

$$\underline{x+y=1} \Rightarrow 1 + \frac{y}{x} = \frac{1}{x} \quad \boxed{x \neq 0} \Leftarrow$$

$$\bar{A}^{-1} \bar{A}x = \bar{y} \Rightarrow A^{-1}y = x \quad \boxed{\bar{A}^{-1} \text{ exists}}$$

A tall

$$\underbrace{\begin{bmatrix} v^T \\ v^T \\ \vdots \\ v^T \end{bmatrix}}_{m \text{ eqns}} \underbrace{\begin{bmatrix} A \end{bmatrix}}_n x = \underbrace{\begin{bmatrix} y \end{bmatrix}}_n \Rightarrow \underbrace{v^T A x}_{\text{scalar}} = \underbrace{v^T y}_{\text{scalar}} \quad 1 \text{ eqn}$$

$$w^T(A)x = w^T y \quad \underbrace{w^T A x}_{\text{scalar}} = \underbrace{w^T y}_{\text{scalar}}$$

m eqns \rightarrow 2 eqns or 1 eqn etc

$$\underbrace{v^T [A x = y]}_{\downarrow \downarrow} \Rightarrow 0 = 0 \Leftarrow$$

$$v^T A = 0 \quad v^T y = 0$$

full col rank

$$(A^T A)^{-1} A^T [A x = y] = \boxed{x = (A^T A)^{-1} A^T y}$$

$$M \boxed{A x = y}$$

$$\boxed{M A x = M y}$$

$$\boxed{A} \quad x = \boxed{y}$$

$$\boxed{\begin{matrix} A \\ \vdots \\ A \end{matrix}} \quad x = \begin{matrix} y_1 \\ \vdots \\ y_n \end{matrix}$$

not full row rank = extra equations ←
 (repeats) fear $y \notin R(A)$

not full col rank = redundant parameters

two x 's give you the
same y .

$$\underbrace{(A^T A)^+}_{\text{pseudo inverse}} \quad \underbrace{A^T}_{\text{not full col rank}} \quad \underbrace{A x =}_{\text{ }} \quad \underbrace{(A^T A)^+ A^T y =}_{\text{ }} \quad \underbrace{x + z}_{\text{a solution}} \quad z \in N(A)$$

$x \perp N(A)$ to $Ax = y$.
minimum norm soln.

Moore -
Penrose
pseudo inverse

for any $A \in \mathbb{R}^{m \times n}$

A is tall \Rightarrow least squares

A is fat \Rightarrow minimum norm

$$A = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^* \quad A^+ = V \begin{bmatrix} \Sigma^{-1} & 0 \\ 0 & 0 \end{bmatrix} U^*$$

$$Ax = y$$

$$\left(\begin{array}{|c|} \hline A^T \\ \hline \end{array} \right) \left[\begin{array}{|c|} \hline -A \\ \hline \vdots \\ \hline \text{full row rank} \\ \hline \end{array} \right] \left[\begin{array}{|c|} \hline 1 \\ \hline x \\ \hline \end{array} \right] = \left[\begin{array}{|c|} \hline y \\ \hline \end{array} \right]$$

$$\frac{AA^T(AA^T)^{-1}}{\mathbb{I}} = I$$

Guess:
 $\underline{x} = \underline{A^T(AA^T)^{-1}y}$

$$\underline{A(A^T(AA^T)^{-1})y} = y \quad \checkmark$$

$$x = A^T(AA^T)^{-1}y + z \quad z \in N(A)$$

Review: Fundamental Thm of LA

$y \in \mathbb{C}^m$
codomain

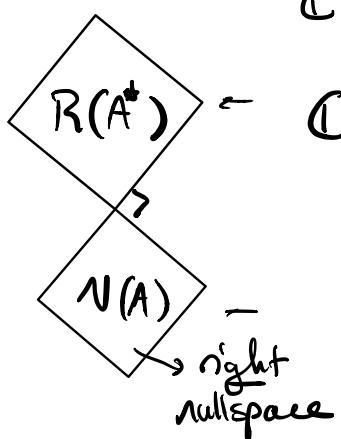
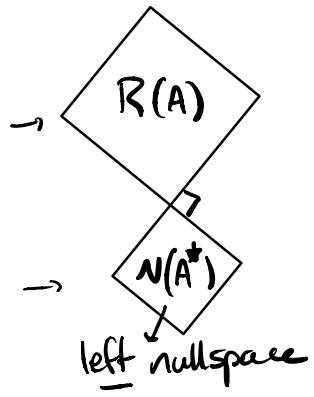
$$y = Ax$$

\leftarrow

$A \in \mathbb{C}^{m \times n}$

$x \in \mathbb{C}^n$
domain

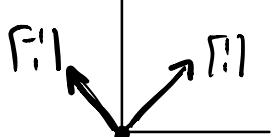
$$\mathbb{C}^n = R(A^*) \oplus N(A)$$



$$\mathbb{C}^m = R(A) \oplus N(A^*)$$

real case: $y^T A = 0$

Ex. $\text{CoDom} = \mathbb{R}^2$



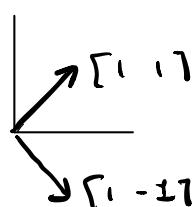
$$R(A) = \mathbb{R}^2$$

$$N(A^T) = 0$$

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

\leftarrow

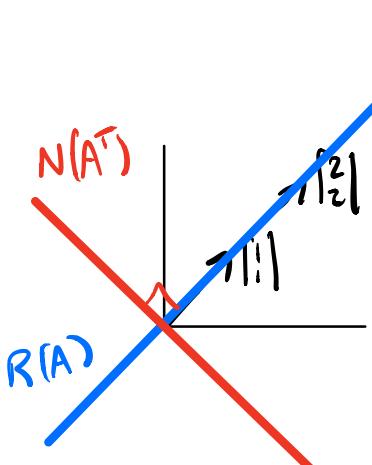
$\text{Dom} = \mathbb{R}^2$



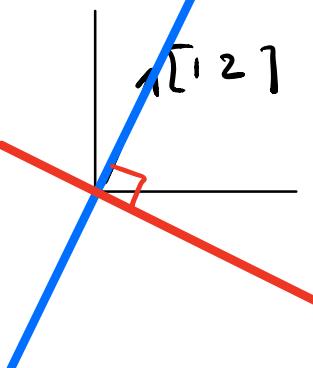
$$R(A^T) = \mathbb{R}^2$$

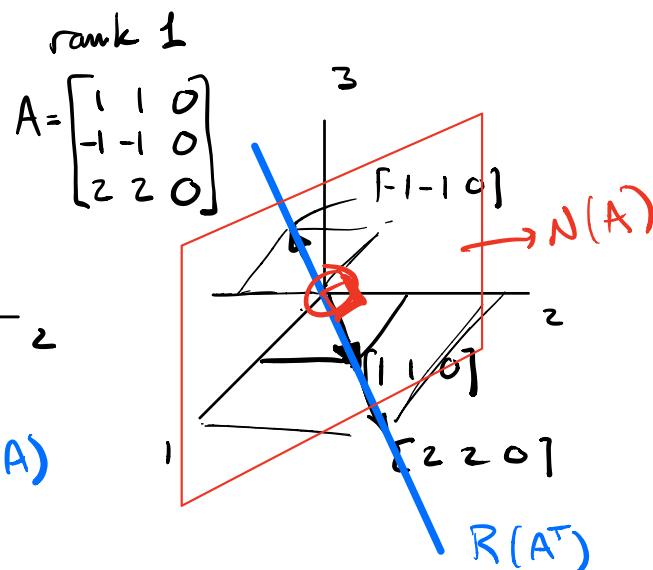
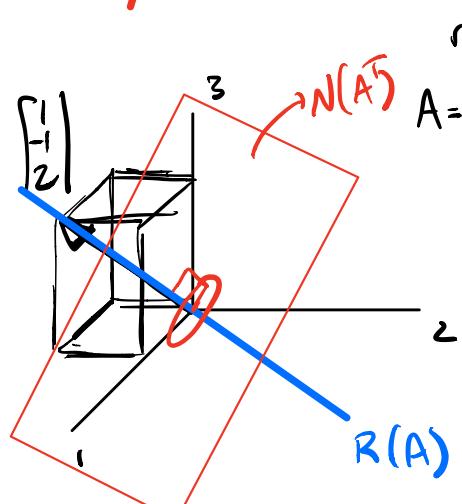
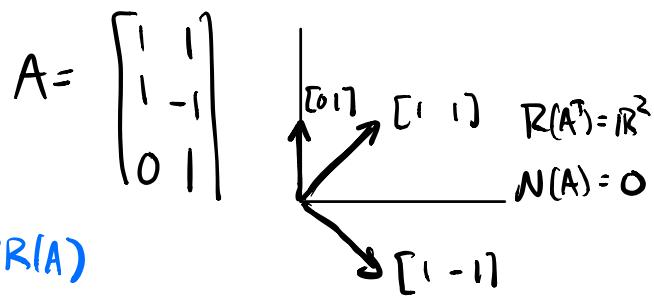
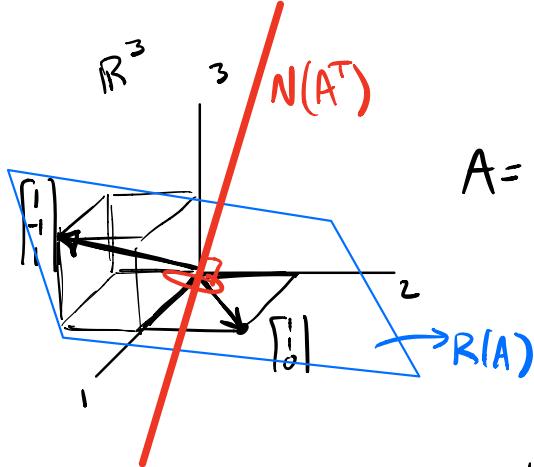
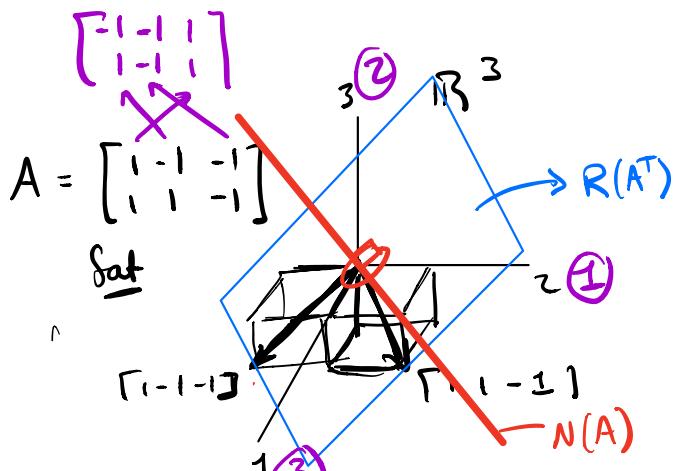
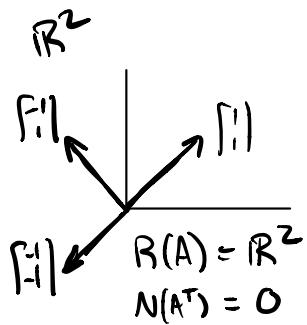
$$N(A) = \emptyset$$

$R(A^T)$



$$A = \begin{bmatrix} 1 & 2 \\ 1 & 2 \end{bmatrix}$$





$$\underline{R(A^T)} \perp \underline{N(A)}$$

$$\begin{aligned} & \xrightarrow{x_1 \in R(A^T)} x_2 \in N(A) \rightarrow Ax_2 = 0 \\ & \exists z \boxed{x_1 = A^T z} \quad \boxed{\underbrace{x_1^T x_2}_{\text{G}} = \underbrace{z^T A x_2}_{=0} = 0} \end{aligned}$$

$$M = \begin{bmatrix} n \\ \underline{B} \quad \underline{C} \\ \underline{n_1} \quad \underline{n_2} \end{bmatrix} \quad M \in \mathbb{R}^{n \times n} \quad \text{invertible}$$

$B \in \mathbb{R}^{n \times n_1}$

$C \in \mathbb{R}^{n \times n_2}$

all cols of M, B, C are lin. ind.

$\begin{matrix} \text{cols } C \\ \text{are} \\ \text{lin. ind.} \\ \text{to cols of } B \end{matrix} \Rightarrow \boxed{C^T B = \begin{bmatrix} 0 \end{bmatrix}_{n_2}}$

$$\boxed{M^{-1} = \begin{bmatrix} (B^T B)^{-1} B^T \\ (C^T C)^{-1} C^T \end{bmatrix}}$$

$$\tilde{M}^{-1} = \frac{1}{\det(M)} \frac{\text{Adj}(M)}{\downarrow}$$

$$\begin{aligned} \tilde{M}^{-1} M &= \begin{bmatrix} (B^T B)^{-1} B^T \\ (C^T C)^{-1} C^T \end{bmatrix} \begin{bmatrix} B \\ C \end{bmatrix} = \begin{bmatrix} (B^T B)^{-1} B^T B \\ (C^T C)^{-1} C^T C \end{bmatrix} = \begin{bmatrix} I \\ 0 \end{bmatrix} = \boxed{I} \end{aligned}$$

Stretch... $M^{-1} M = I \Rightarrow M M^{-1} = I \leftarrow \text{fact}$

$$M M^{-1} = \begin{bmatrix} B \\ C \end{bmatrix} \begin{bmatrix} (B^T B)^{-1} B^T \\ (C^T C)^{-1} C^T \end{bmatrix} = \underbrace{B (B^T B)^{-1} B^T}_{\substack{\text{Proj onto} \\ \text{span of } B}} + \underbrace{C (C^T C)^{-1} C^T}_{\substack{\text{Proj onto} \\ \text{span of } C}} = \boxed{I}$$

span of cols of B perpendicular span of cols of C

not obvious

Define a coord transform $M = [BC]$

related to the $R(A^T)$

$\in N(A)$

constructed a basis

for $N(A)$

\Rightarrow cols of N

$$P = [A^T N]$$

assume A is full row
rank
and N is full
col rank

$$M^T M = \begin{bmatrix} B^T \\ C^T \end{bmatrix} \begin{bmatrix} B & C \end{bmatrix} = \begin{bmatrix} B^T B & B^T C \\ C^T B & C^T C \end{bmatrix} = \begin{bmatrix} B^T B & 0 \\ 0 & C^T C \end{bmatrix}$$

$$\begin{bmatrix} B^T B & 0 \\ 0 & C^T C \end{bmatrix}^{-1} = \begin{bmatrix} (B^T B)^{-1} & 0 \\ 0 & (C^T C)^{-1} \end{bmatrix}$$

$$\underbrace{\begin{bmatrix} (B^T B)^{-1} & 0 \\ 0 & (C^T C)^{-1} \end{bmatrix}}_{M^{-1}} M^T M = I$$

$$M^{-1} = \begin{bmatrix} (B^T B)^{-1} & 0 \\ 0 & (C^T C)^{-1} \end{bmatrix} \begin{bmatrix} B^T \\ C^T \end{bmatrix}$$

$$\underline{x} = Px' = [A^T N] \begin{bmatrix} x'_1 \\ x'_2 \end{bmatrix} = A^T x'_1 + N x'_2$$

$$x' = P^{-1} \underline{x}$$

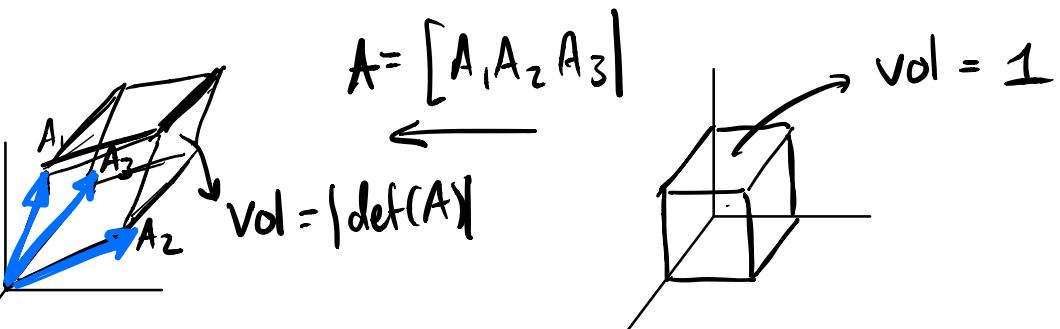
$$P^{-1} = \begin{bmatrix} (AA^T)^{-1} A \\ (N^T N)^{-1} N^T \end{bmatrix}$$

$$\begin{bmatrix} x'_1 \\ x'_2 \end{bmatrix} = \begin{bmatrix} (AA^T)^{-1} A \underline{x} \\ (N^T N)^{-1} N^T \underline{x} \end{bmatrix}$$

EIGEN VALUES & EIGEN VECTORS:

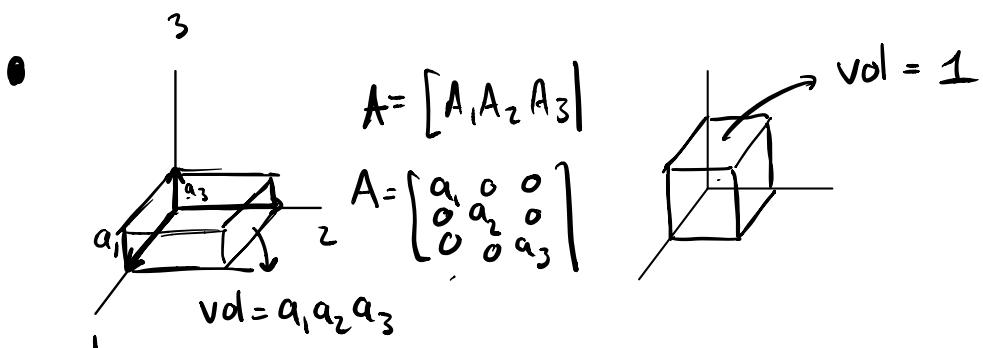
EIGEN: "SAME" in German

Review Determinants



- Compute Vol of parallelepiped

$$\text{Vol} = \left| \det \begin{bmatrix} \mathbf{A}_1 & \mathbf{A}_2 & \mathbf{A}_3 \end{bmatrix} \right|$$



$$A \in \mathbb{R}^{n \times n}$$

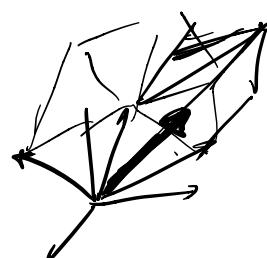
diagonal

$$\det(A) = A_{11} \times \cdots \times A_{nn}$$

- $\det(A) = 0$ A flattens out the unit cube

$$\det(A) = 0$$

A not full rank



EIGENVALUE PROBLEM: $A \in \mathbb{R}^{n \times n}$

find λ : scalar s.t. $\underline{A}\underline{v} = \underline{\lambda}\underline{v}$
 v : vector