

Lecture : Bases and Coordinates

Winter 2021

Lecturer: Dan Calderone

Basis

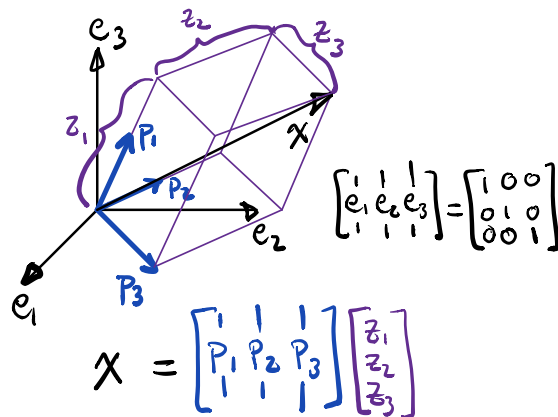
A set of vectors $\{V_i\}_{i=1}^n$ are a **basis** for a vector space \mathcal{V} if

- $\{V_i\}_{i=1}^n$ span \mathcal{V} .
- $\{V_i\}_{i=1}^n$ are linearly independent

Every basis for \mathcal{V} has the same number of vectors and the number of vectors in a basis for \mathcal{V} is called the **dimension** of \mathcal{V} .

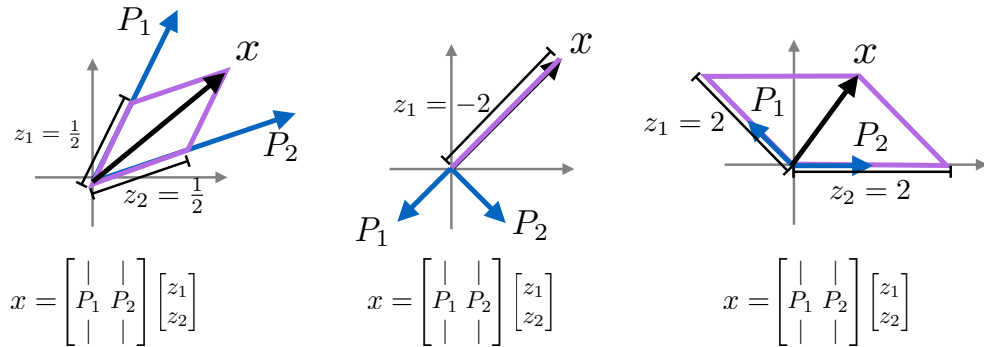
Change of Basis

Suppose we have a basis for \mathbb{R}^n stored in the columns of a square matrix $P \in \mathbb{R}^{n \times n}$ and a vector $x \in \mathbb{R}^n$. The *coordinates* of x with respect to the basis P are the coefficients of the linear combination of the columns of P that gives the vector x . We represent these coordinates in a vector $z \in \mathbb{R}^n$ and have that $x = Pz$. Note that x is really the coordinates of itself with respect to the *standard basis vectors* which are the columns of the identity matrix, ie. $x = Ix$.



To compute the coordinates of x with respect to P , we simply invert P , ie. $z = P^{-1}x$. If the columns of P are a basis, then they must be linearly independent and P is invertible.

For simple 2×2 and 3×3 cases, we could also compute the coordinates z by drawing the basis vectors and x and eyeballing the appropriate coordinates as in the figure above. This is a useful exercise in order to develop intuition coordinates. We give several examples in the figures below. (Once you guess z , you can always easily check how close you are by computing Pz and comparing it with x .)



Similarity Transforms

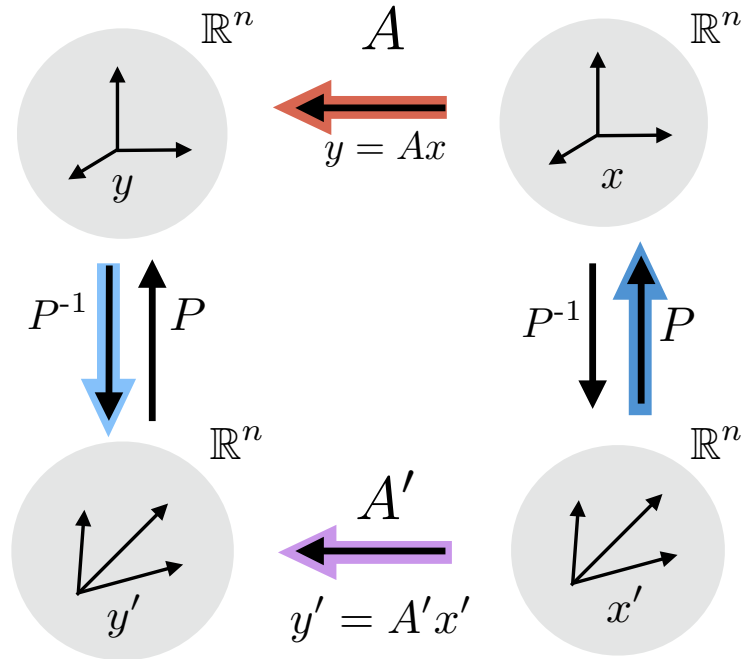
Now suppose, we have a square matrix $A \in \mathbb{R}^{n \times n}$ that transforms the vector $x \in \mathbb{R}^n$ into a vector $y \in \mathbb{R}^n$, ie. $y = Ax$. We represent both x and y in terms of a new basis given by the columns of $P \in \mathbb{R}^{n \times n}$, ie. $x = Px'$ and $y = Py'$. We want to find a matrix A' that represents the action of A when x and y are expressed in the x' and y' coordinates respectively, ie. we want to find $A' \in \mathbb{R}^{n \times n}$ such that $y' = A'x'$. We can do this by plugging in the relationships between x and z

$$y = Ax \tag{1}$$

$$Py' = APx' \tag{2}$$

$$y' = \underbrace{P^{-1}AP}_{A'} x' \tag{3}$$

We say that A' is related to A by a *similarity transform*, ie. A' represents the transformation of A just with respect to a different coordinate system. The construction of A' is illustrated in the figure below.



$$A' = P^{-1} A P$$

Similarity Transform: $A \in \mathbb{R}^{n \times n}$

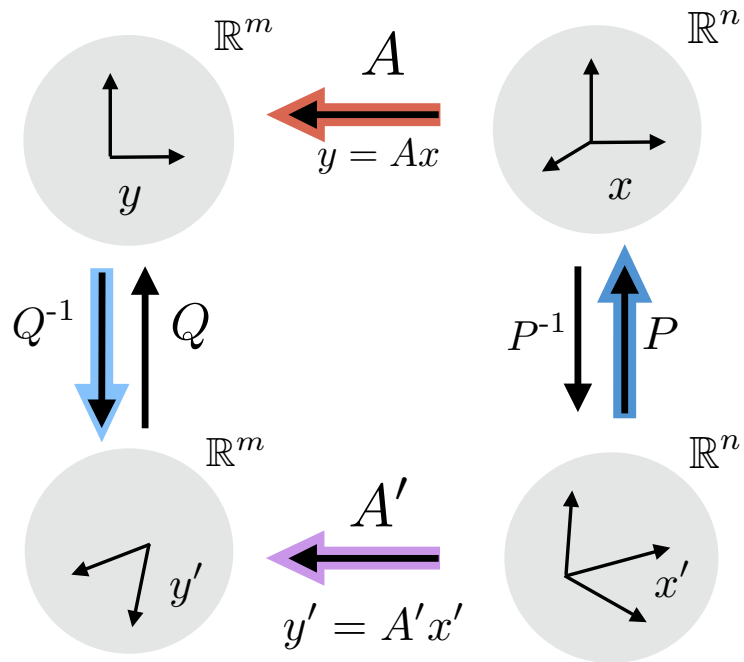
A generalization of this concept is that $x \in \mathbb{R}^n$ and $y \in \mathbb{R}^m$ are transformed under different coordinate transformations, ie. $x = Px'$ and $y = Qy'$. A is then transformed as

$$y = Ax \tag{4}$$

$$Qy' = APx' \tag{5}$$

$$y' = \underbrace{Q^{-1}AP}_{A'} x' \tag{6}$$

Note that here, it is not necessary that A be square and x and y have the same dimension. This situation is illustrated in the figure below.



$$A' = Q^{-1} A P$$

Coordinate Transform: $A \in \mathbb{R}^{m \times n}$