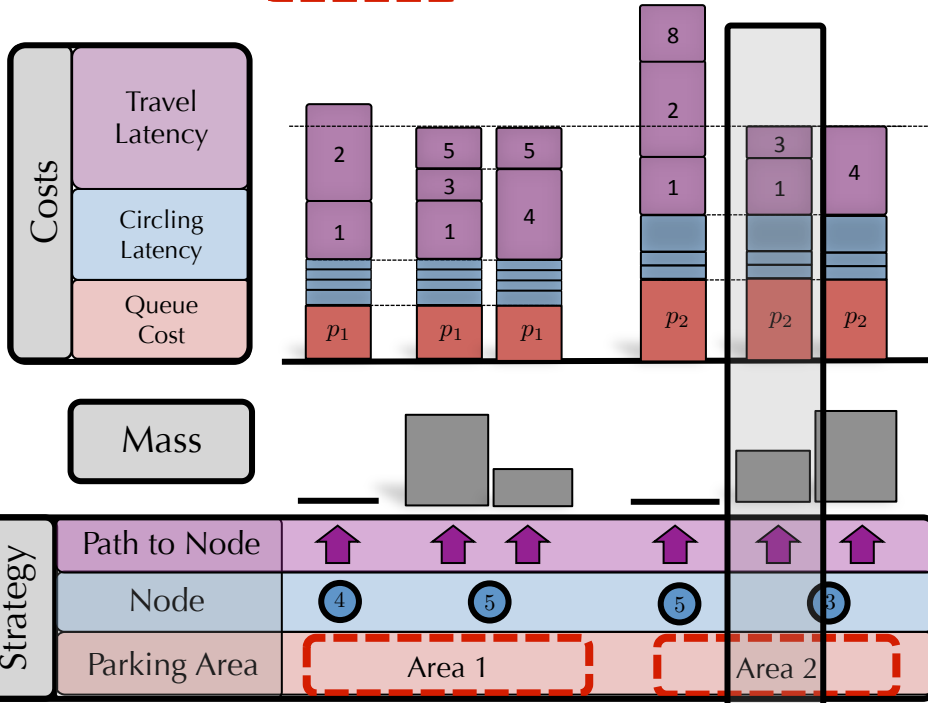
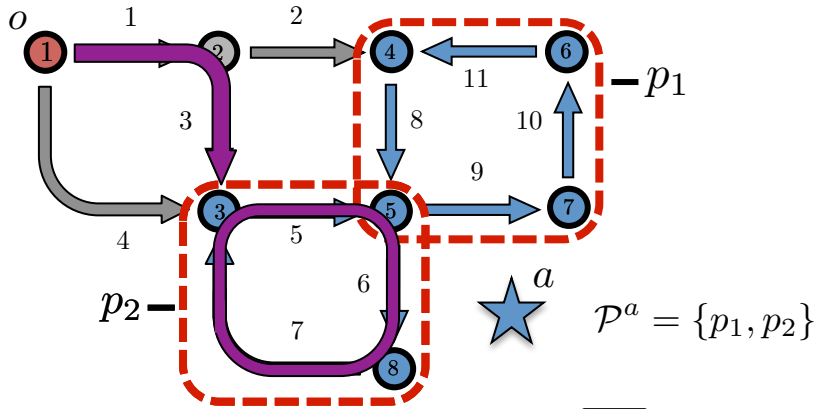
Edge Formulation



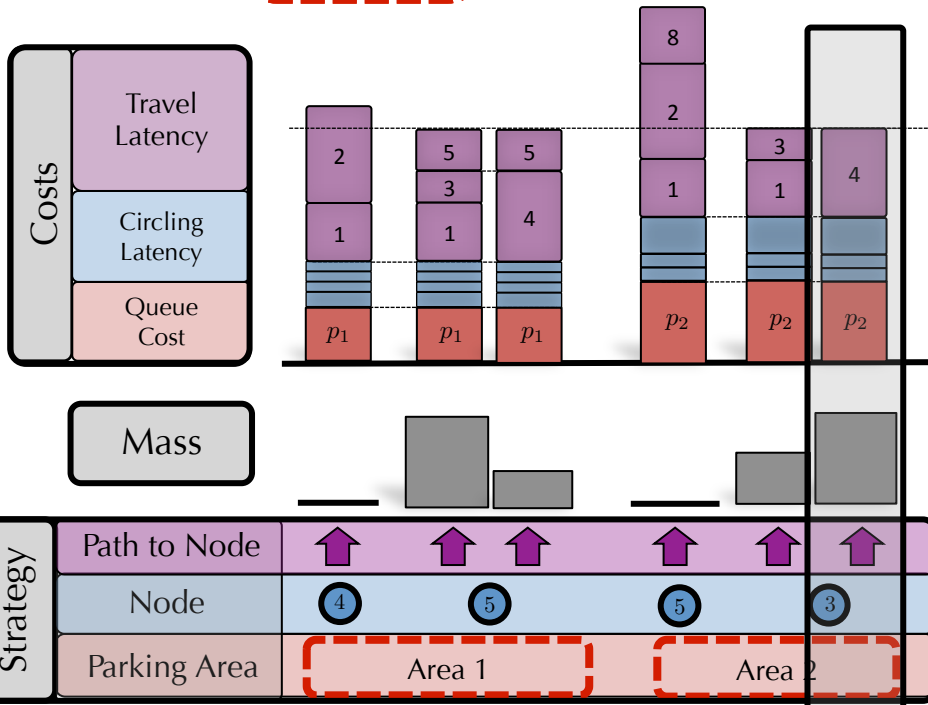
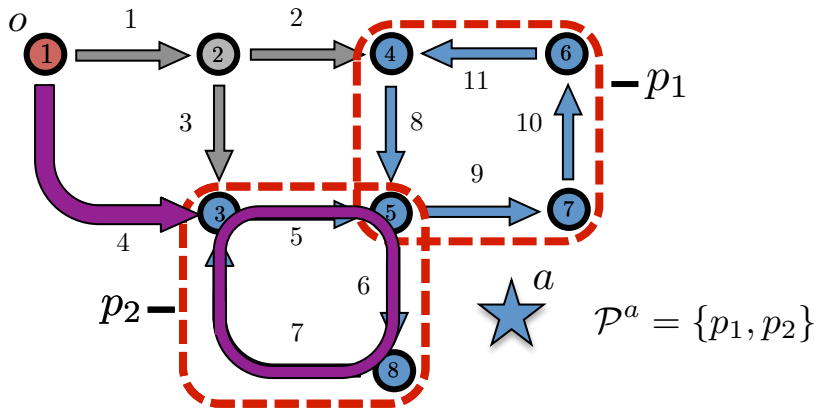
Edge Formulation



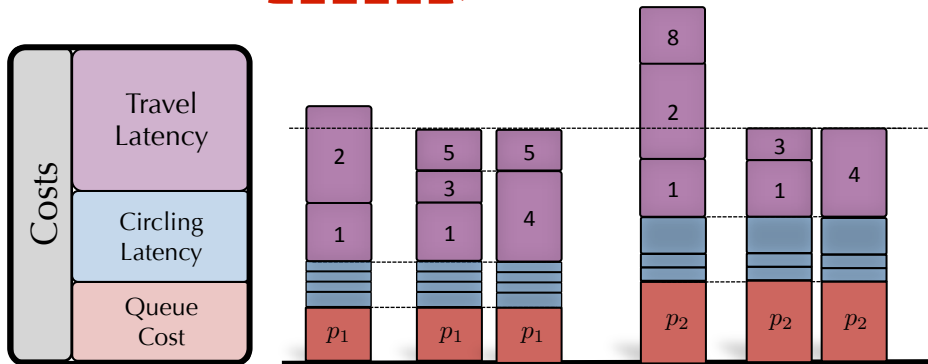
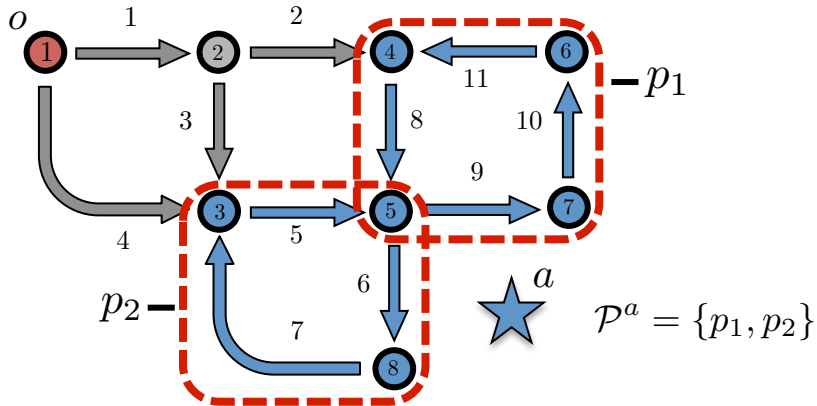
Edge Formulation



Edge Formulation



Edge Formulation



Equilibrium Condition

Mass

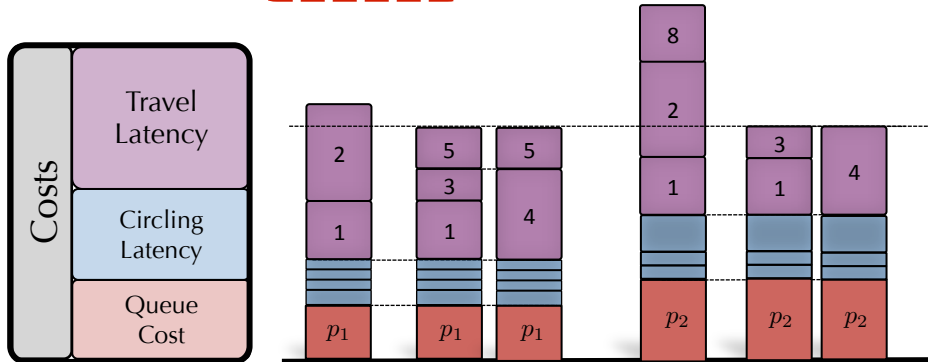
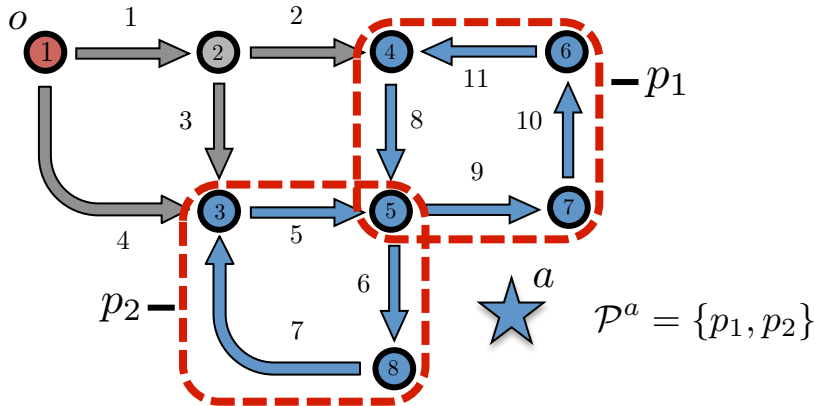


Queue-Routing Wardrop Equilibrium

Strategy	Path to Node	↑	↑	↑	↑	↑	↑
	Node	4	5	5	5	3	3
	Parking Area	Area 1			Area 2		

Edge Formulation

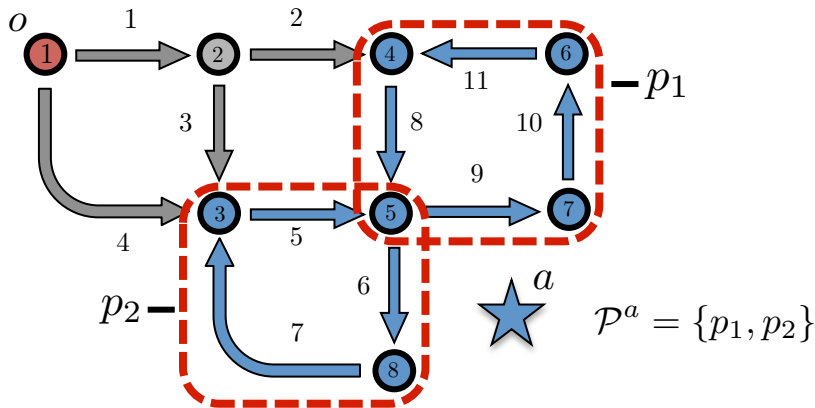
s_o^a : Traffic from origin o to attraction a



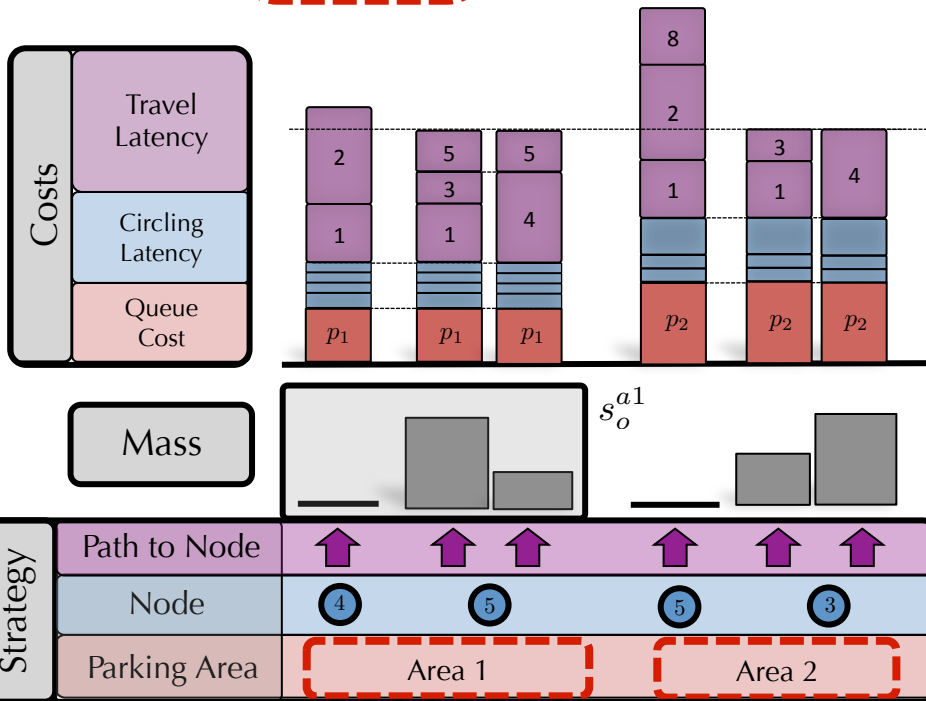
s_o^a

Strategy	Path to Node	Node	Parking Area
	↑	4	Area 1
	↑	5	Area 1
	↑	5	Area 2
	↑	3	Area 2

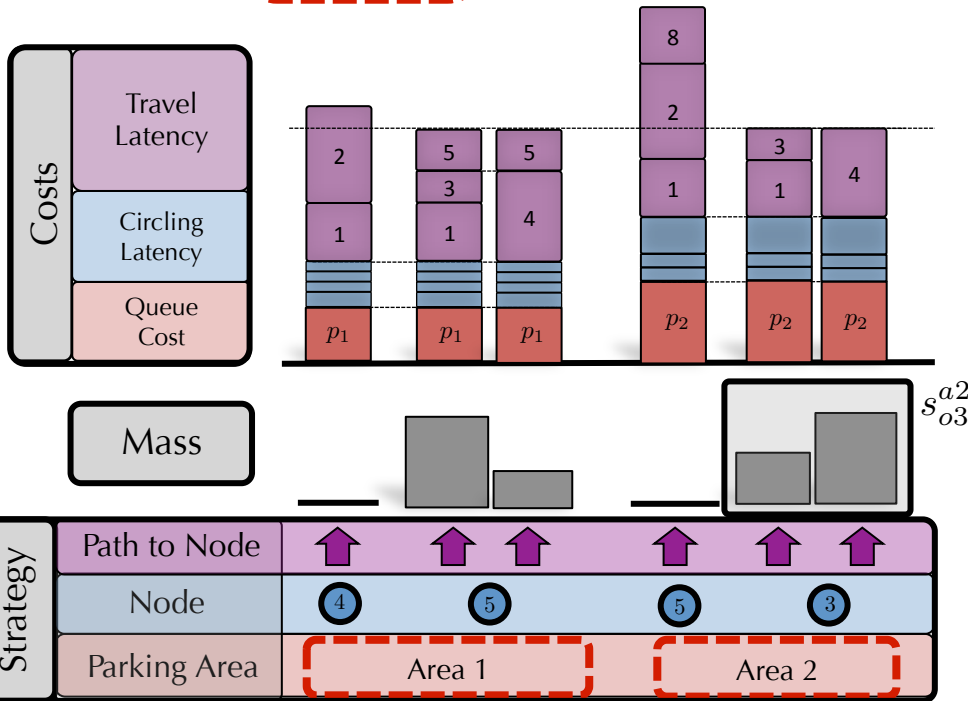
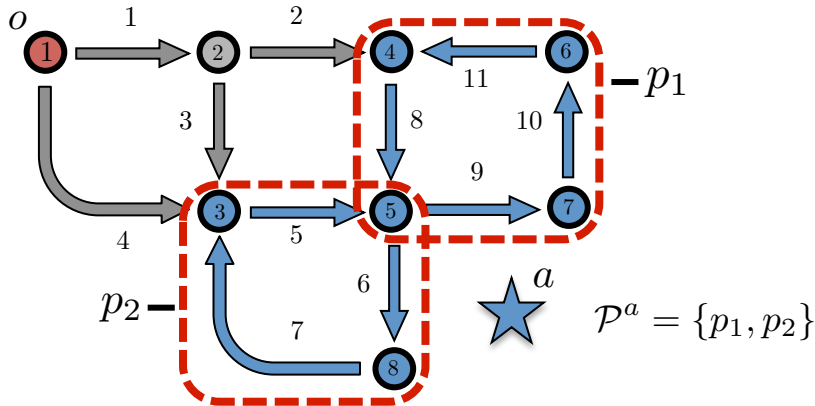
Edge Formulation



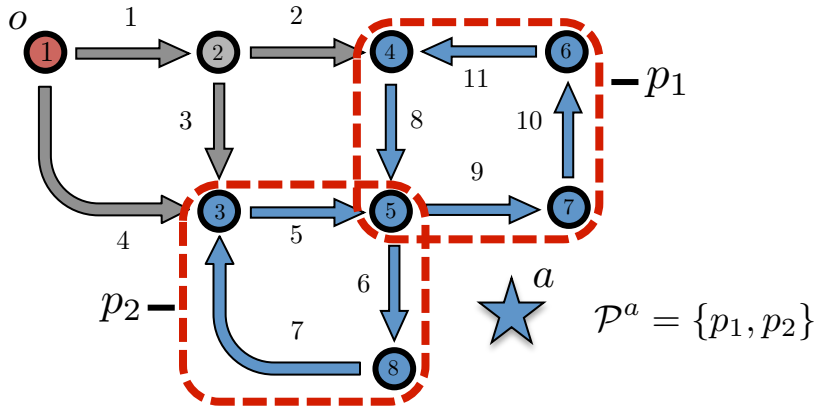
s_o^a : Traffic from origin o to attraction a
 s_o^{ap} : ...parking in area p $s_o^a = \sum_{p \in \mathcal{P}^a} s_o^{ap}$



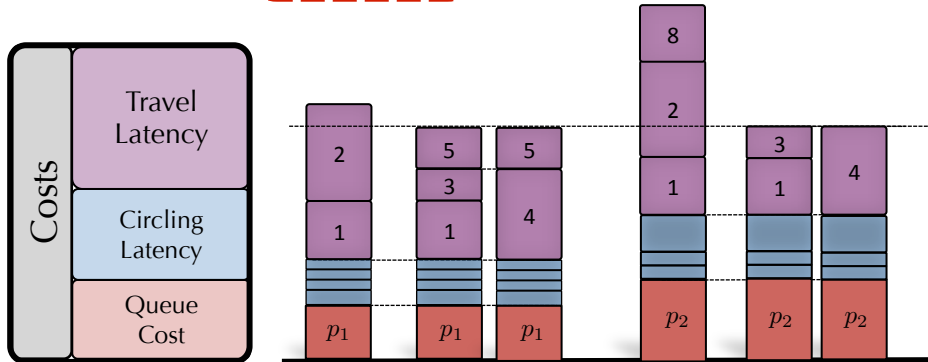
Edge Formulation



Edge Formulation

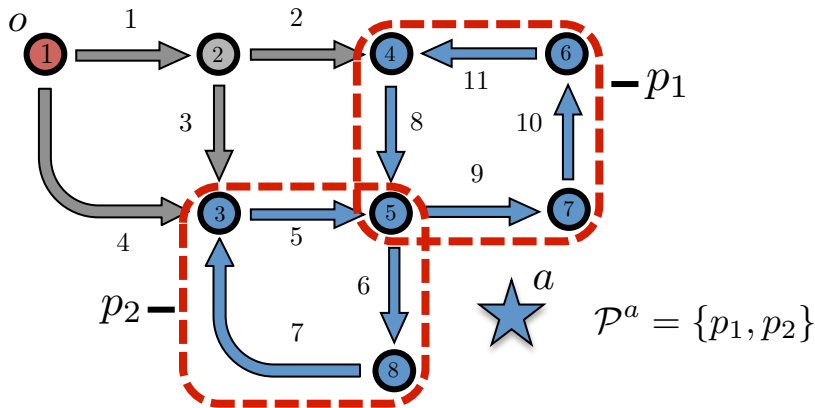


- s_o^a : Traffic from origin o to attraction a
- s_o^{ap} : ...parking in area p $s_o^a = \sum_{p \in \mathcal{P}^a} s_o^{ap}$
- s_{od}^{ap} : ...entering thru node d $s_o^{ap} = \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$
- s^p : Total traffic in area p $s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$



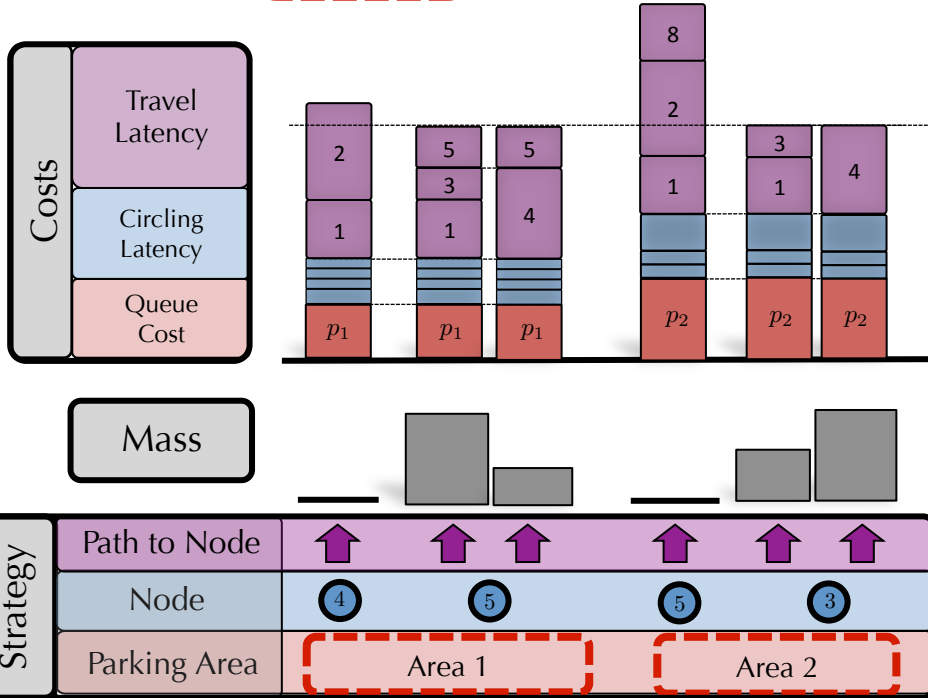
Strategy	Path to Node	Node	Parking Area
	↑	4	Area 1
	↑	5	Area 1
	↑	5	Area 2
	↑	3	Area 2

Edge Formulation

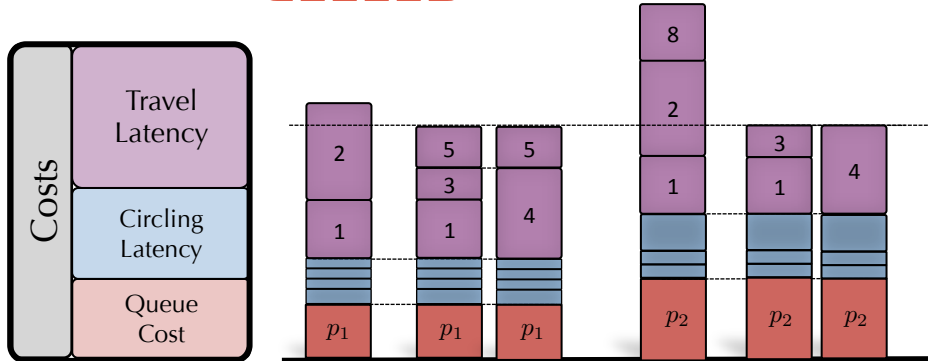
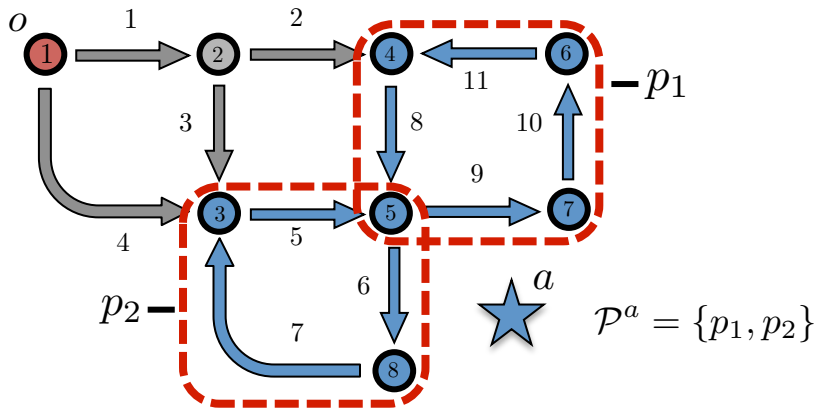


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x_{od}^{ap} : Edge flows from population s_{od}^{ap}
 $Gx_{od}^{ap} = S_{od}^{ap}$ $(S_{od}^{ap})_i = \begin{cases} s_{od}^{ap} & ; \text{if } i = o \\ -s_{od}^{ap} & ; \text{if } i = d \\ 0 & ; \text{otherwise} \end{cases}$



Edge Formulation



Strategy	Path to Node	Node	Parking Area
	↑	4	Area 1
	↑	5	Area 1
	↑	5	Area 1
	↑	3	Area 2

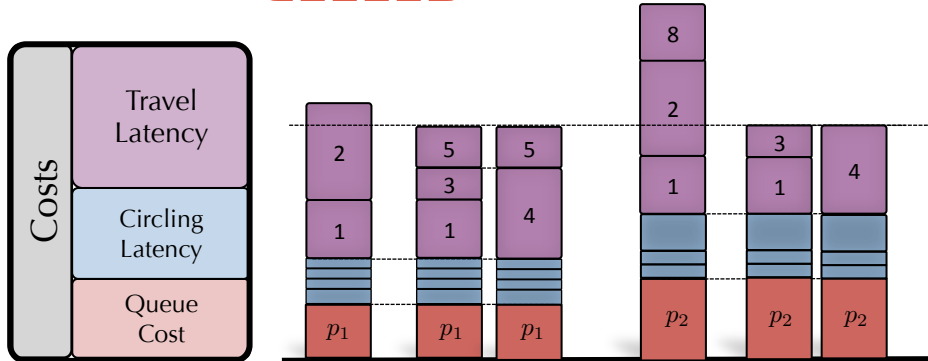
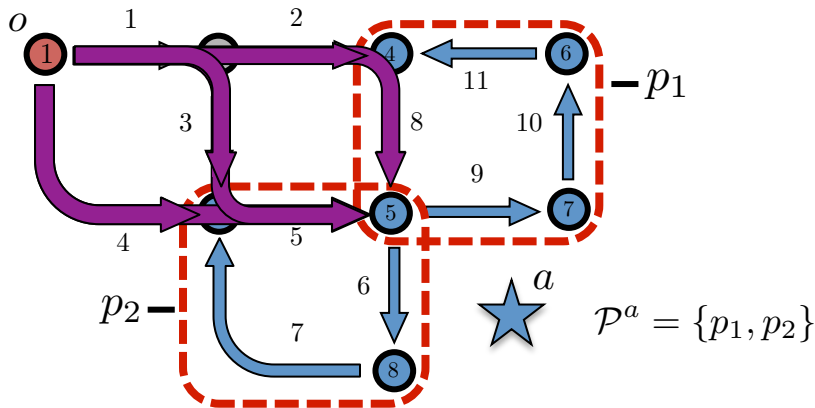
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x : Total edge flows

$$x = \underbrace{\sum_{o,a,p,d} x_{od}^{ap}}_{\text{Traveling Flows}} + \underbrace{\sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p s_o^{ap}}_{\text{Circling Flows}}$$

Edge Formulation



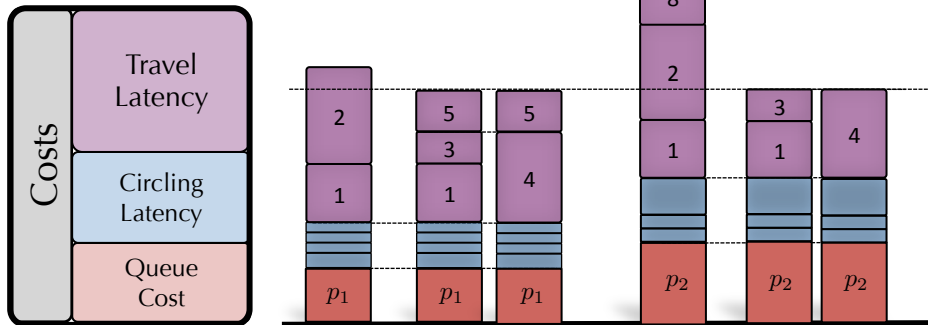
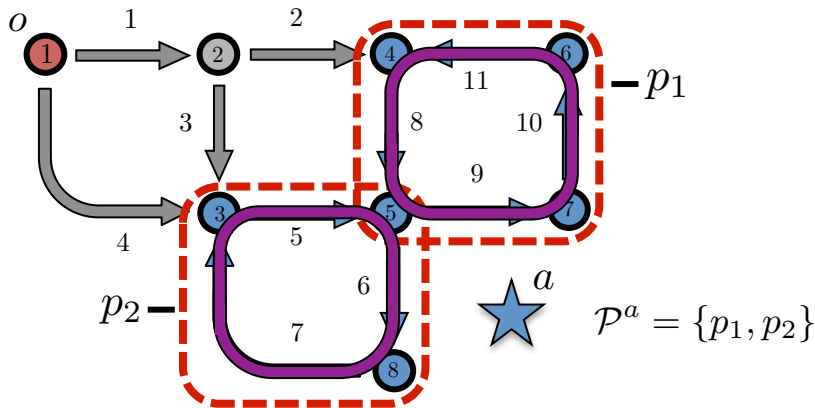
Strategy	Path to Node	Node	Parking Area
	↑	4	Area 1
	↑	5	Area 1
	↑	5	Area 2
	↑	3	Area 2

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Edge Formulation



Strategy	Path to Node	Node	Parking Area
	↑	4	Area 1
	↑	5	Area 1
	↑	5	Area 2
	↑	3	Area 2

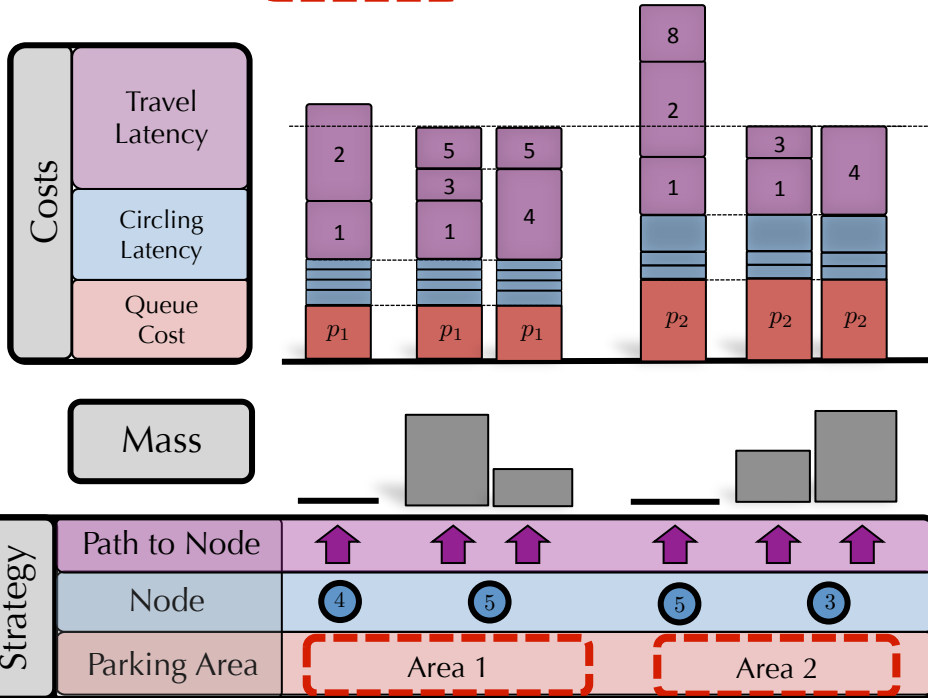
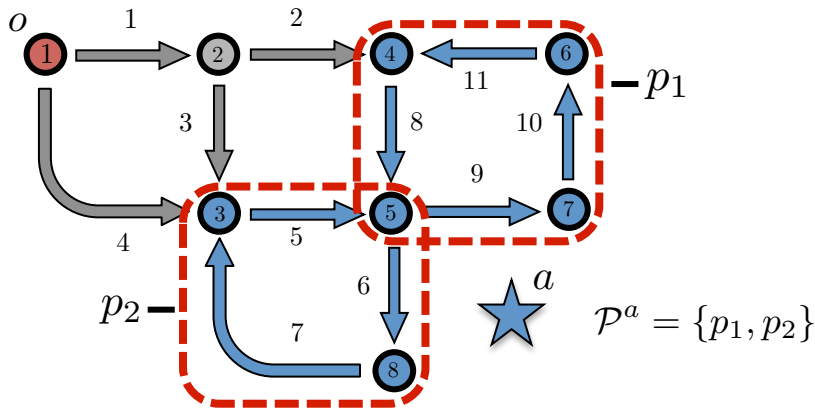
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Edge Formulation



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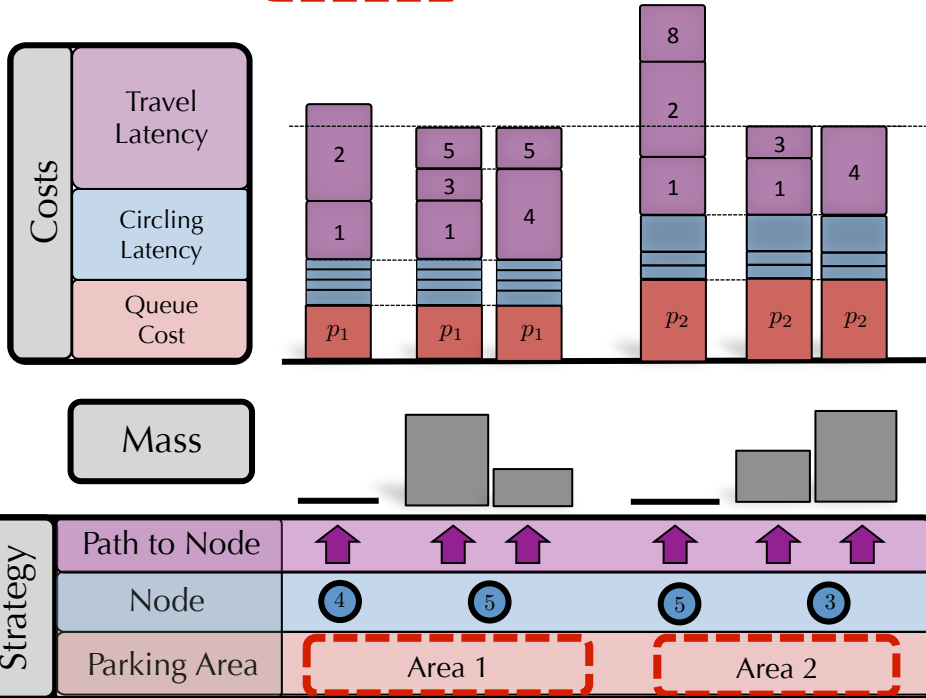
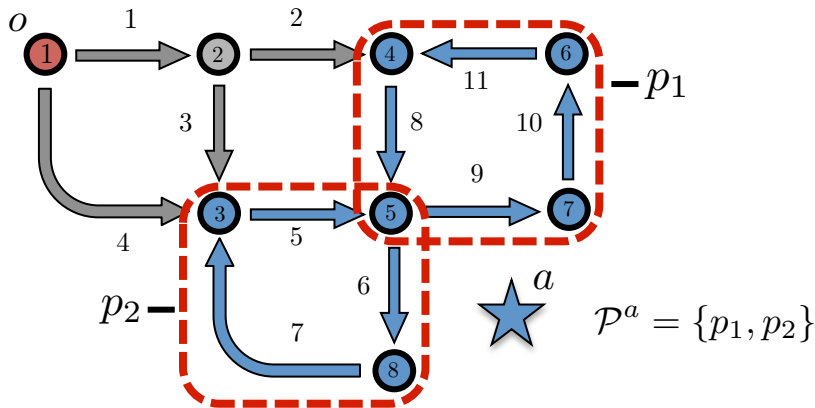
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Potential Function

$$P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

Edge Formulation



s_o^a : Traffic from origin o to attraction a
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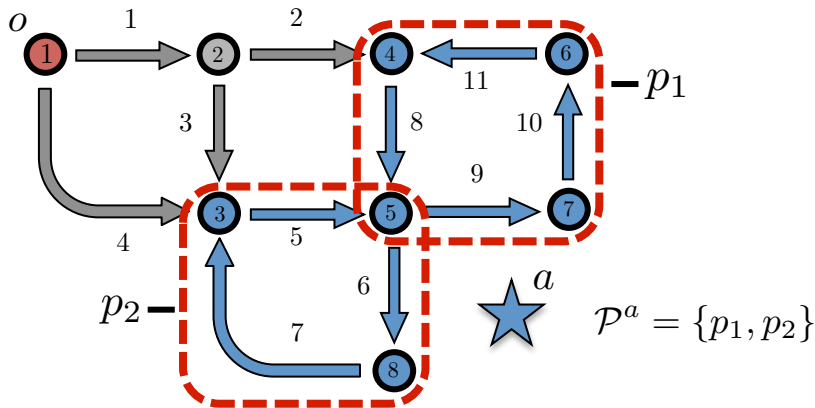
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Optimization Problem

$$\begin{aligned}
 \min_{x_{od}^{ap}, s_{od}^{ap}} \quad & P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du \\
 \text{s.t.} \quad & x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p \\
 & s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p
 \end{aligned}$$

Edge Formulation



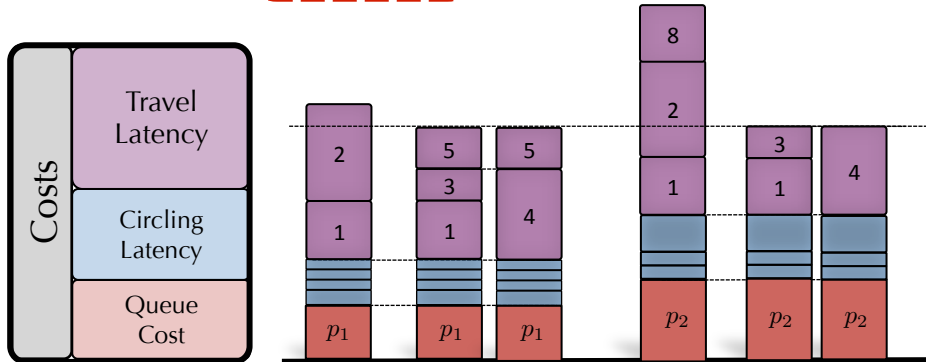
$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

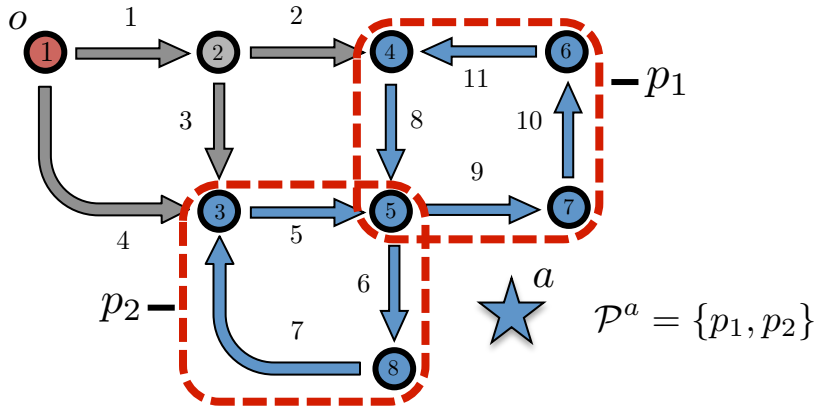
$$\text{s.t.} \quad x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p$$

$$s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p$$



Strategy	Path to Node	Node	Parking Area
	↑	4	Area 1
	↑	5	Area 1
	↑	5	Area 1
	↑	5	Area 2
	↑	3	Area 2
	↑	3	Area 2

Edge Formulation



$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

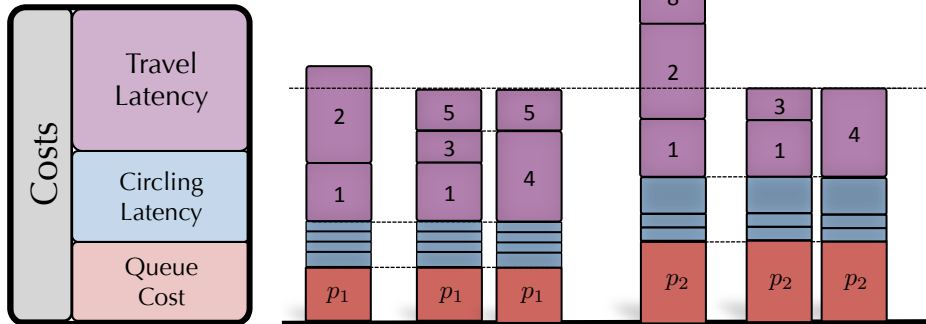
$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

$$\text{s.t.} \quad x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p$$

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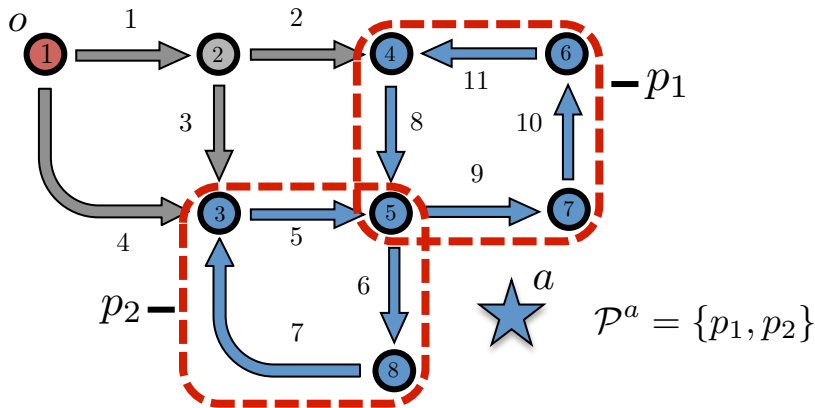
Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

Travel Latency



Strategy	Path to Node	↑ ↑ ↑ ↑ ↑ ↑
	Node	④ ⑤ ⑤ ③
	Parking Area	Area 1 Area 2

Edge Formulation



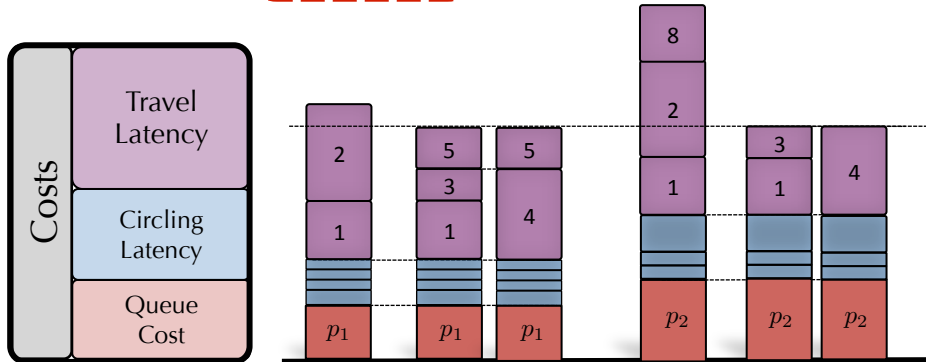
$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

$$\text{s.t.} \quad x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p$$

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Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

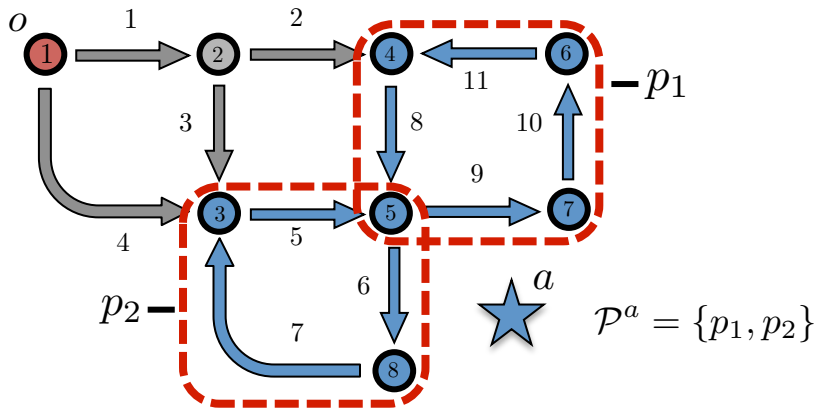
$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

Travel Latency
Circling Latency
Queue Cost



Strategy	Path to Node	↑	↑	↑	↑	↑	↑
	Node	4	5	5	5	3	
	Parking Area	Area 1			Area 2		

Edge Formulation



$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\begin{aligned} \min_{x_{od}^{ap}, s_{od}^{ap}} \quad & P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du \\ \text{s.t.} \quad & x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p \\ & s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p \end{aligned}$$

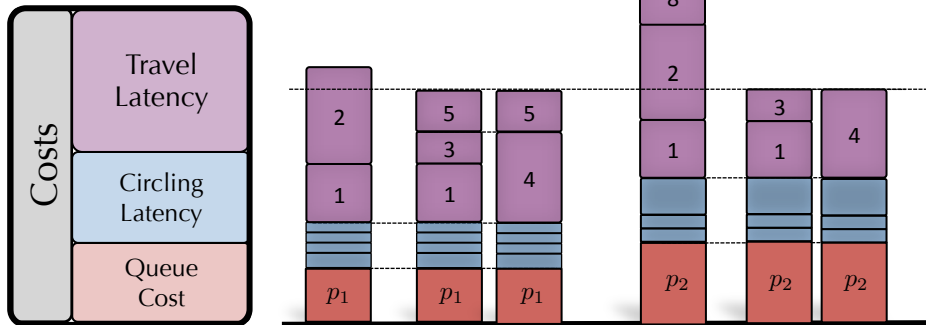
Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

First Order Optimality...

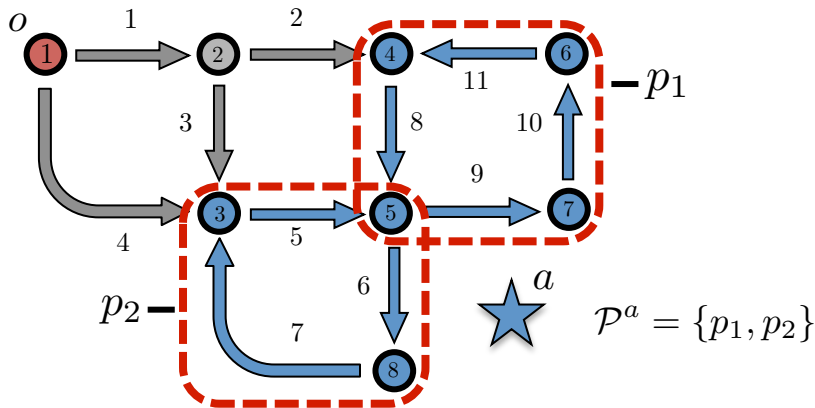
$$\begin{aligned} \mathcal{L}(x, s, \pi, \lambda, \nu, \mu) = & P(x) + \\ & - \sum_{o,d,a,p} (\pi_{od}^{ap})^T (Gx_{od}^{ap} - S_{od}^{ap}) - \sum_{o,d,a,p} (\nu_{od}^{ap})^T x_{od}^{ap} \\ & - \sum_{o,a} \lambda_o^a [\sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} - s_o^a] - \sum_{o,d,a,p} (\mu_{od}^{ap})^T s_{od}^{ap} \end{aligned}$$

Travel Latency
Circling Latency
Queue Cost



Strategy	Path to Node	↑ ↑ ↑ ↑ ↑ ↑
	Node	4 5 5 3
	Parking Area	Area 1 Area 2

Edge Formulation



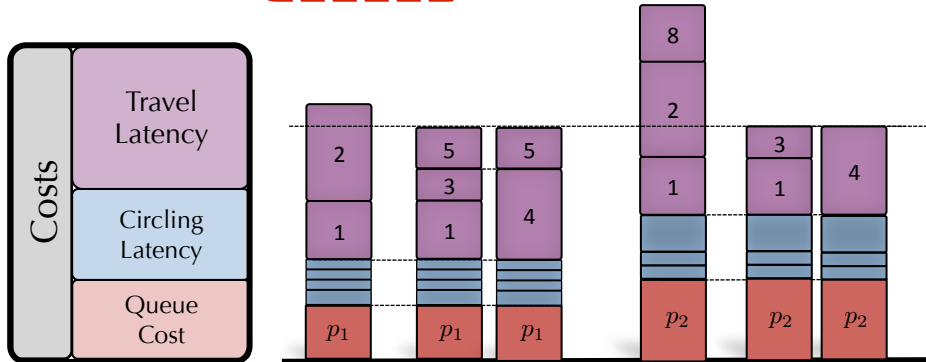
$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

$$\text{s.t.} \quad x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p$$

$$s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p$$

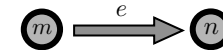


Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

First Order Optimality...

$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : l_e(x_e) = (\pi_{od}^{ap})_n - (\pi_{od}^{ap})_m + (\nu_{od}^{ap})_e$$

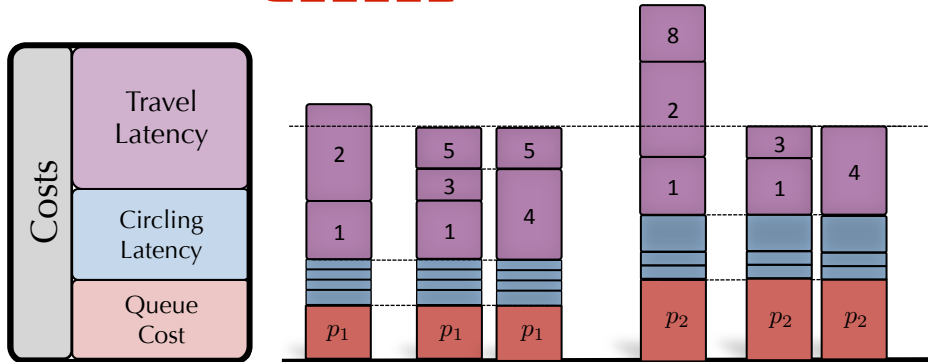
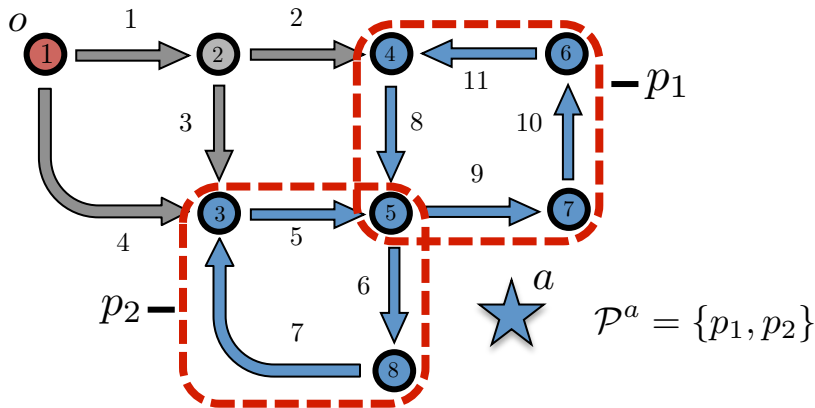


Travel Latency
Circling Latency
Queue Cost



Strategy	Path to Node	↑ ↑ ↑ ↑ ↑ ↑
	Node	4 5 5 3
	Parking Area	Area 1 Area 2

Edge Formulation



Strategy	Path to Node	Node	Parking Area
	↑ ↑ ↑ ↑ ↑ ↑	4 5 5 3	Area 1 Area 2

$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

$$\text{s.t.} \quad x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p$$

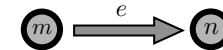
$$s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p$$

Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

First Order Optimality...

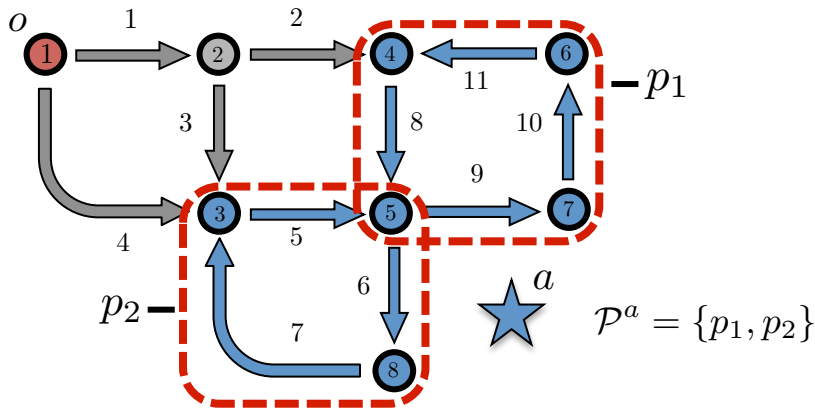
$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : l_e(x_e) = (\pi_{od}^{ap})_n - (\pi_{od}^{ap})_m + (\nu_{od}^{ap})_e$$



summing over path from o to d

Travel Latency
Circling Latency
Queue Cost

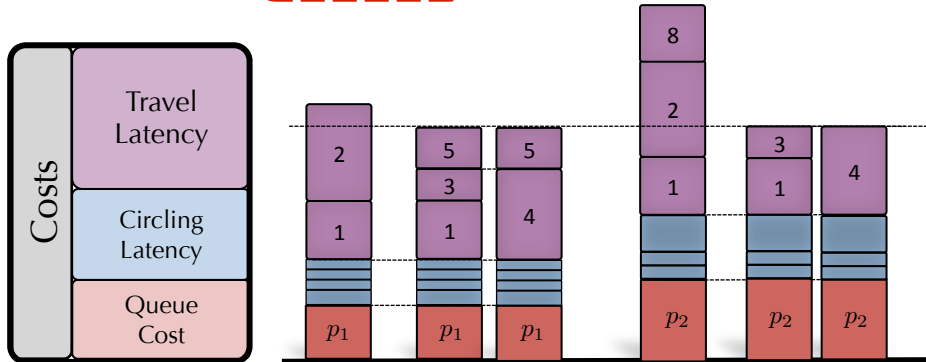
Edge Formulation



$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\begin{aligned} \min_{x_{od}^{ap}, s_{od}^{ap}} \quad & P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du \\ \text{s.t.} \quad & x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p \\ & s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p \end{aligned}$$



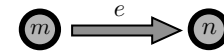
Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

Travel Latency
Circling Latency
Queue Cost

First Order Optimality...

$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : \quad l_e(x_e) = (\pi_{od}^{ap})_n - (\pi_{od}^{ap})_m + (\nu_{od}^{ap})_e$$

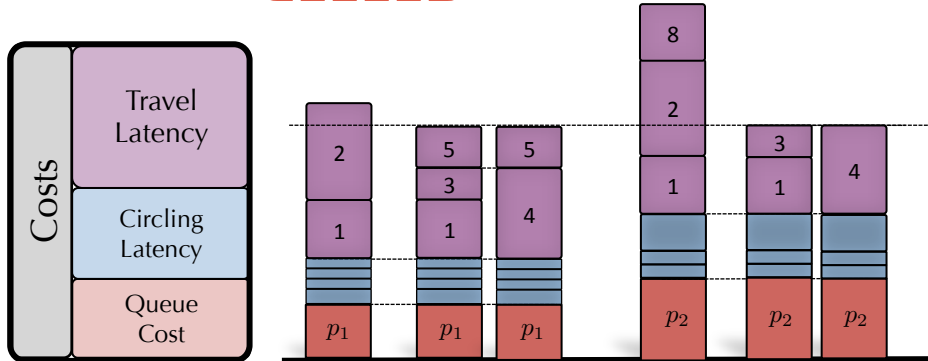
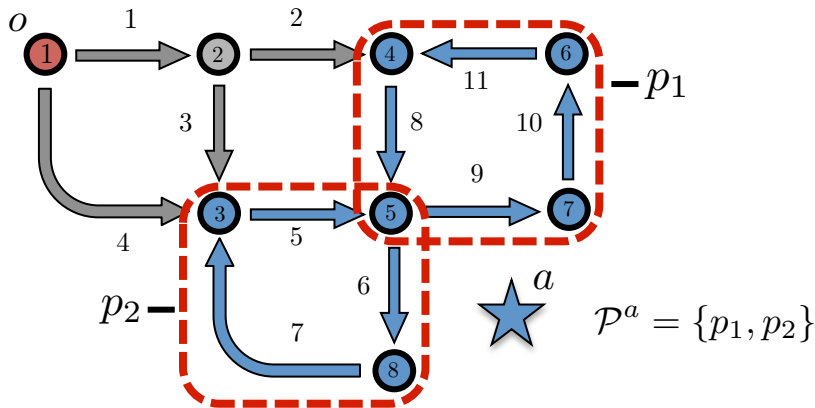


summing over path from o to d

$$\sum_{e \in \mathcal{R}} l_e(x_e) = (\pi_{od}^{ap})_d - (\pi_{od}^{ap})_o + \sum_{e \in \mathcal{R}} (\nu_{od}^{ap})_e$$

Mass	
Strategy	
Path to Node	
Node	
Parking Area	

Edge Formulation



Strategy	Path to Node	Node	Parking Area
	↑ ↑ ↑ ↑ ↑ ↑	4 5 5 3	Area 1 Area 2

$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

$$\text{s.t.} \quad x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p$$

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Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

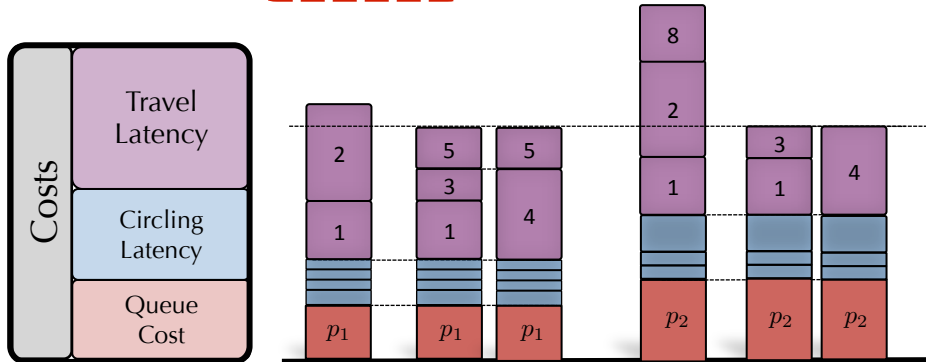
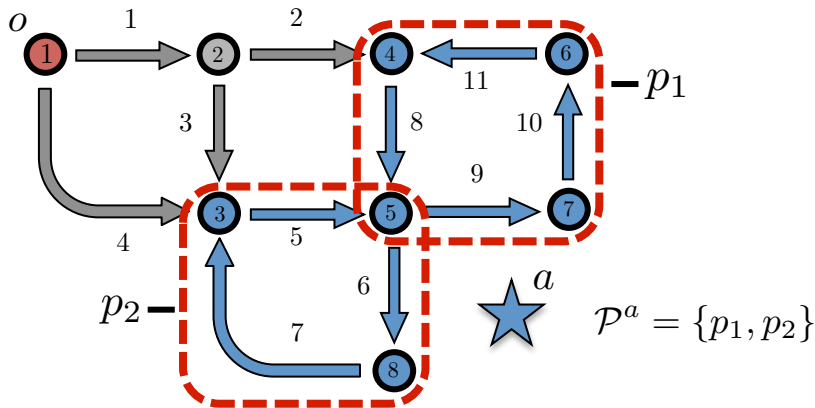
First Order Optimality...

$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : \sum_{e \in \mathcal{R}} l_e(x_e) = (\pi_{od}^{ap})_d - (\pi_{od}^{ap})_o + \sum_{e \in \mathcal{R}} (\nu_{od}^{ap})_e$$

$$\frac{\partial \mathcal{L}}{\partial s_{od}^{ap}} :$$

Travel Latency
Circling Latency
Queue Cost

Edge Formulation



Strategy	Path to Node	Node	Parking Area
	↑ ↑ ↑ ↑ ↑ ↑	4 5 5 3	Area 1 Area 2

$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

$$\text{s.t.} \quad x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p$$

$$s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p$$

Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

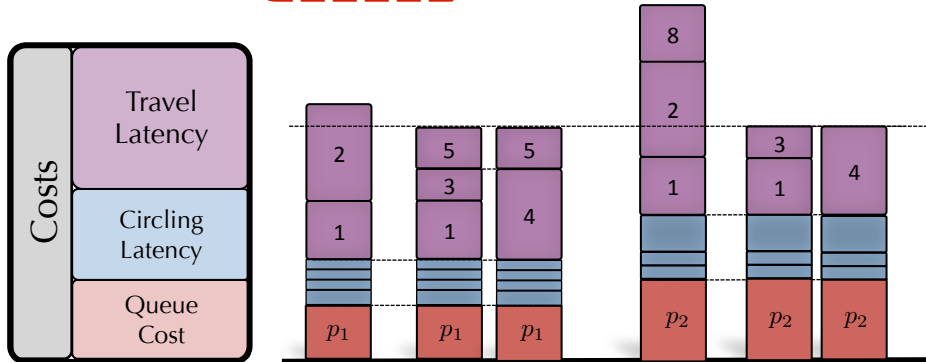
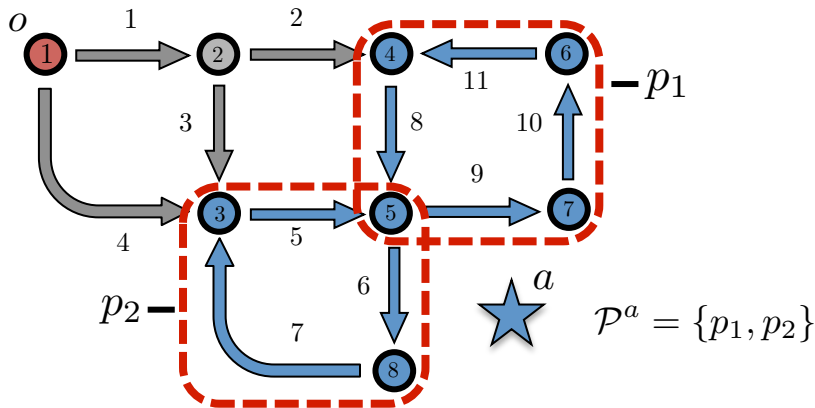
Travel Latency
Circling Latency
Queue Cost

First Order Optimality...

$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : \sum_{e \in \mathcal{R}} l_e(x_e) = (\pi_{od}^{ap})_d - (\pi_{od}^{ap})_o + \sum_{e \in \mathcal{R}} (\nu_{od}^{ap})_e$$

$$\frac{\partial \mathcal{L}}{\partial s_{od}^{ap}} : \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p - R_p + C_p s^p = (\pi_{od}^{ap})_o - (\pi_{od}^{ap})_d + \lambda_o^a + \mu_{od}^{ap}$$

Edge Formulation



Strategy	Path to Node	Node	Parking Area
	↑ ↑ ↑ ↑ ↑ ↑	4 5 5 3	Area 1 Area 2

$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

$$\text{s.t.} \quad x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p$$

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$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

Travel Latency
Circling Latency
Queue Cost

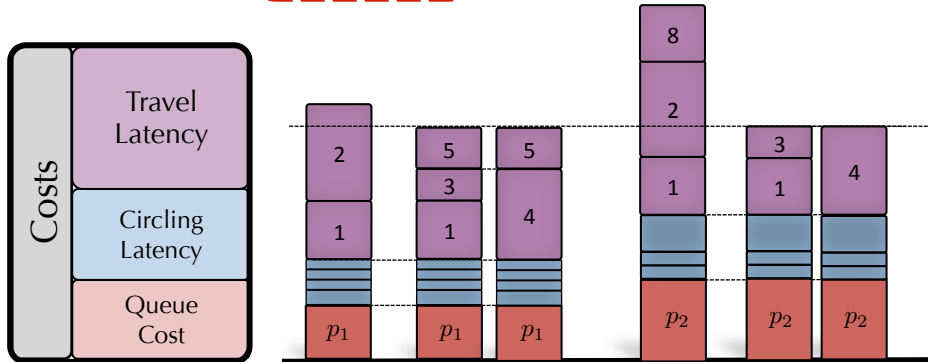
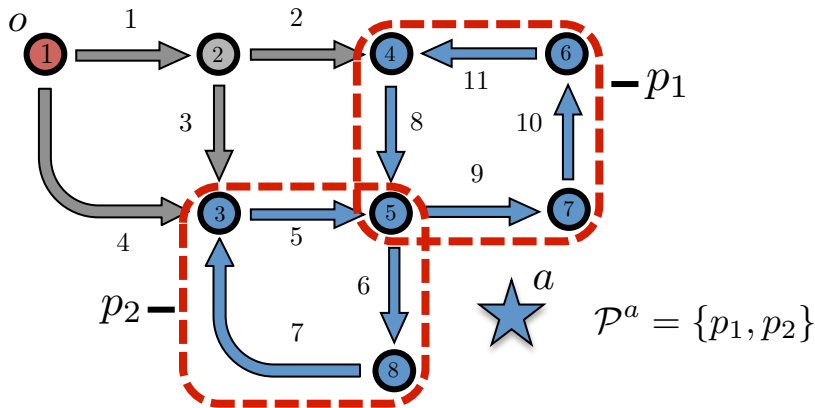
First Order Optimality...

$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : \sum_{e \in \mathcal{R}} l_e(x_e) = (\pi_{od}^{ap})_d - (\pi_{od}^{ap})_o + \sum_{e \in \mathcal{R}} (v_{od}^{ap})_e$$

$$\frac{\partial \mathcal{L}}{\partial s_{od}^{ap}} : \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p - R_p + C_p s^p = (\pi_{od}^{ap})_o - (\pi_{od}^{ap})_d + \lambda_o^a + \mu_{od}^{ap}$$

$$\sum_{e \in \mathcal{R}} l_e(x_e) + \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p - R_p + C_p s^p = \lambda_o^a + \sum_{e \in \mathcal{R}} (v_{od}^{ap})_e + \mu_{od}^{ap}$$

Edge Formulation



Strategy	Path to Node	↑ ↑ ↑ ↑ ↑ ↑
	Node	4 5 5 3
	Parking Area	Area 1 Area 2

$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\min_{x_{od}^{ap}, s_{od}^{ap}} P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du$$

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$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

Travel Latency
Circling Latency
Queue Cost

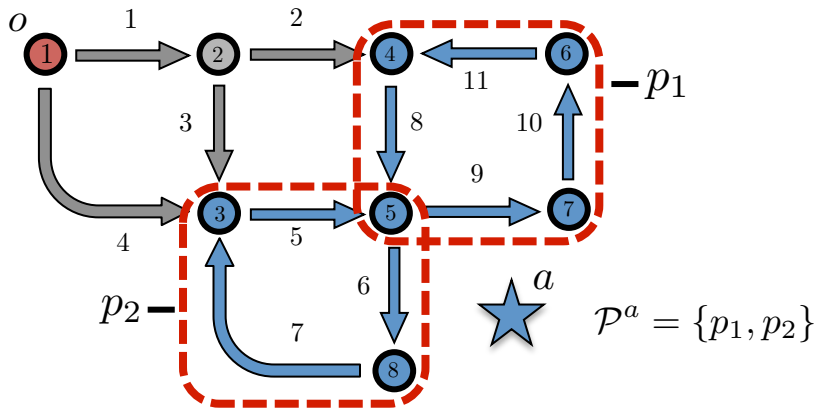
First Order Optimality...

$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : \sum_{e \in \mathcal{E}^r} l_e(x_e) = (\pi_{od}^{ap})_d - (\pi_{od}^{ap})_o + \sum_{e \in \mathcal{E}^r} (v_{od}^{ap})_e$$

$$\frac{\partial \mathcal{L}}{\partial s_{od}^{ap}} : \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p - R_p + C_p s^p = (\pi_{od}^{ap})_o - (\pi_{od}^{ap})_d + \lambda_o^a + \mu_{od}^{ap}$$

$\sum_{e \in \mathcal{E}^r} l_e(x_e)$	$\frac{1}{ \mathcal{E}^p } l(x) \mathbf{E}^p$	$-R_p + C_p s^p$	$= \lambda_o^a + \sum_{e \in \mathcal{E}^r} (v_{od}^{ap})_e + \mu_{od}^{ap}$
Traveling Cost	Circling Cost	Queue Cost	

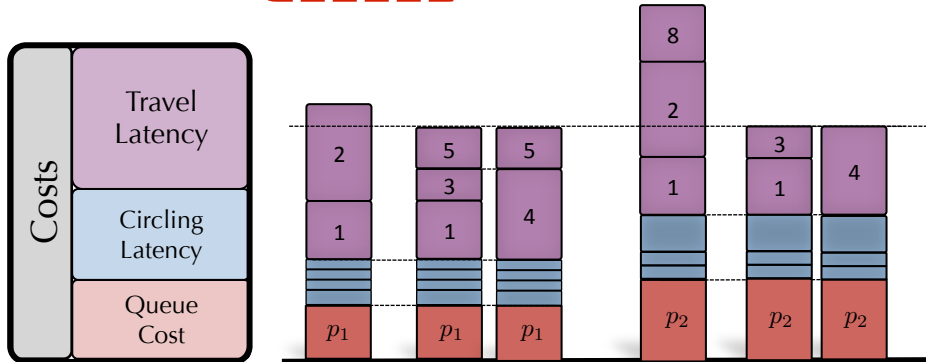
Edge Formulation



$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\begin{aligned} \min_{x_{od}^{ap}, s_{od}^{ap}} \quad & P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du \\ \text{s.t.} \quad & x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p \\ & s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p \end{aligned}$$



Gradient... $\nabla_{x_{od}^{ap}} P = l(x)$

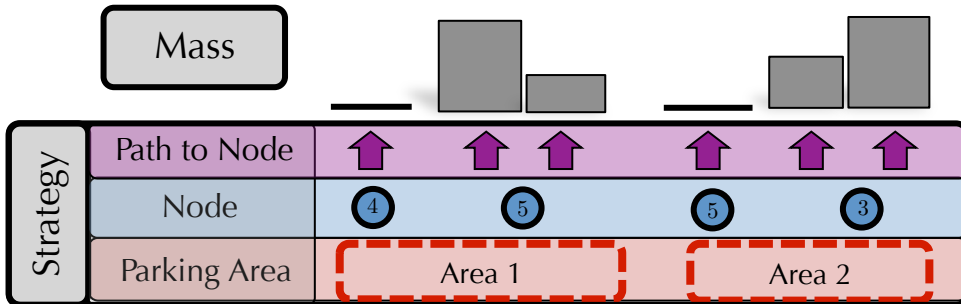
$$\nabla_{s_{od}^{ap}} P = \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + -R_p + C_p s^p$$

Travel Latency
Circling Latency
Queue Cost

First Order Optimality...

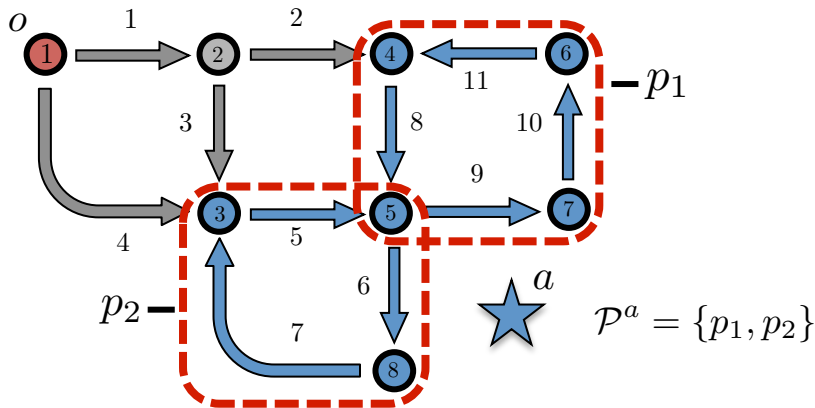
$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : \sum_{e \in \mathcal{E}^r} l_e(x_e) = (\pi_{od}^{ap})_d - (\pi_{od}^{ap})_o + \sum_{e \in \mathcal{E}^r} (v_{od}^{ap})_e$$

$$\frac{\partial \mathcal{L}}{\partial s_{od}^{ap}} : \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p - R_p + C_p s^p = (\pi_{od}^{ap})_o - (\pi_{od}^{ap})_d + \lambda_o^a + \mu_{od}^{ap}$$



$\sum_{e \in \mathcal{E}^r} l_e(x_e)$	$+$	$\frac{1}{ \mathcal{E}^p } l(x) \mathbf{E}^p$	$-$	$R_p + C_p s^p$	$=$	$\lambda_o^a + \sum_{e \in \mathcal{E}^r} (v_{od}^{ap})_e + \mu_{od}^{ap}$
Traveling Cost		Circling Cost		Queue Cost		Total Cost

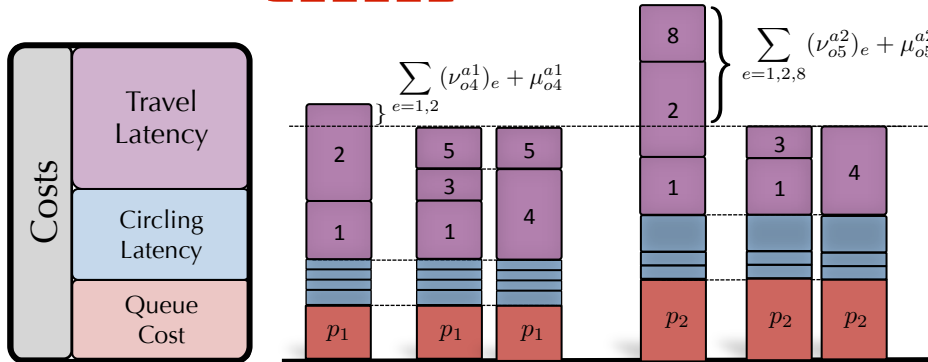
Edge Formulation



$$x = \sum_{o,a,p,d} x_{od}^{ap} + \sum_{o,a,p} \frac{1}{|\mathcal{E}^p|} \mathbf{E}^p \left[\sum_{d \in \mathcal{N}^p} s_{od}^{ap} \right] \quad s^p = \sum_{o,a} \sum_{d \in \mathcal{N}^p} s_{od}^{ap}$$

Optimization Problem

$$\begin{aligned} \min_{x_{od}^{ap}, s_{od}^{ap}} \quad & P(x) = \sum_e \int_0^{x_e} l_e(u) du + \sum_p \int_0^{s^p} -R_p + C_p u du \\ \text{s.t.} \quad & x_{od}^{ap} \geq 0, \quad Gx_{od}^{ap} = S_{od}^{ap} \quad \forall o, d, a, p \\ & s_{od}^{ap} \geq 0, \quad \sum_p \sum_{d \in \mathcal{N}^p} s_{od}^{ap} = s_o^a \quad \forall o, d, a, p \end{aligned}$$



Gradient...

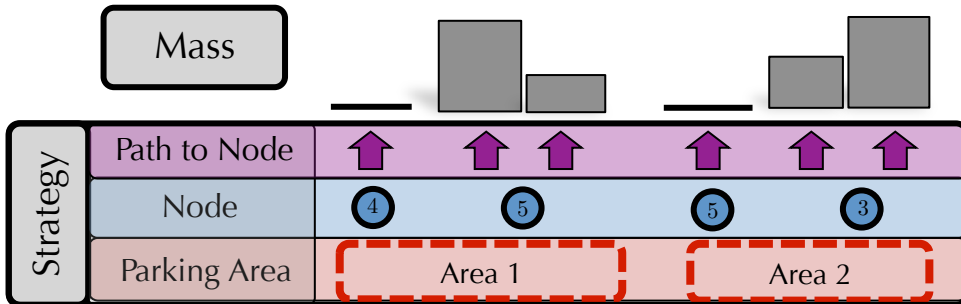
$$\begin{aligned} \nabla_{x_{od}^{ap}} P &= l(x) \\ \nabla_{s_{od}^{ap}} P &= \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p + \\ &\quad -R_p + C_p s^p \end{aligned}$$

Travel Latency
Circling Latency
Queue Cost

First Order Optimality...

$$\frac{\partial \mathcal{L}}{\partial (x_{od}^{ap})_e} : \sum_{e \in \mathcal{E}^r} l_e(x_e) = (\pi_{od}^{ap})_d - (\pi_{od}^{ap})_o + \sum_{e \in \mathcal{E}^r} (v_{od}^{ap})_e$$

$$\frac{\partial \mathcal{L}}{\partial s_{od}^{ap}} : \frac{1}{|\mathcal{E}^p|} l(x) \mathbf{E}^p - R_p + C_p s^p = (\pi_{od}^{ap})_o - (\pi_{od}^{ap})_d + \lambda_o^a + \mu_{od}^{ap}$$



$\sum_{e \in \mathcal{E}^r} l_e(x_e)$	$\frac{1}{ \mathcal{E}^p } l(x) \mathbf{E}^p$	$-R_p + C_p s^p$	$= \lambda_o^a + \sum_{e \in \mathcal{E}^r} (v_{od}^{ap})_e + \mu_{od}^{ap}$
Traveling Cost	Circling Cost	Queue Cost	Total Cost
			Extra Cost