

# Graph Structures & Matrices

## Algebraic Graph Theory

**Acknowledgements:** Mehran Mesbahi  
Mathias Colbert Russelson,  
Sarah Li  
Shahriar Talebi

**Spring 2022 - Dan Calderone**

# Graphs

**Graph:**

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

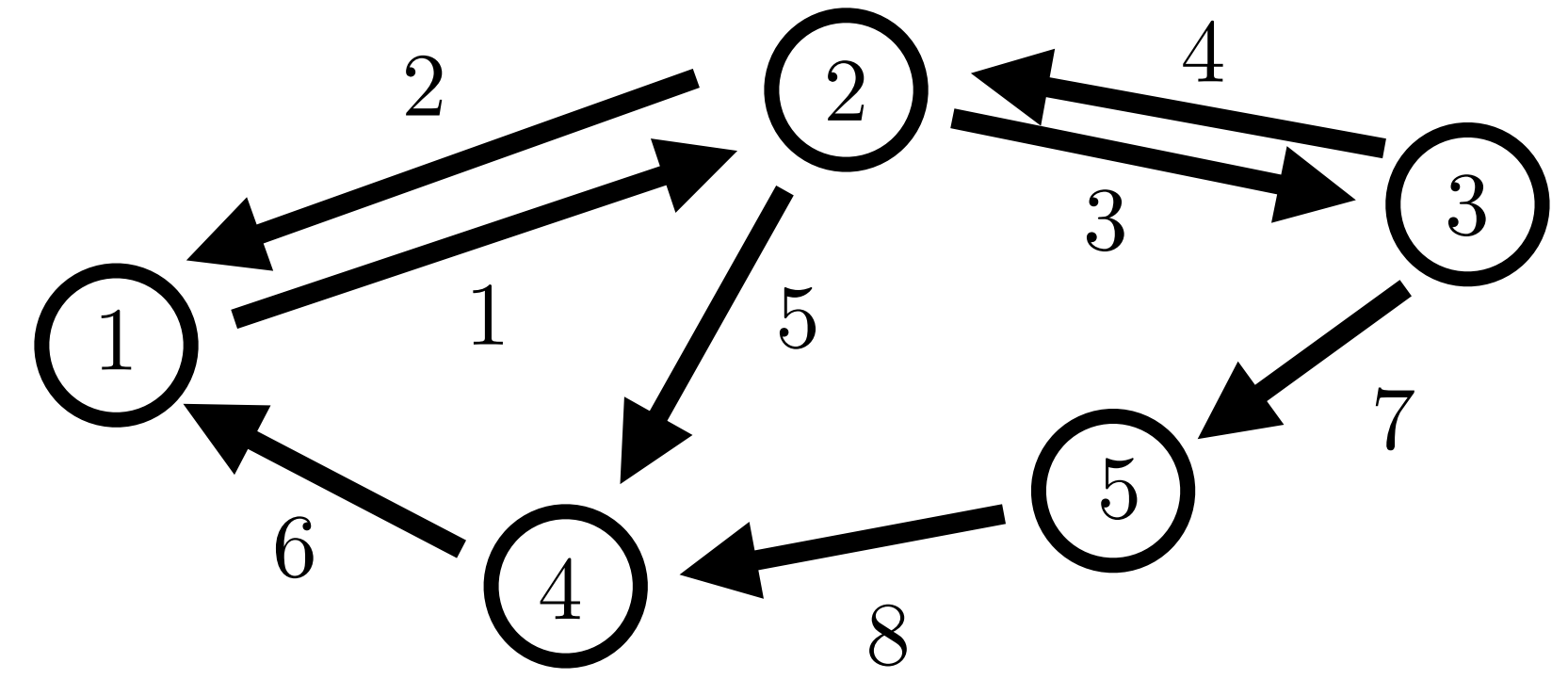
**Vertices**

$$v \in \mathcal{V}$$

**Edges**

$$e \in \mathcal{E}$$

$$e = (v, v')$$



# Graphs

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**Directed or Undirected Edges**

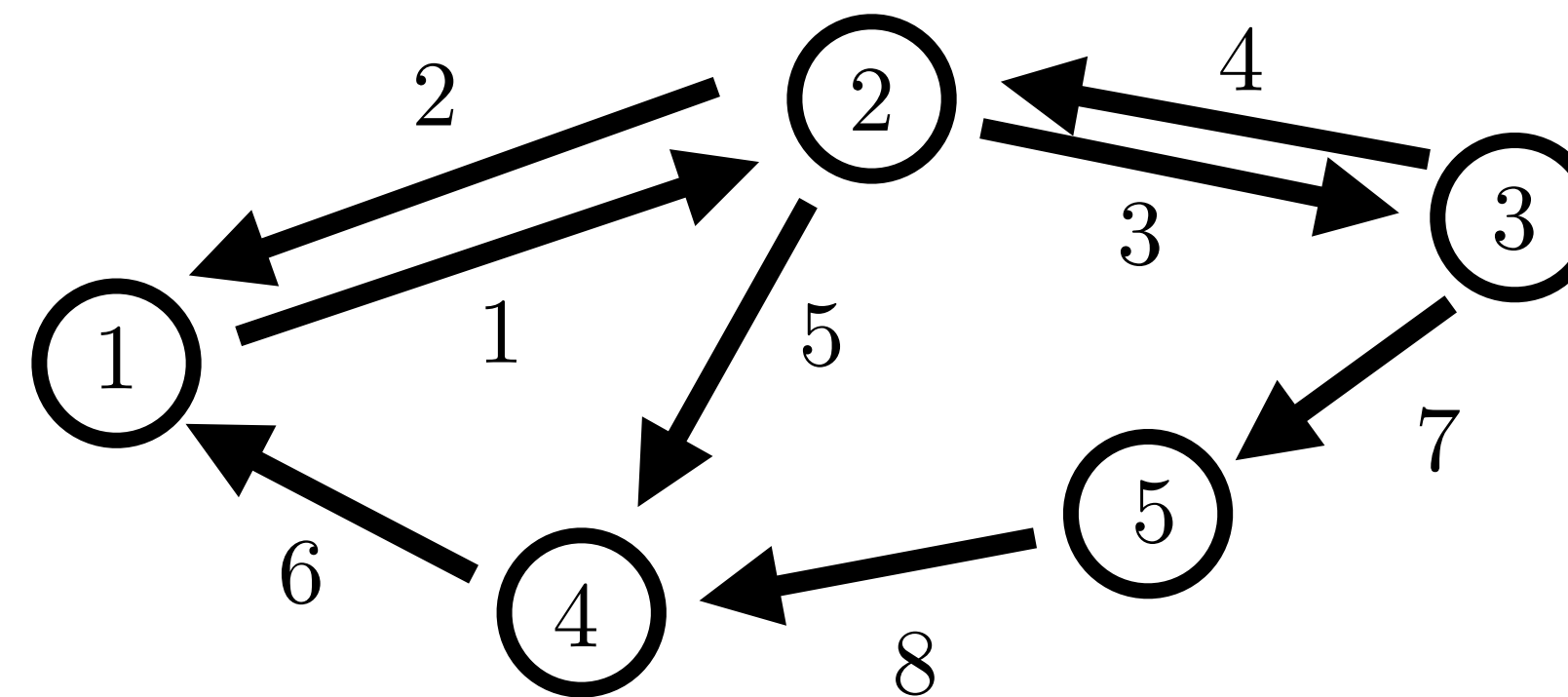
$$e = (v, v')$$

edge  $e$  is “incident” to  $v$  and  $v'$

**Neighborhoods:** set of “adjacent” nodes

$$\mathcal{N}_v = \{v' \in \mathcal{V} \mid e = (v, v') \in \mathcal{E}\}$$

(degree of vertex)  $d_v = |\mathcal{N}_v|$



# Incidence Matrix

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

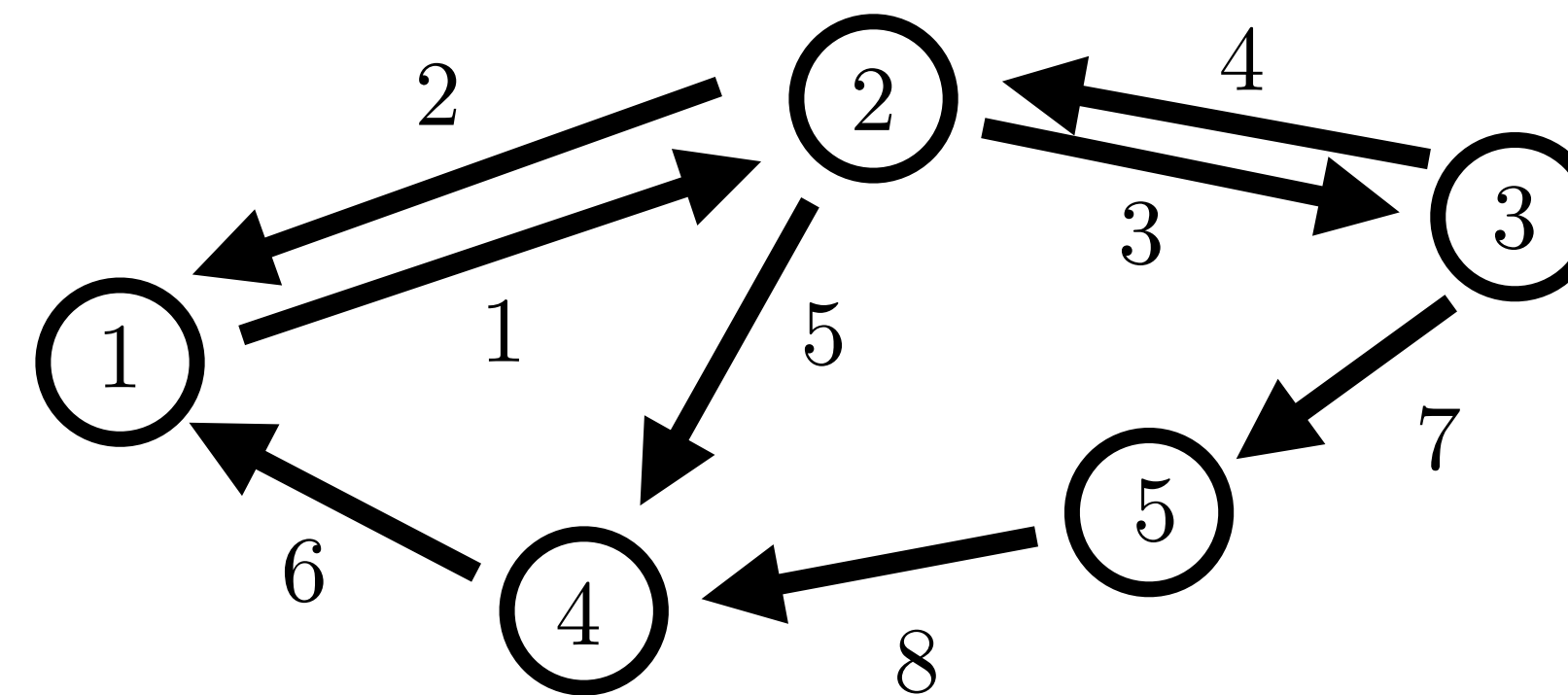
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**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{if } e \text{ out of } v \\ 0 & ; \text{otherwise} \end{cases}$$

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$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

← edges →

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↑ vertices  
↓

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

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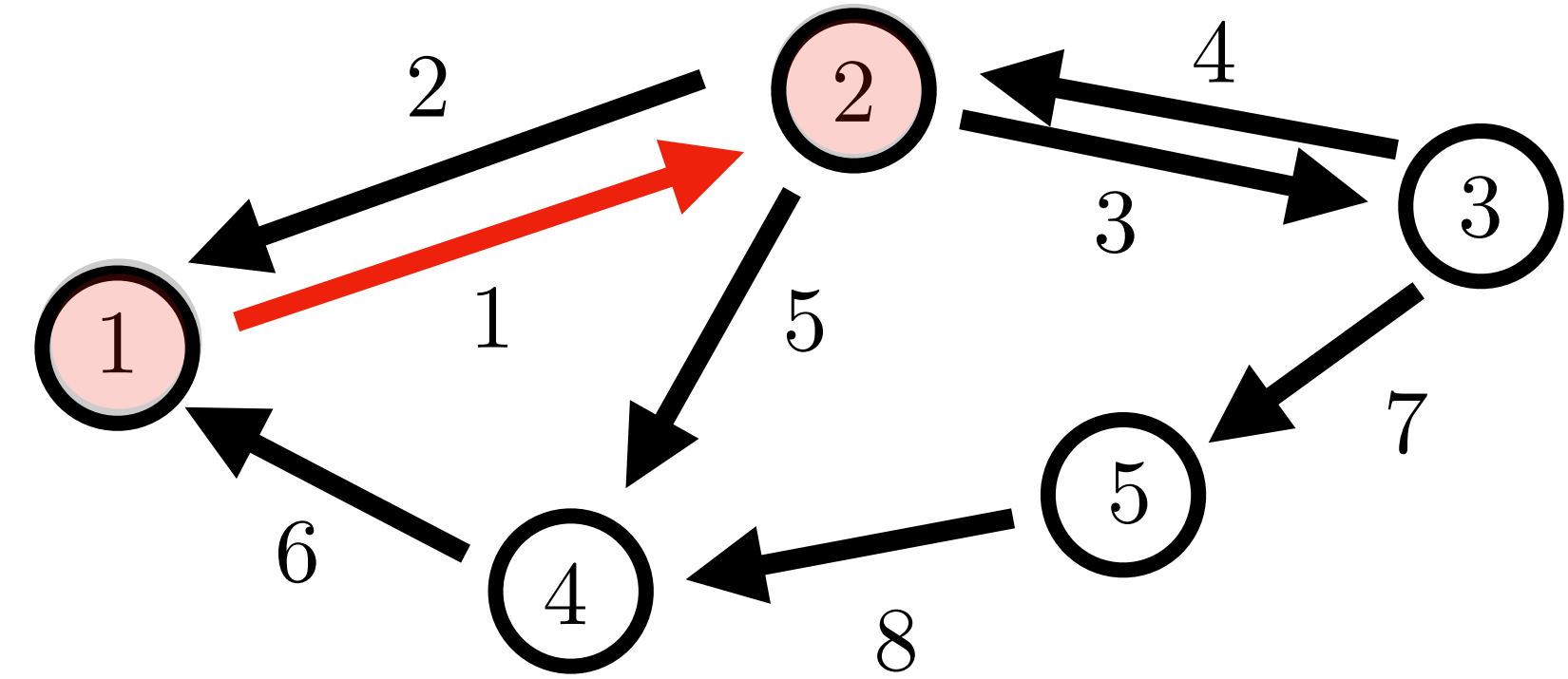
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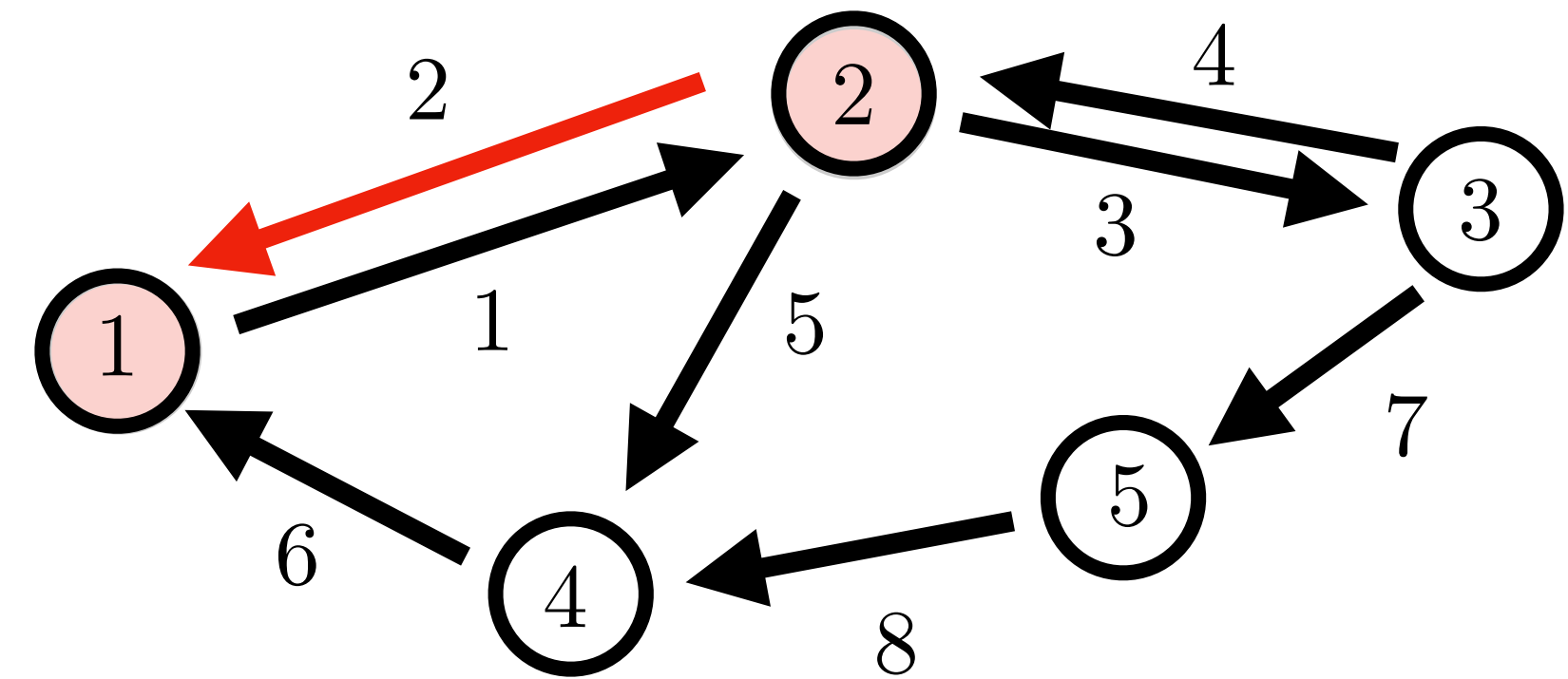
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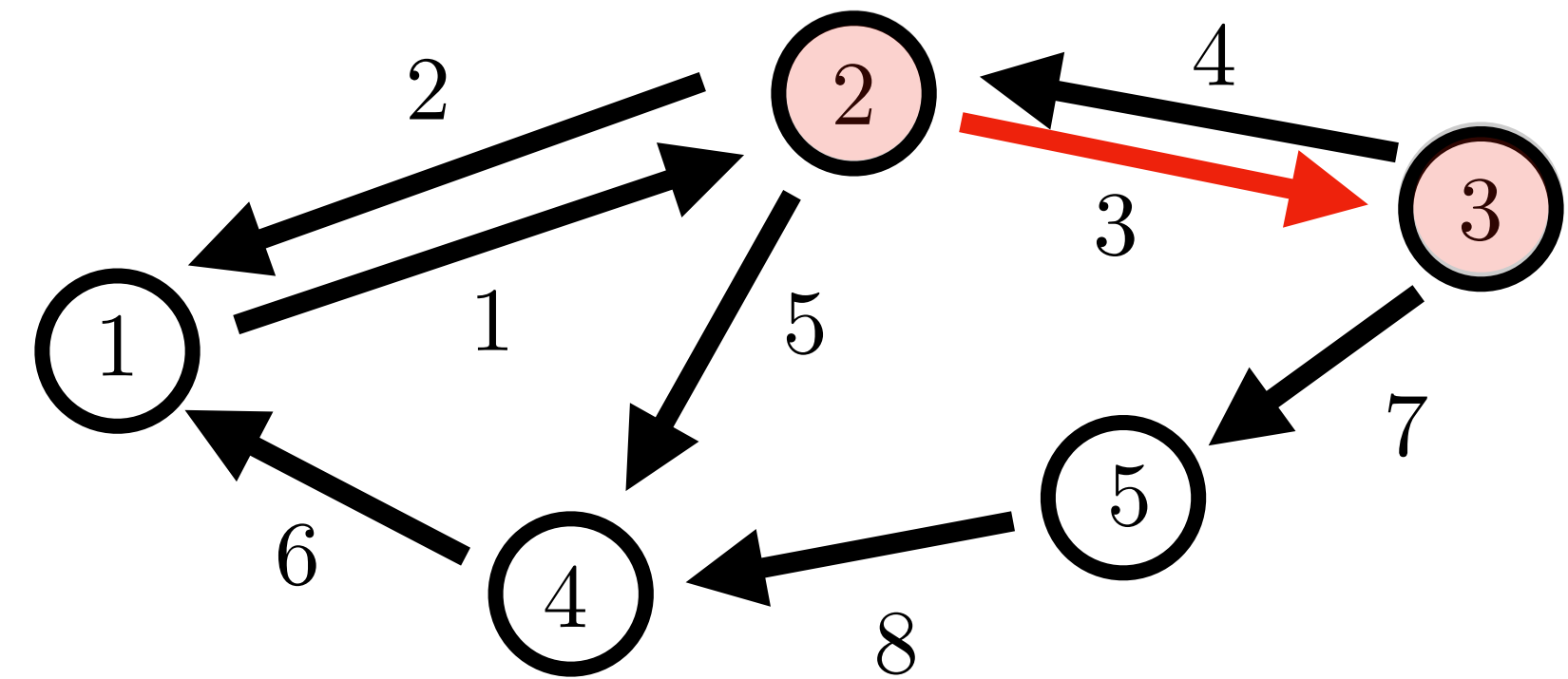
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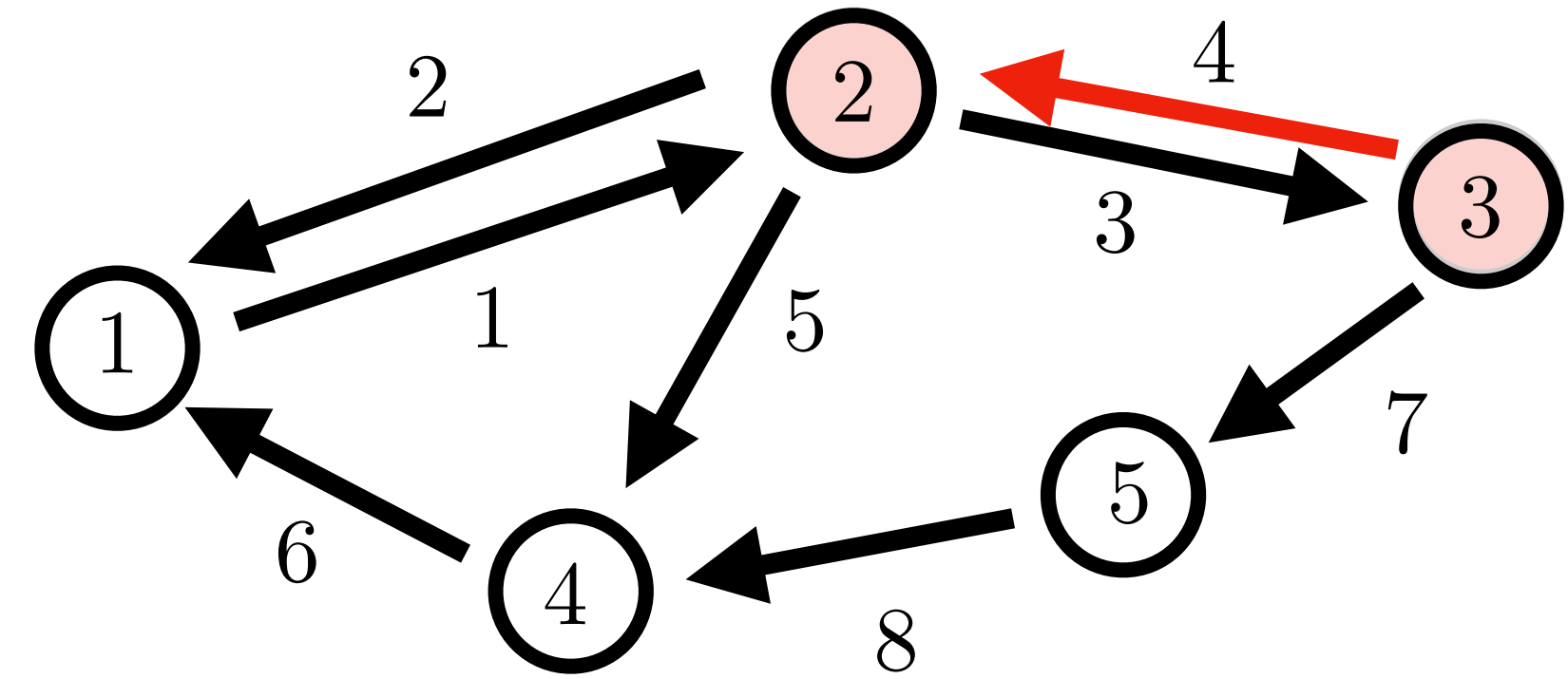
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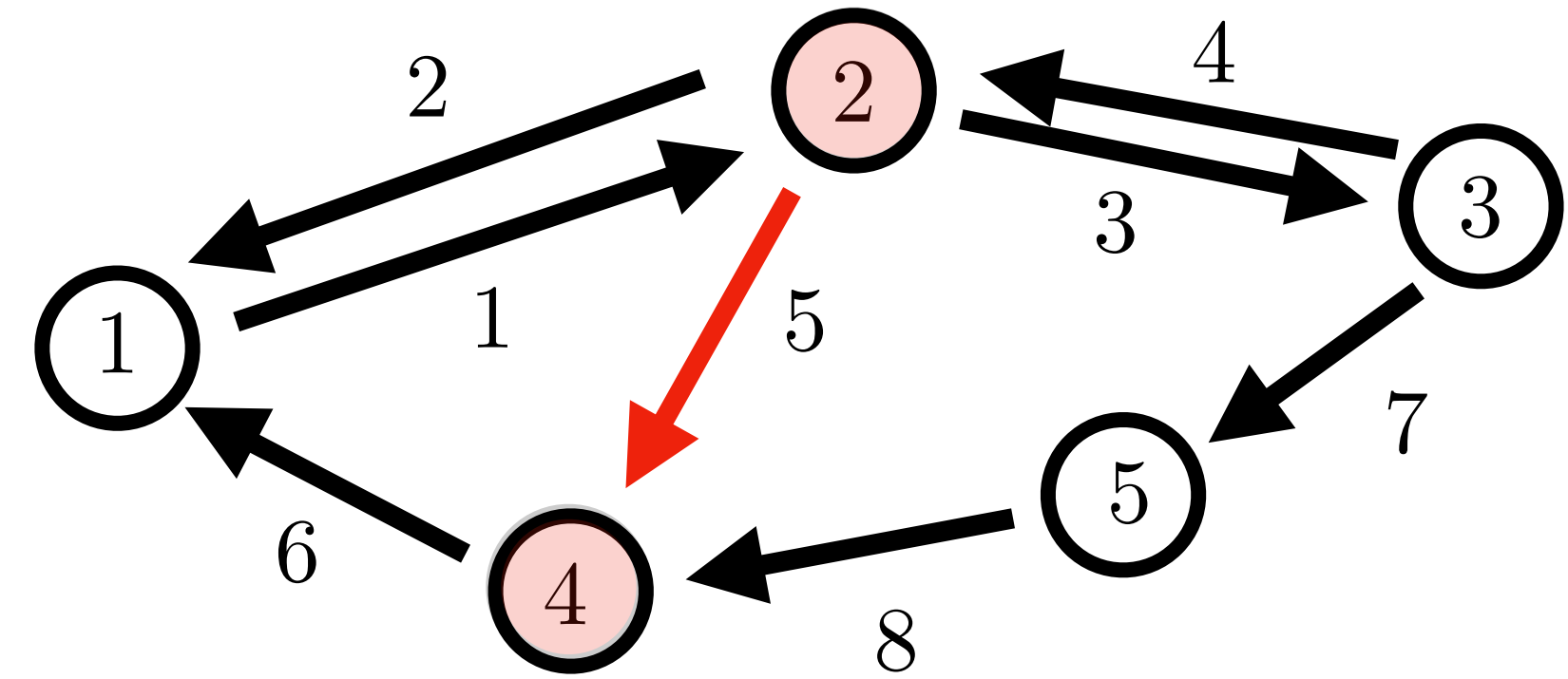
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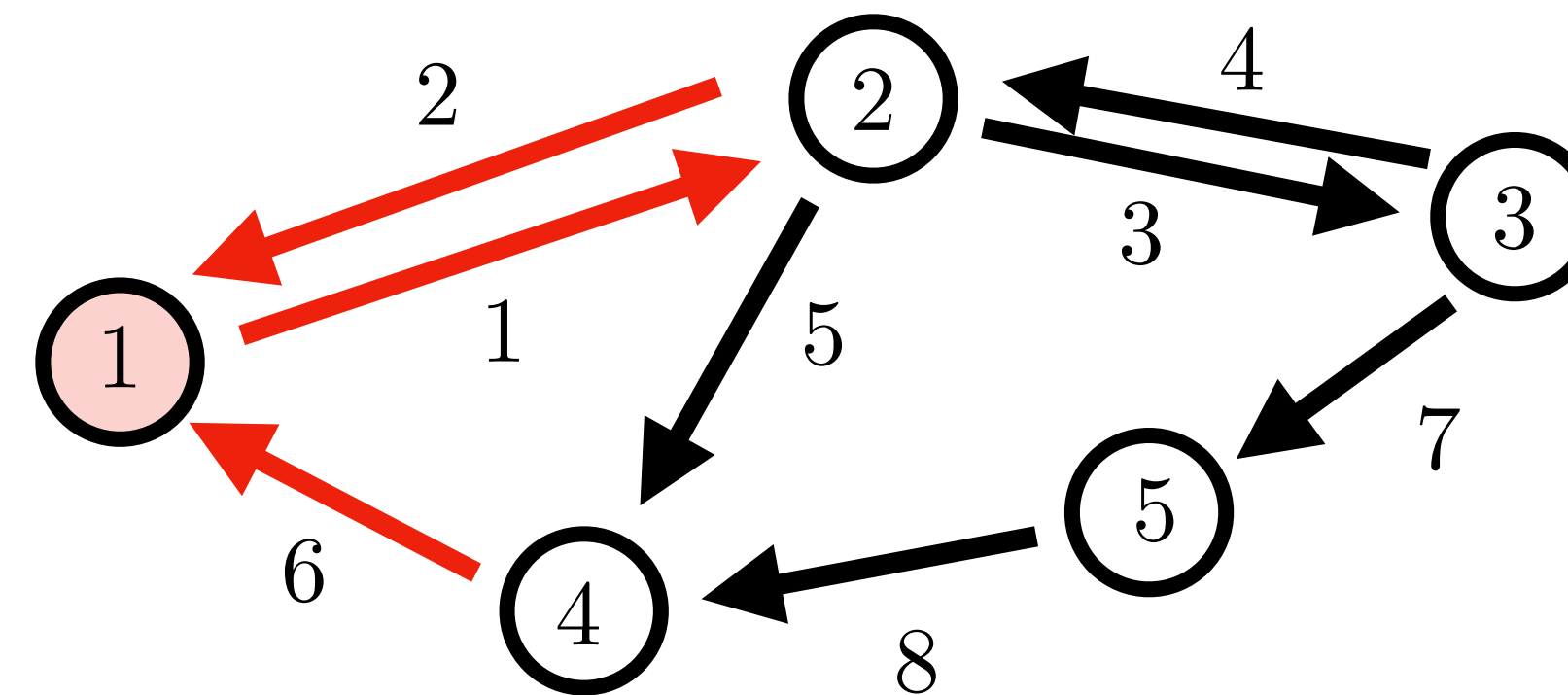
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↓

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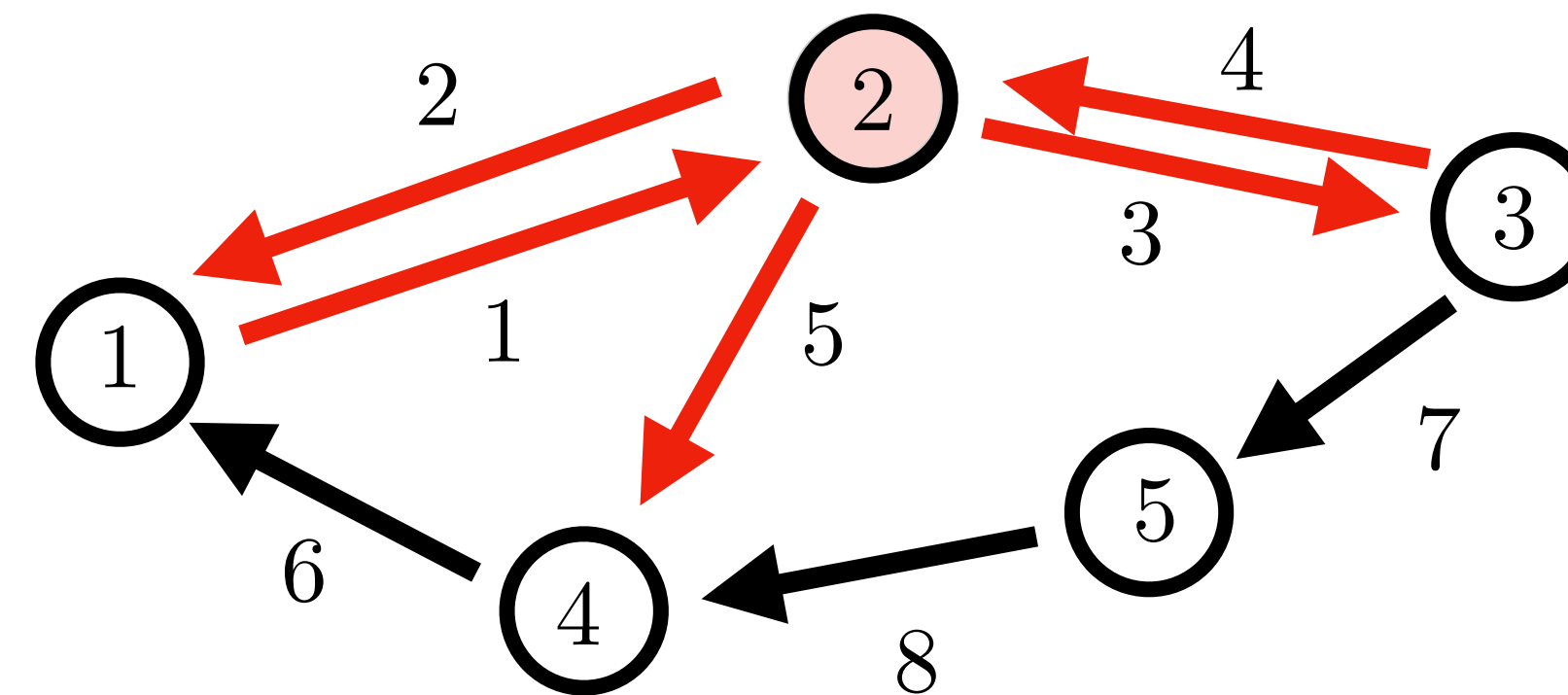
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↓

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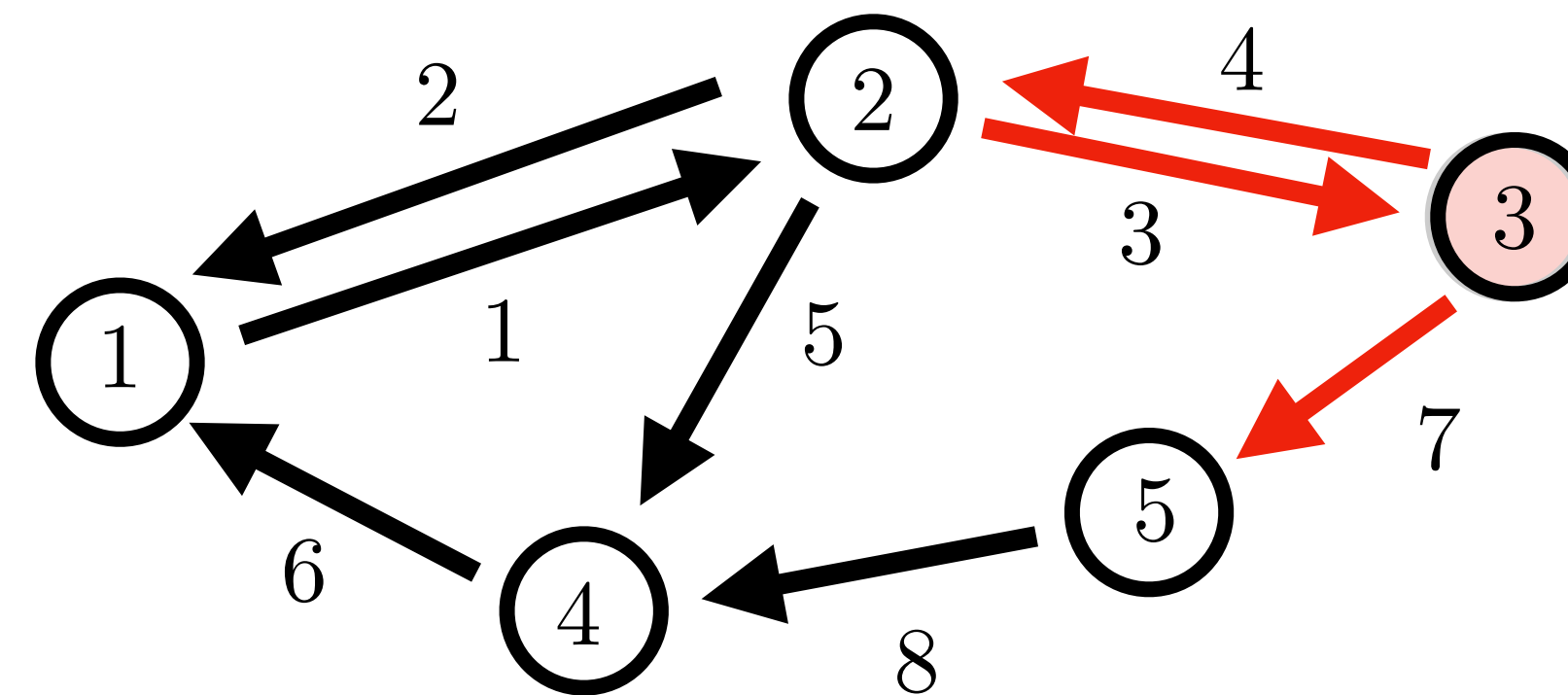
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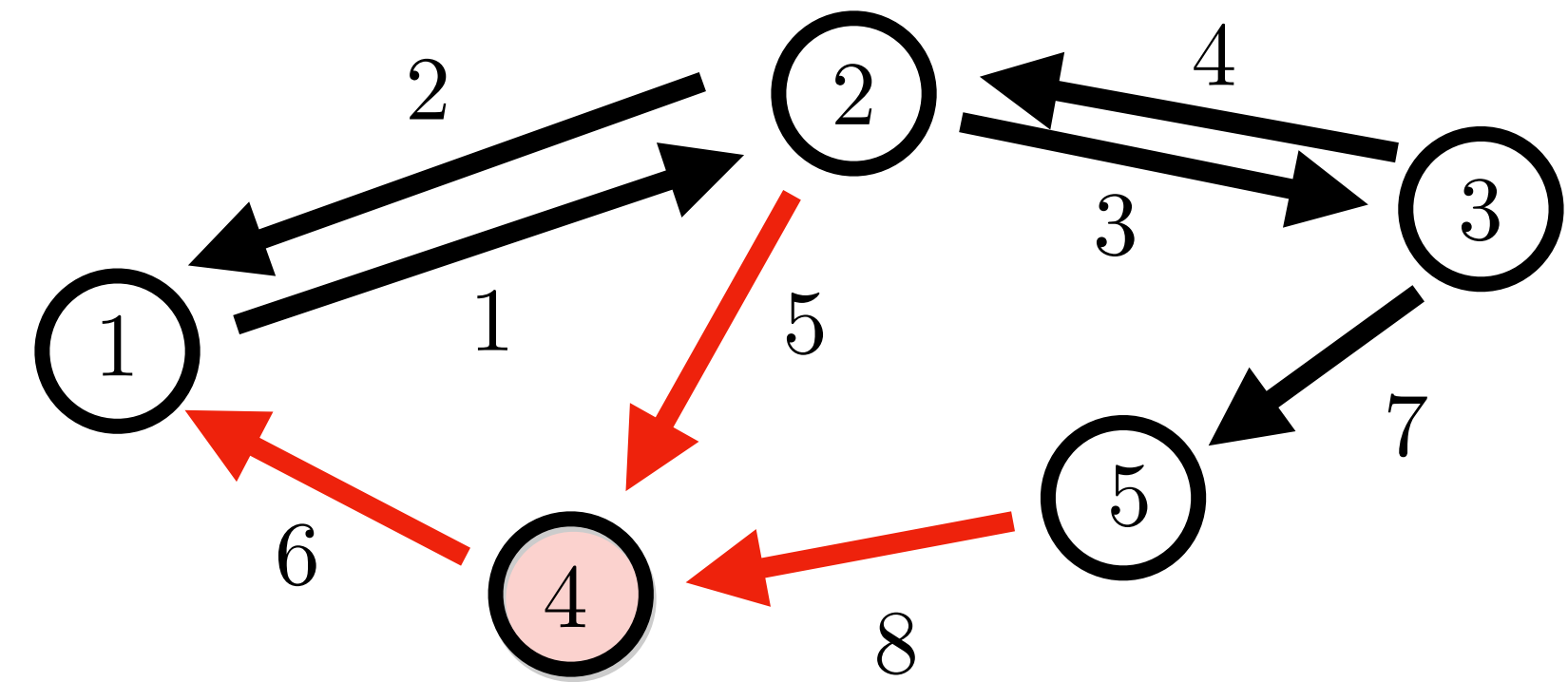
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↑  
vertices  
↓

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# Incidence Matrix - Left Nullspace

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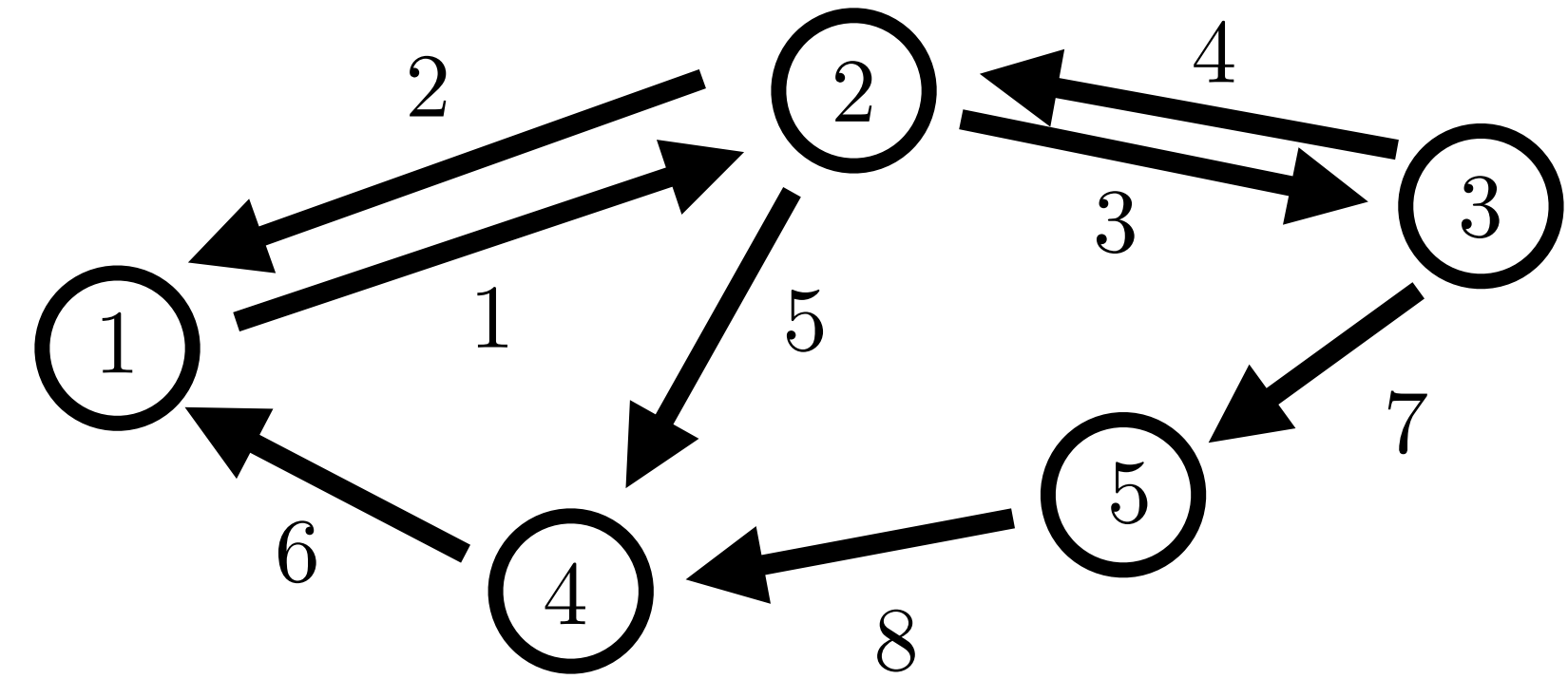
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$$[1 \ 1 \ 1 \ 1 \ 1] \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} = \mathbf{0}$$

Left  
Nullspace

$$\mathbf{1}^T D = \mathbf{0}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

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$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

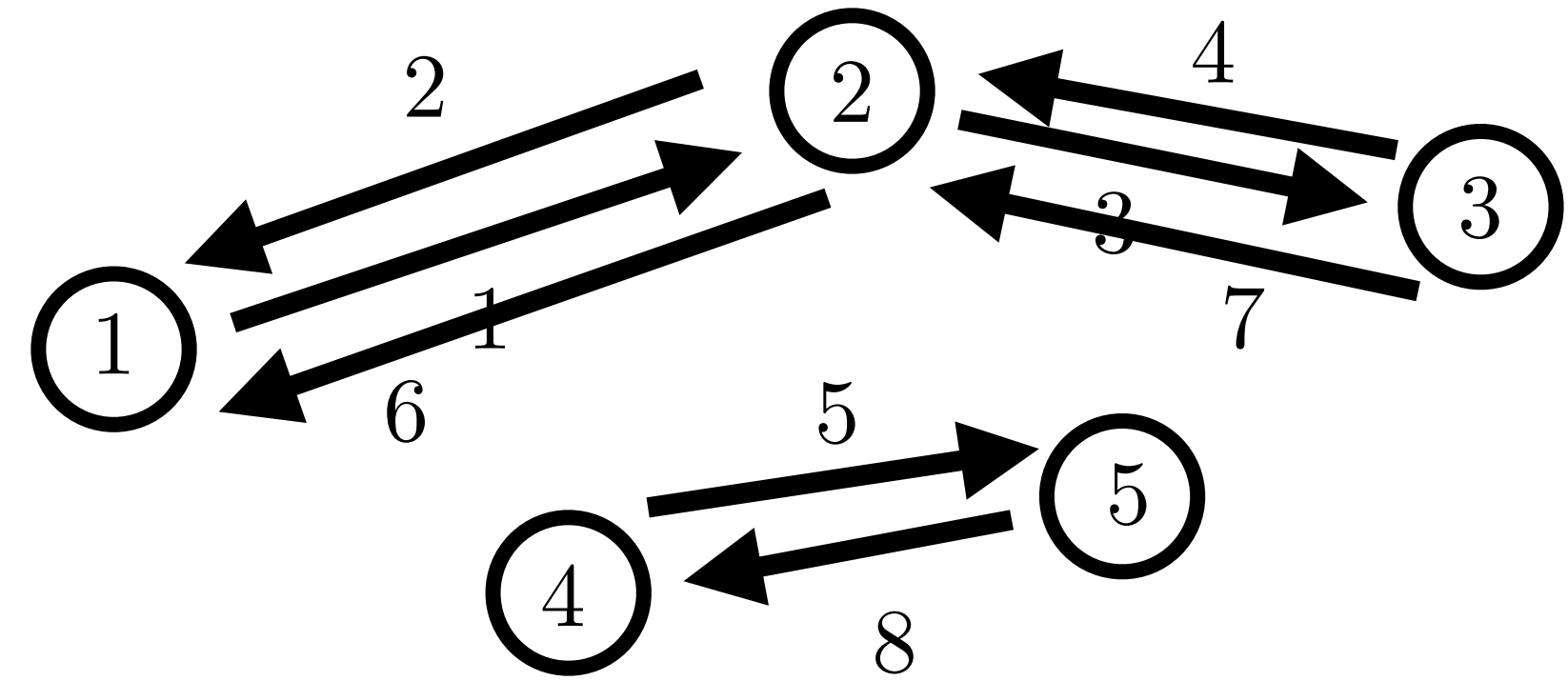
$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{if } e \text{ out of } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$[1 \ 1 \ 1 \ 1 \ 1] \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \end{bmatrix} = \mathbf{0}$$

Left  
Nullspace

$$\mathbf{1}^T D = \mathbf{0}$$



$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

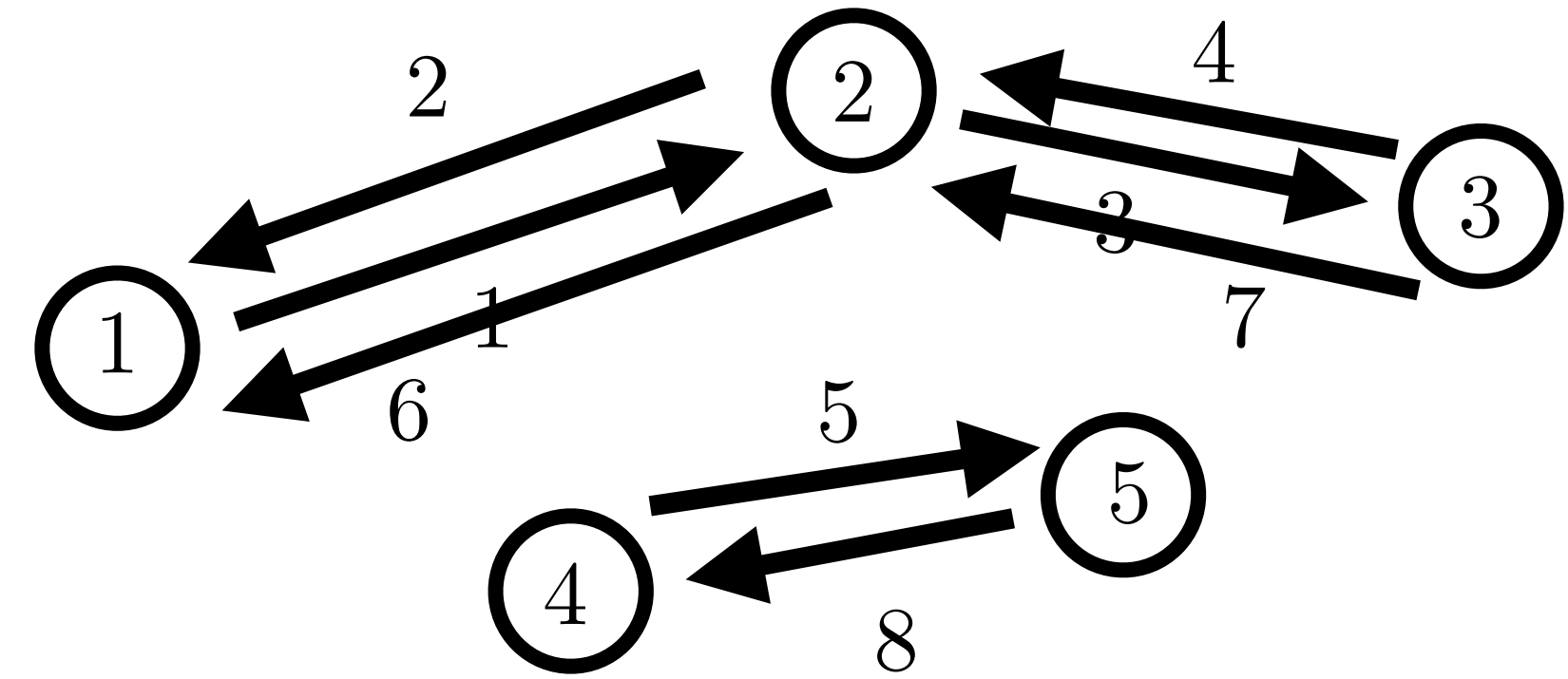
$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

# Incidence Matrix - Left Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$



**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$[D_{\text{out}}]_{ve} = \begin{cases} 1 & ; \text{if } e \text{ out of } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$[D_{\text{in}}]_{ve} = \begin{cases} 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$D_{\text{out}} = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & 0 & -1 & 1 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 \end{bmatrix} = \mathbf{0}$$

$$D_{\text{in}} = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

**Left Nullspace (General)**

$$\begin{bmatrix} \mathbf{1}^T & 0 & \dots & 0 \\ 0 & \mathbf{1}^T & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \mathbf{1}^T \end{bmatrix} \begin{bmatrix} D \end{bmatrix} = \mathbf{0}$$

dim left nullspace = num connected components



# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows  $\rightarrow$

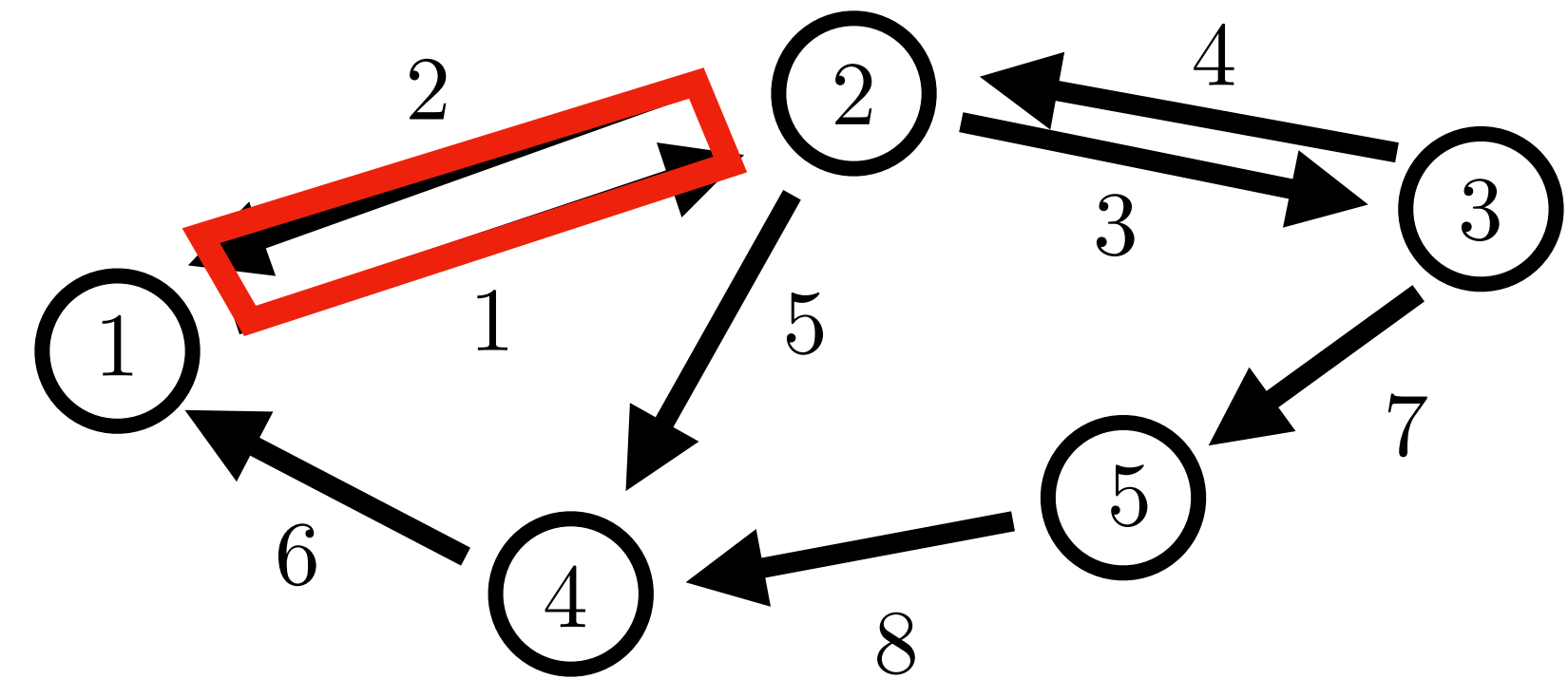
ea. equation:  
Conservation of flow at ea. node

Right Nullspace

$$DC = 0$$

Cycle space  $\mathcal{C}$   $\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$

Ex:  $8 - 5 + 1 = 4$



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{if } e \text{ flows with cycle } c \\ -1 & ; \text{if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates if cycle goes with or against edge direction

Columns = basis for  $\mathcal{C}$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

ea. equation: Conservation of flow at ea. node

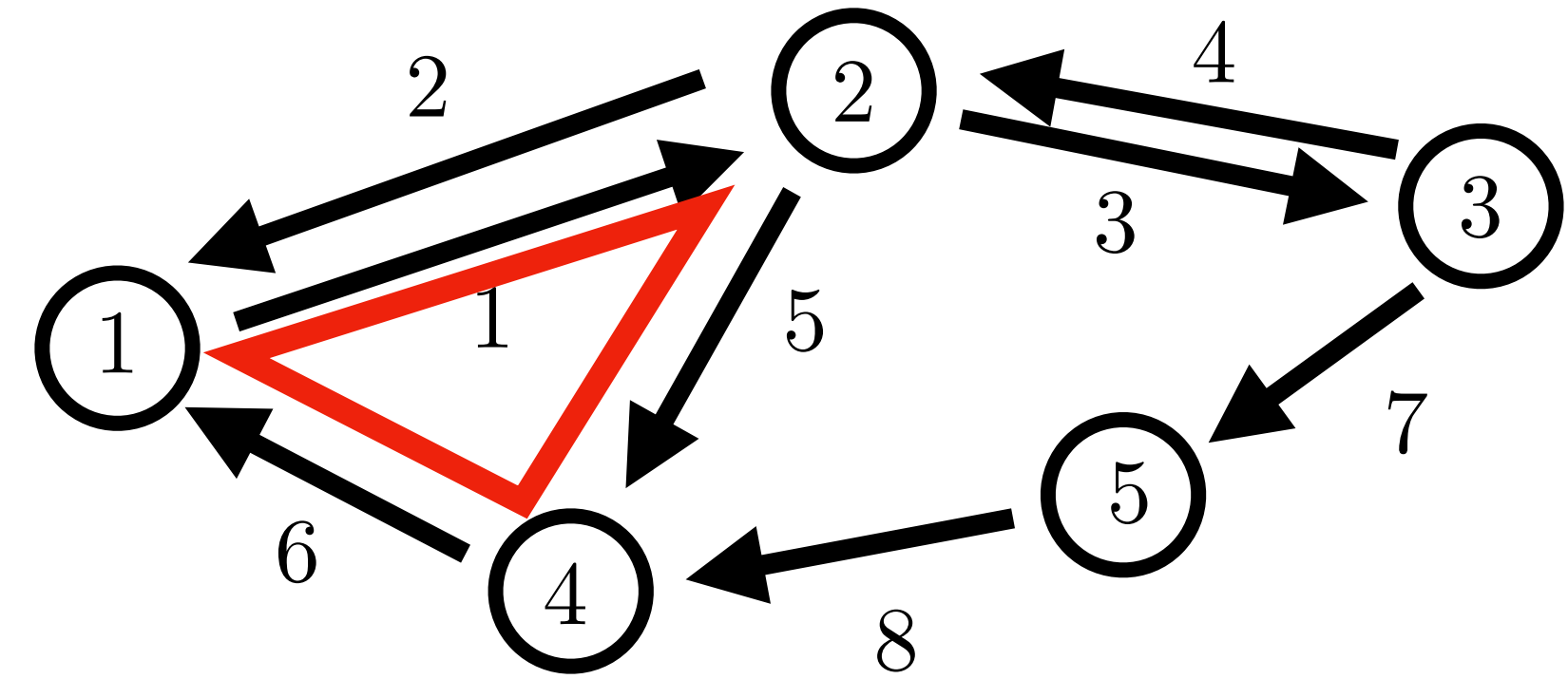
edge mass flows  $\rightarrow$

Right Nullspace

$$DC = 0$$

Cycle space  $\mathcal{C}$   $\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$

Ex:  $8 - 5 + 1 = 4$



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{if } e \text{ flows with cycle } c \\ -1 & ; \text{if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates if cycle goes with or against edge direction

Columns = basis for  $\mathcal{C}$

# Incidence Matrix - Right Nullspace

Graph:

Vertices

$$v \in \mathcal{V}$$

$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

Edges

$$e \in \mathcal{E}$$

$$e = (v, v')$$

Incidence Matrix:

$$D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$$

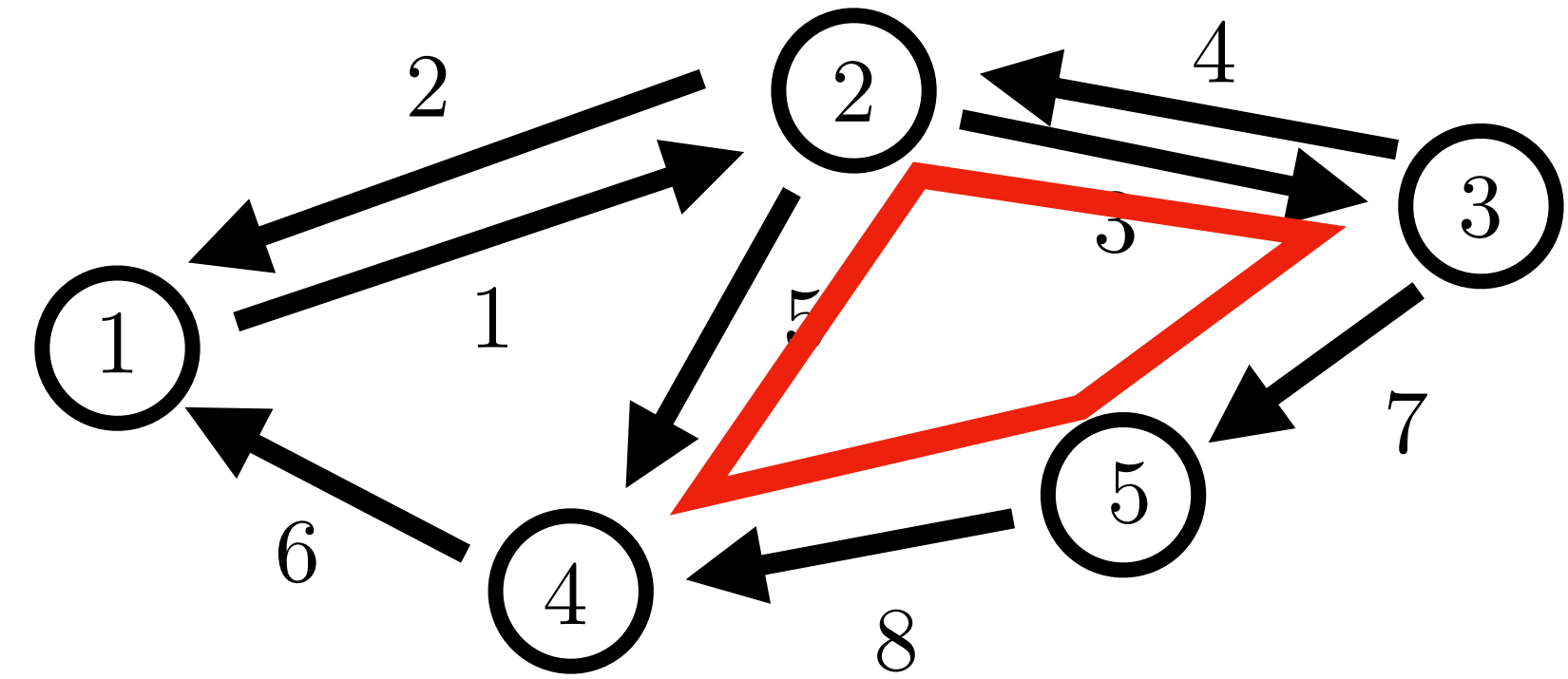
$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows  $\rightarrow$

ea. equation:

Conservation  
of flow  
at ea. node



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{if } e \text{ flows with cycle } c \\ -1 & ; \text{if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

Right  
Nullspace

$$DC = 0$$

Cycle space  $\mathcal{C}$

$$\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$$

$$\text{Ex: } 8 - 5 + 1 = 4$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

← Sign indicates  
if cycle goes  
with or against  
edge direction

Columns =  
basis for  $\mathcal{C}$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows  $\rightarrow$

ea. equation:  
Conservation of flow at ea. node

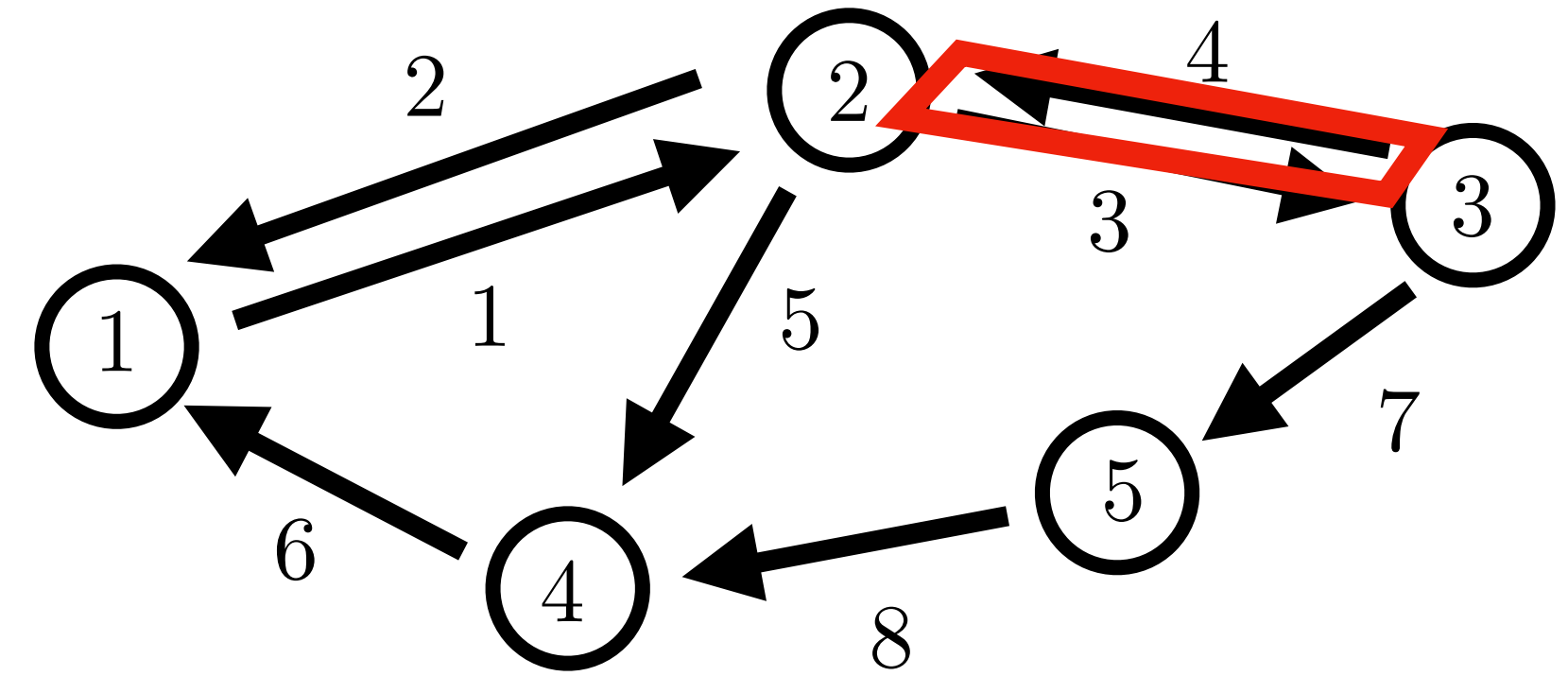
Right Nullspace

$$DC = 0$$

Cycle space  $\mathcal{C}$

$$\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$$

Ex:  $8 - 5 + 1 = 4$



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{if } e \text{ flows with cycle } c \\ -1 & ; \text{if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates if cycle goes with or against edge direction

Columns = basis for  $\mathcal{C}$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

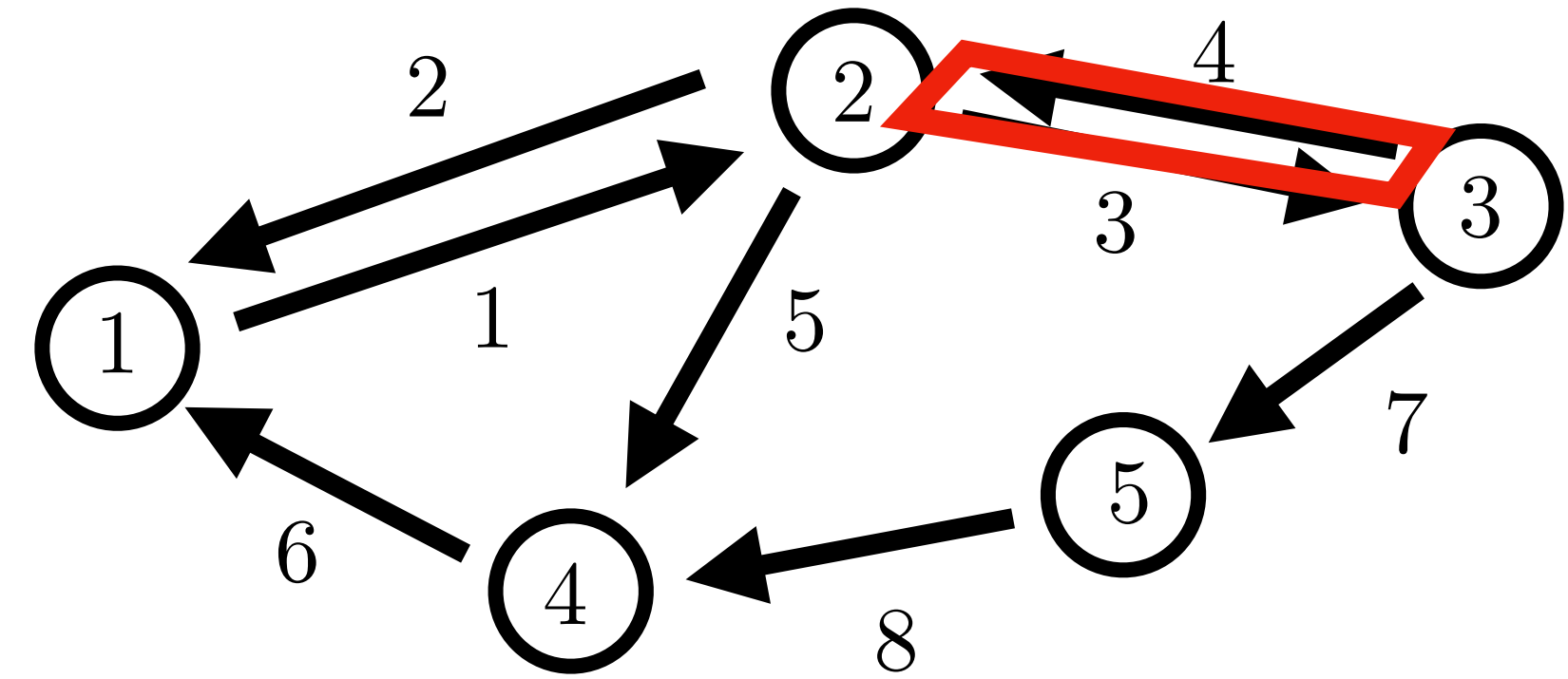
**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

edge mass flows  $\rightarrow$

ea. equation:  
Conservation  
of flow  
at ea. node



Cycle indicator (basis) matrix:

$$[C]_{ec} = \begin{cases} 1 & ; \text{if } e \text{ flows with cycle } c \\ -1 & ; \text{if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

Subspace Constraint  $Dx = 0 \Rightarrow x = Cz$

Cycle space  $\mathcal{C}$   $\dim \mathcal{C} = |\mathcal{E}| - |\mathcal{V}| + 1$

Ex:  $8 - 5 + 1 = 4$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

← Sign indicates  
if cycle goes  
with or against  
edge direction

Columns =  
basis for  $\mathcal{C}$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

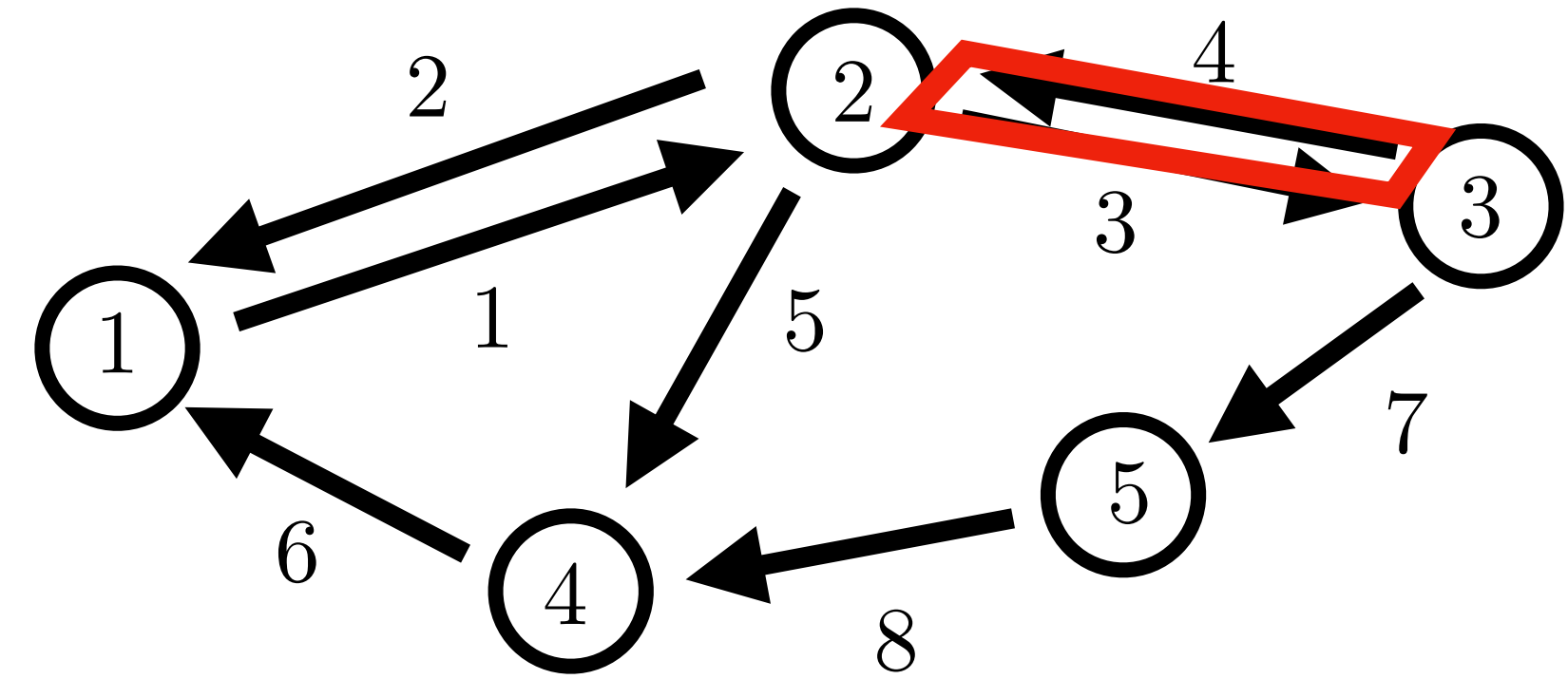
**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 1 & 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & -1 & 1 & -1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node



**Cycle indicator (basis) matrix:**

$$[C]_{ec} = \begin{cases} 1 & ; \text{if } e \text{ flows with cycle } c \\ -1 & ; \text{if } e \text{ flows against cycle } c \\ 0 & ; e \text{ not in cycle } c \end{cases}$$

**Affine Constraint**

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

**Min Norm Solution**

$$\bar{x} = D^T (DD^T)^\dagger S$$

$$C = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & -1 \\ 0 & 1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Sign indicates if cycle goes with or against edge direction

Columns = basis for  $\mathcal{C}$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$\left[ D \right]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

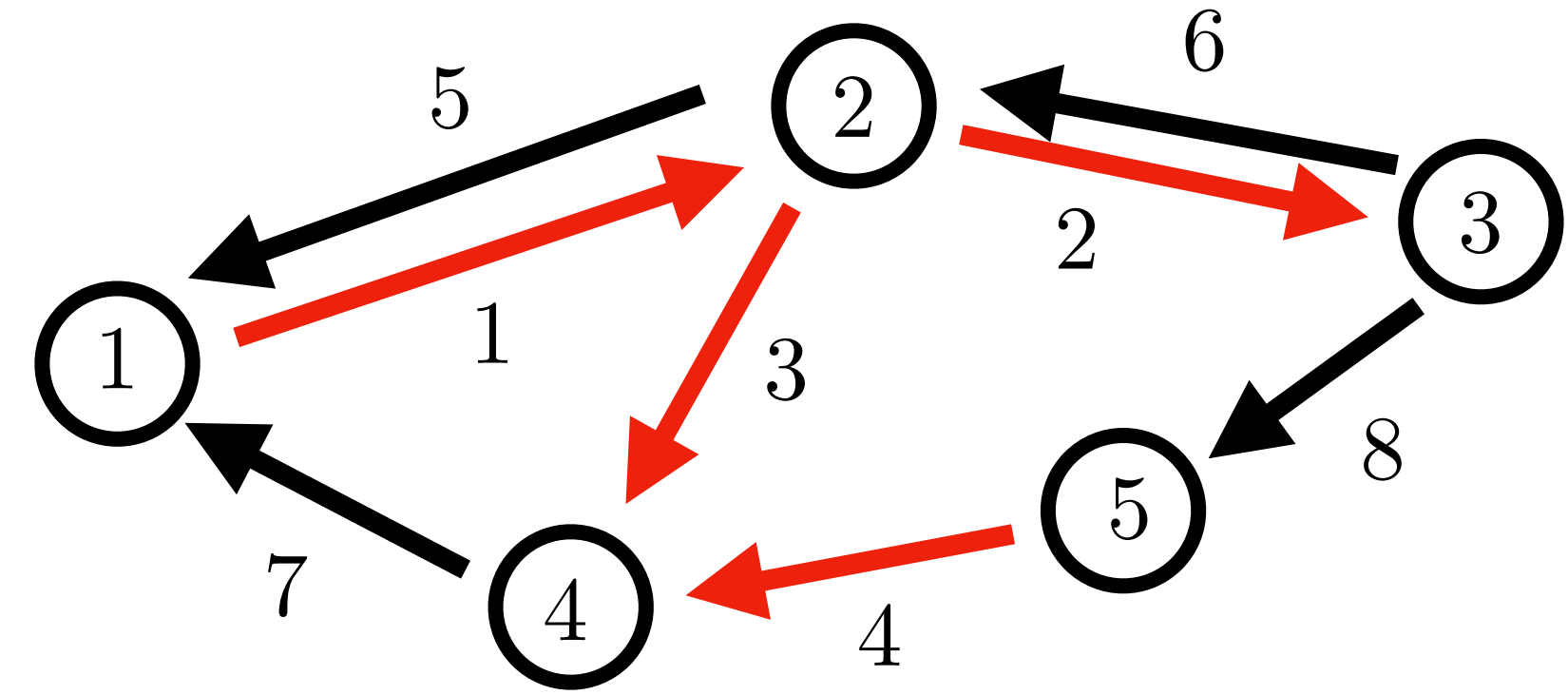
Affine Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific Solution      Cyclic Flow

Min Norm Solution

$$\bar{x} = D^T (DD^T)^\dagger S$$



## Spanning Tree Construction:

$$D = [D' \quad D''] = [D' \quad D'M] = D'[I \quad M]$$

$$|\mathcal{V}| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$|\mathcal{V}| - 1$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$\left[ D \right]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

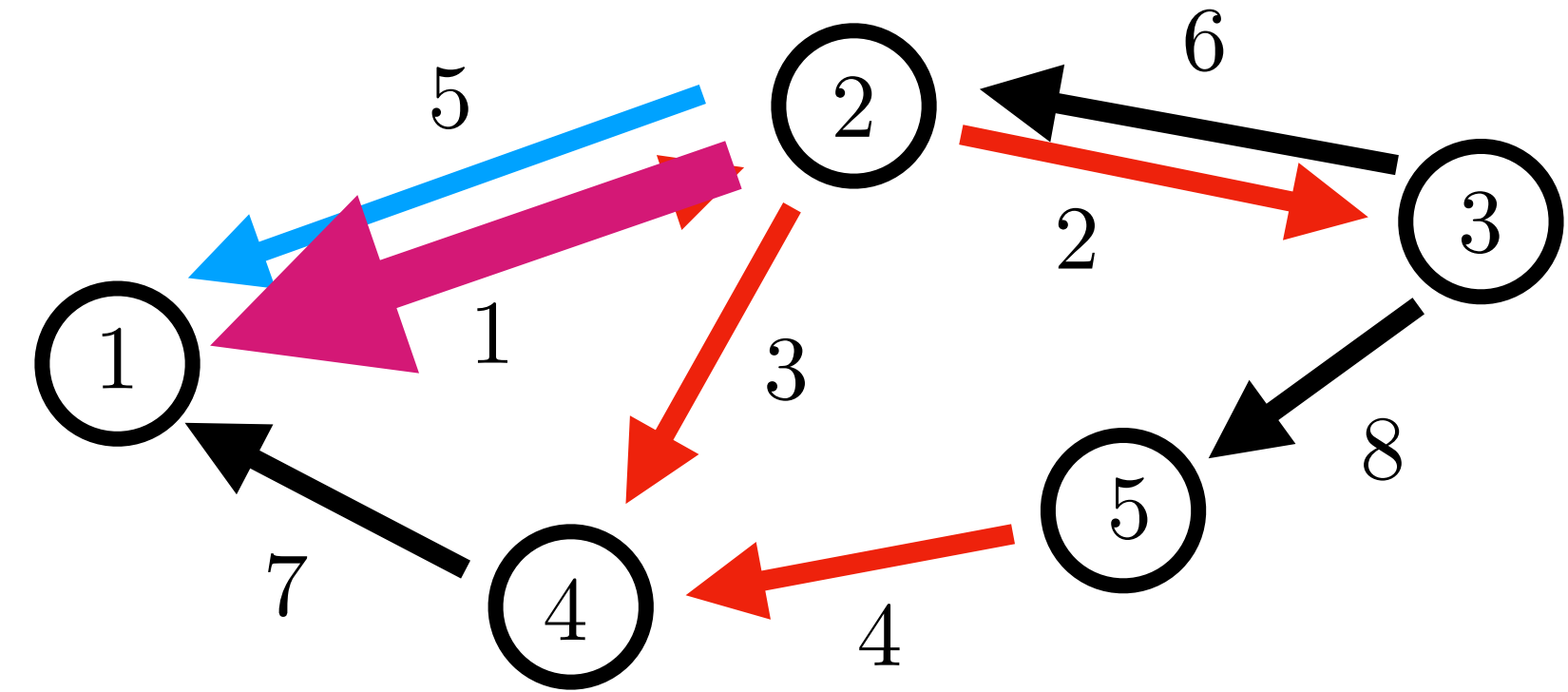
Affine Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Min Norm Solution

$$\bar{x} = D^T (DD^T)^\dagger S$$

Specific Solution      Cyclic Flow



## Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$|\mathcal{V}| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$|\mathcal{V}| - 1$

$$D'M = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$



# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$[D]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

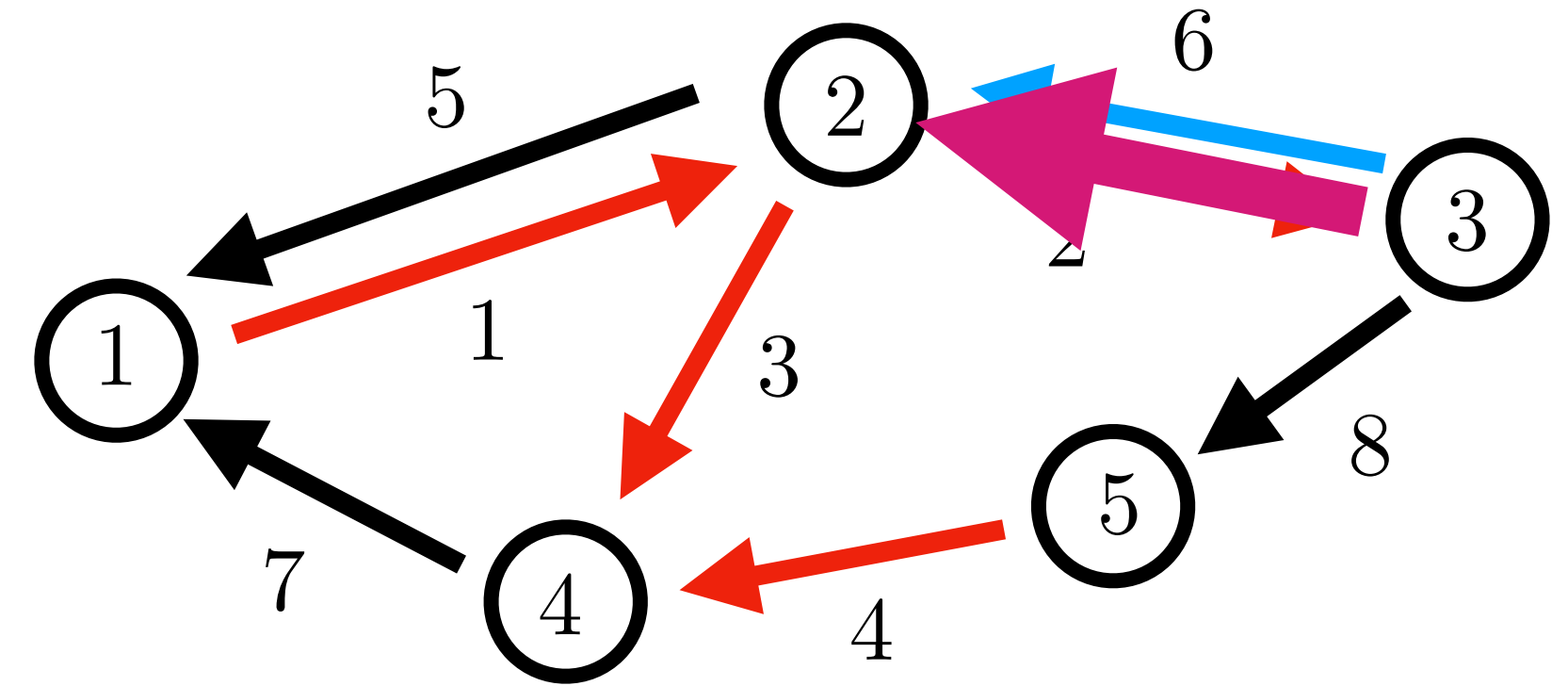
**Affine Constraint**

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

**Min Norm Solution**

$$\bar{x} = D^T (DD^T)^\dagger S$$

Specific Solution      Cyclic Flow



## Spanning Tree Construction:

$$D = [D' \quad D''] = [D' \quad D'M] = D'[I \quad M]$$

$$|\mathcal{V}| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$|\mathcal{V}| - 1$

$$D'M = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$\begin{bmatrix} D \end{bmatrix}_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

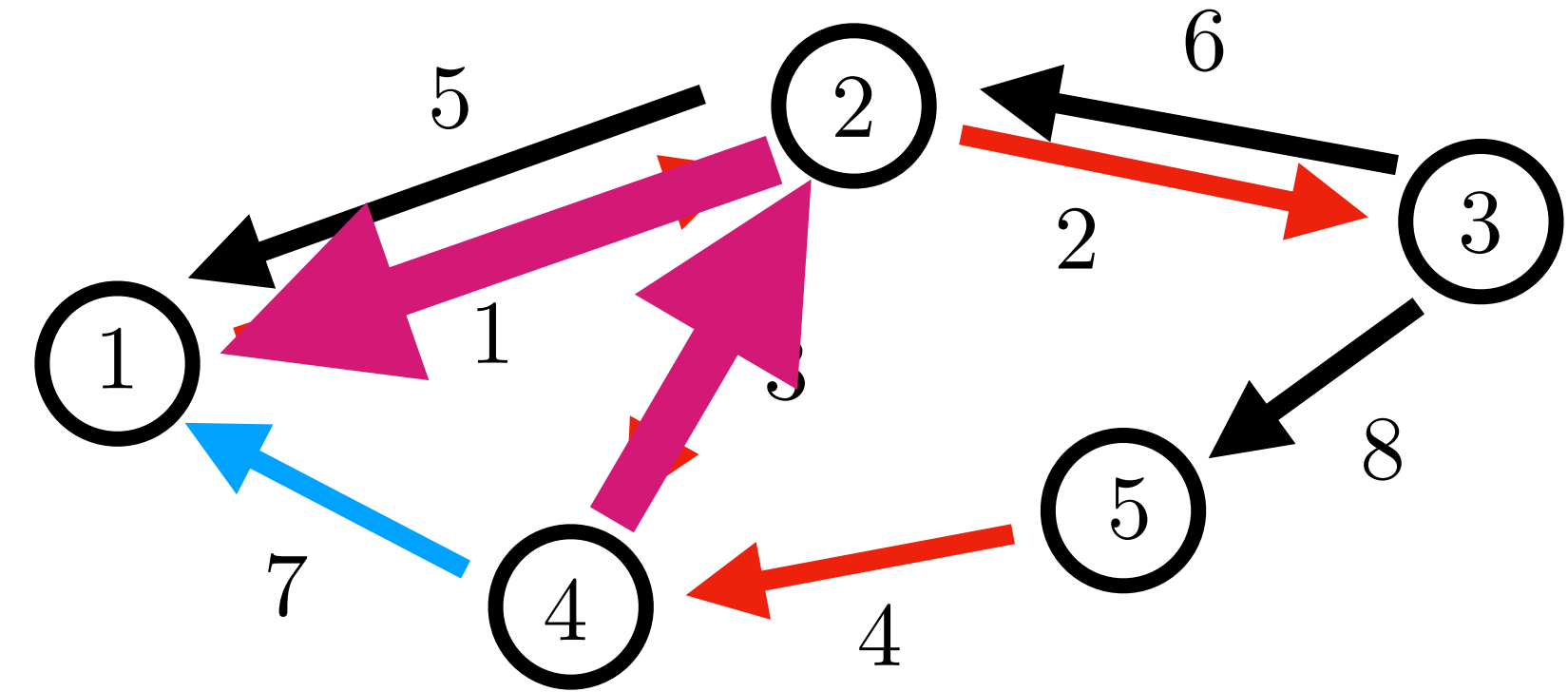
**Affine Constraint**

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

**Min Norm Solution**

$$\bar{x} = D^T (DD^T)^\dagger S$$

Specific Solution      Cyclic Flow



## Spanning Tree Construction:

$$D = [D' \quad D''] = [D' \quad D'M] = D'[I \quad M]$$

$$|\mathcal{V}| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$|\mathcal{V}| - 1$

$$D'M = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$\left[ D \right]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

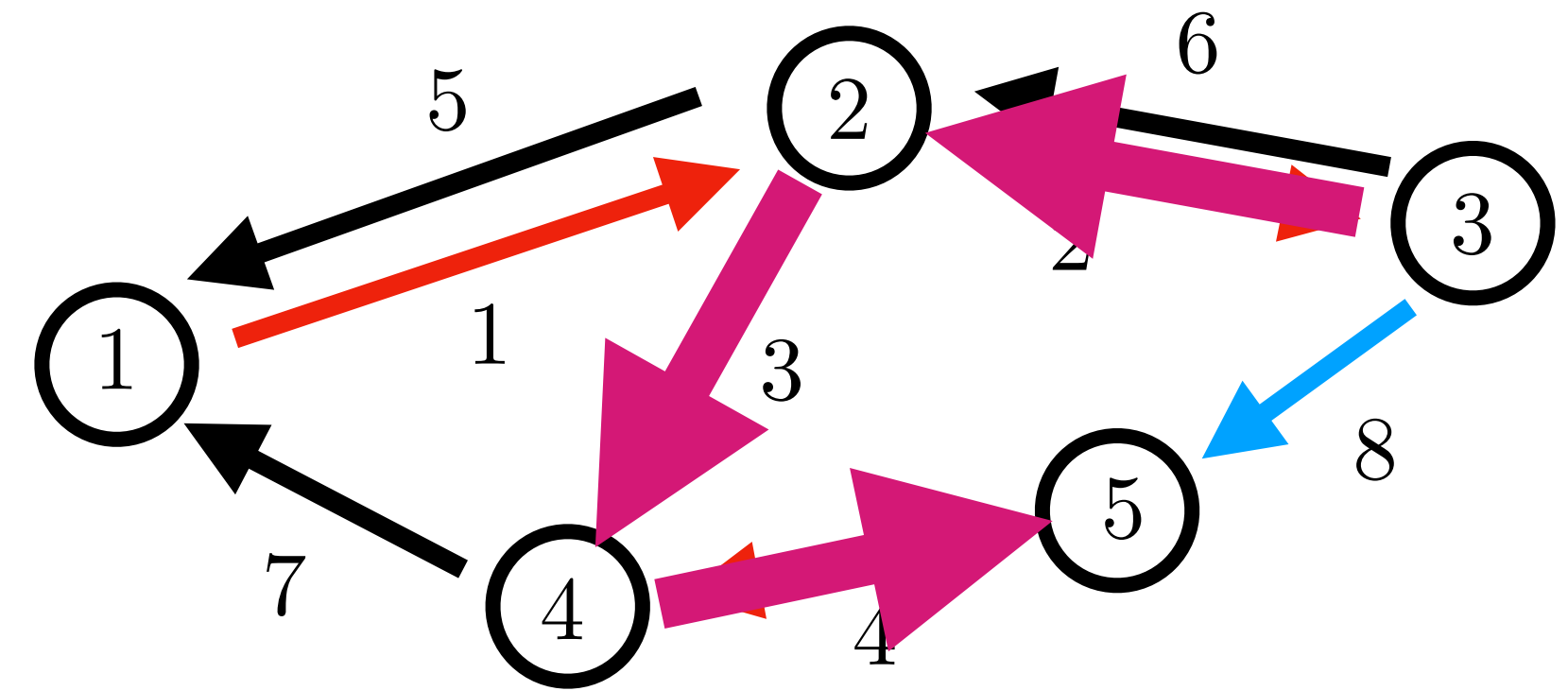
Affine Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Min Norm Solution

$$\bar{x} = D^T (DD^T)^\dagger S$$

Specific Solution      Cyclic Flow



## Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

$$|\mathcal{V}| \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$|\mathcal{V}| - 1$

$$D'M = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

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$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

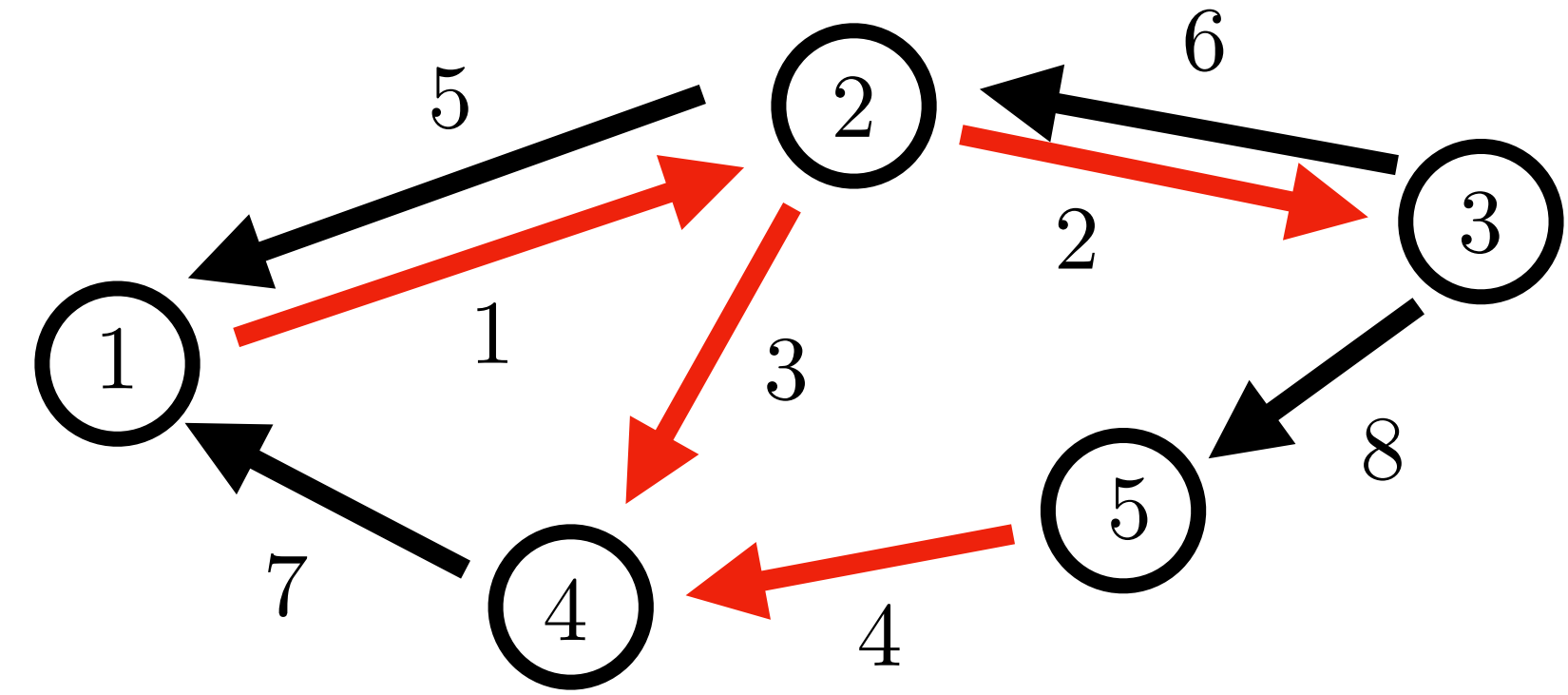
Affine Constraint

$$Dx = S \Rightarrow x = \bar{x} + Cz$$

Specific Solution      Cyclic Flow

Min Norm Solution

$$\bar{x} = D^T (DD^T)^\dagger S$$



## Spanning Tree Construction:

$$D = [D' \quad D''] = [D' \quad D'M] = D'[I \quad M]$$

$$D = \begin{bmatrix} \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} & \begin{bmatrix} -1 & 0 & 0 & 0 \\ 1 & -1 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} & \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \end{bmatrix}$$

# Incidence Matrix - Right Nullspace

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

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**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$\left[ D \right]_{ve} = \begin{cases} -1 & ; \text{if } e \text{ out of } v \\ 1 & ; \text{if } e \text{ into } v \\ 0 & ; \text{otherwise} \end{cases}$$

$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

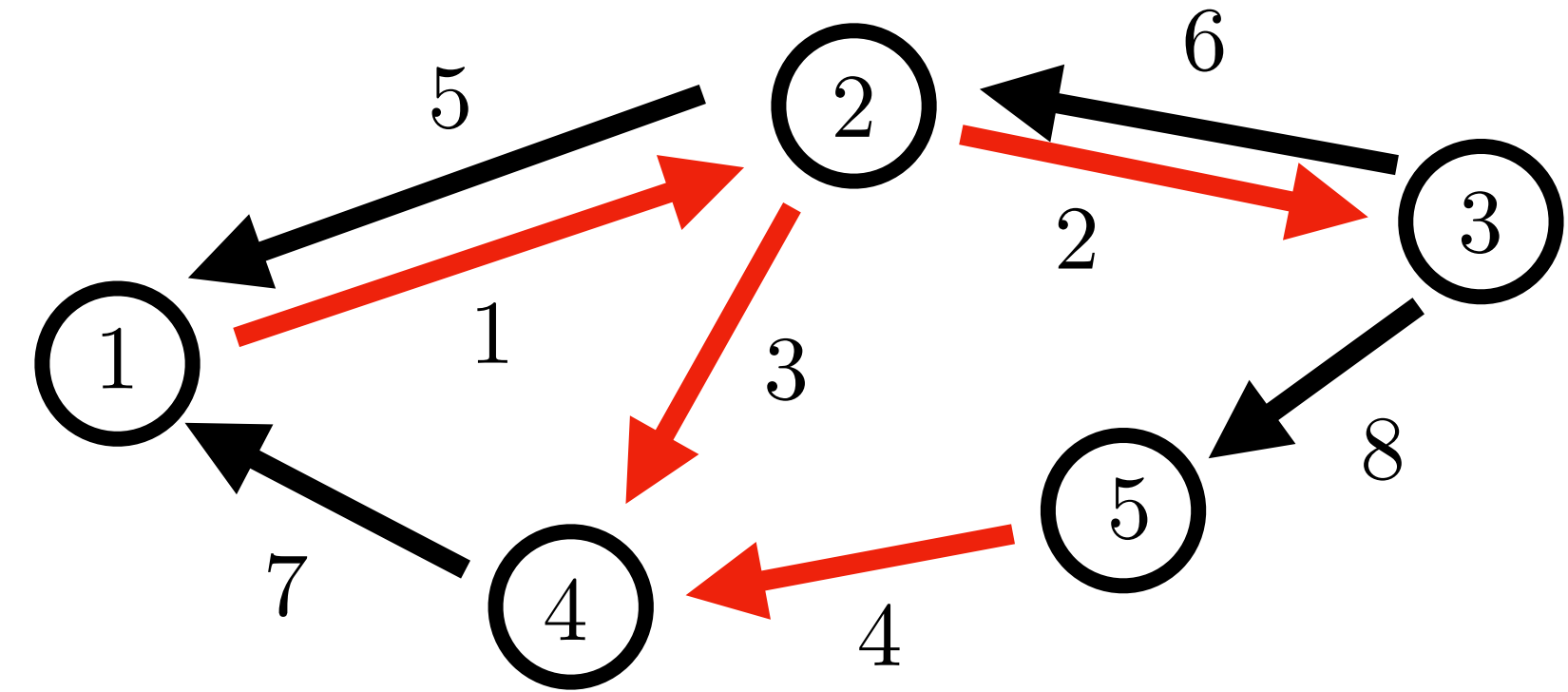
Affine Constraint

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Min Norm Solution

$$\bar{x} = D^T (DD^T)^\dagger S$$

Specific Solution      Cyclic Flow



## Spanning Tree Construction:

$$D = [D' \ D''] = [D' \ D'M] = D'[I \ M]$$

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**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

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$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

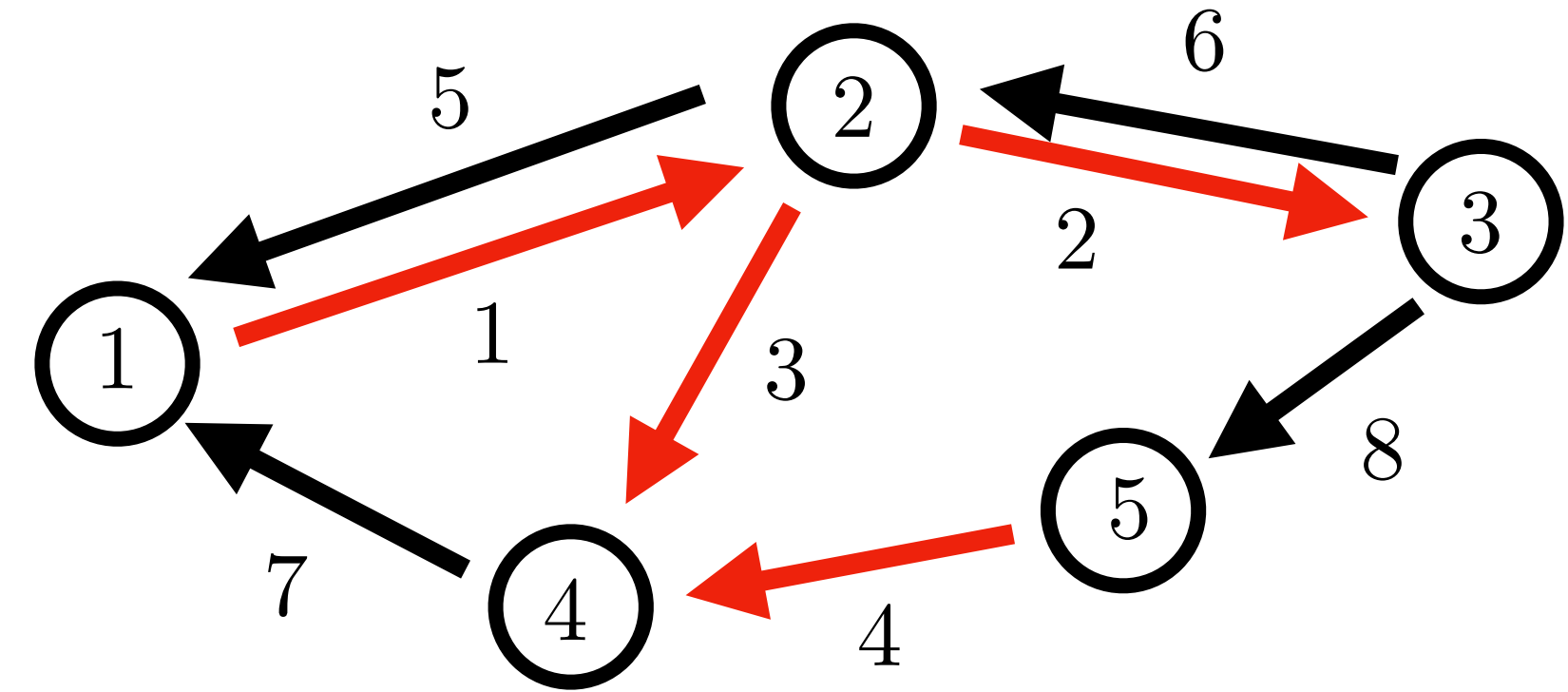
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Specific Solution      Cyclic Flow



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$$C = \begin{bmatrix} M \\ -I \end{bmatrix} = \begin{bmatrix} -1 & 0 & -1 & 0 \\ 0 & -1 & 0 & -1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & -1 \\ -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

$$DC = [D' \ D''] \begin{bmatrix} M \\ -I \end{bmatrix} = D'M - D'' = 0$$

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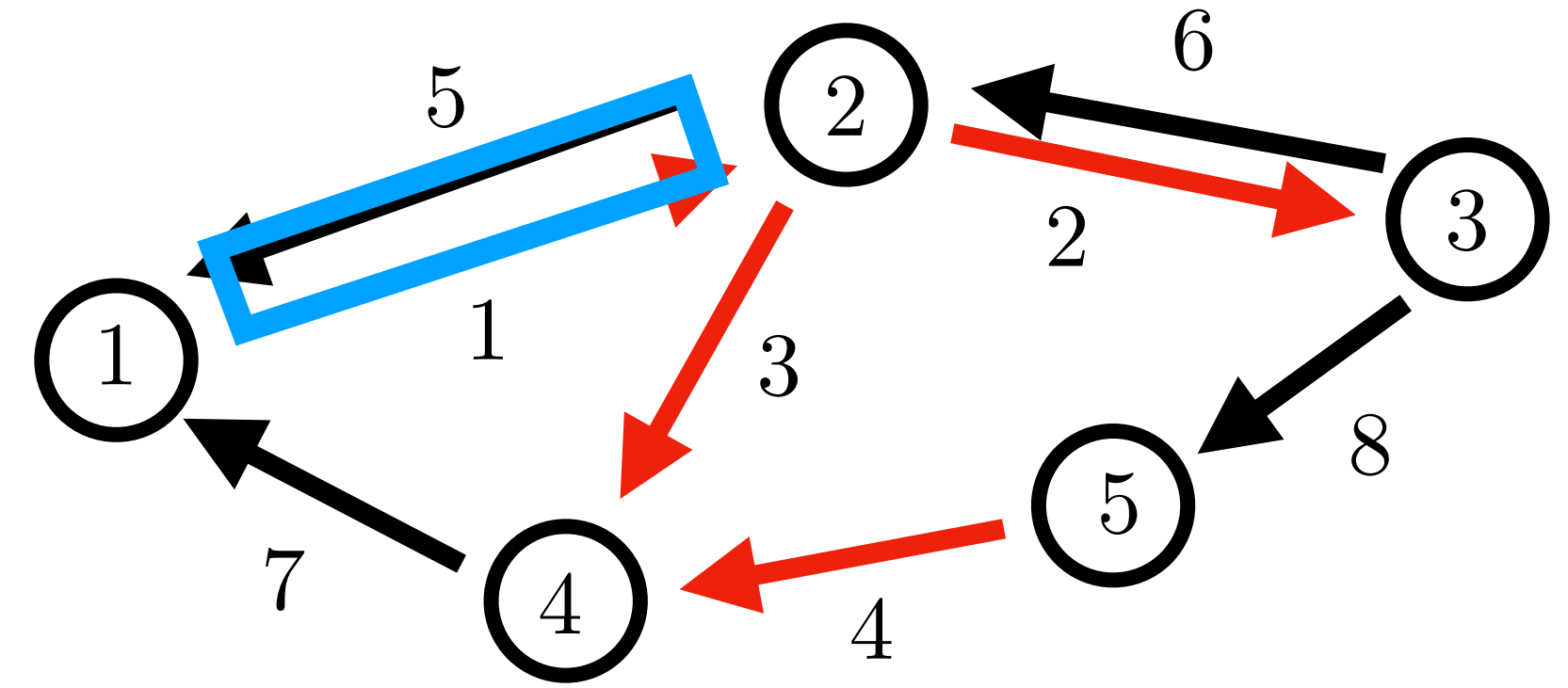
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flow source at ea. node

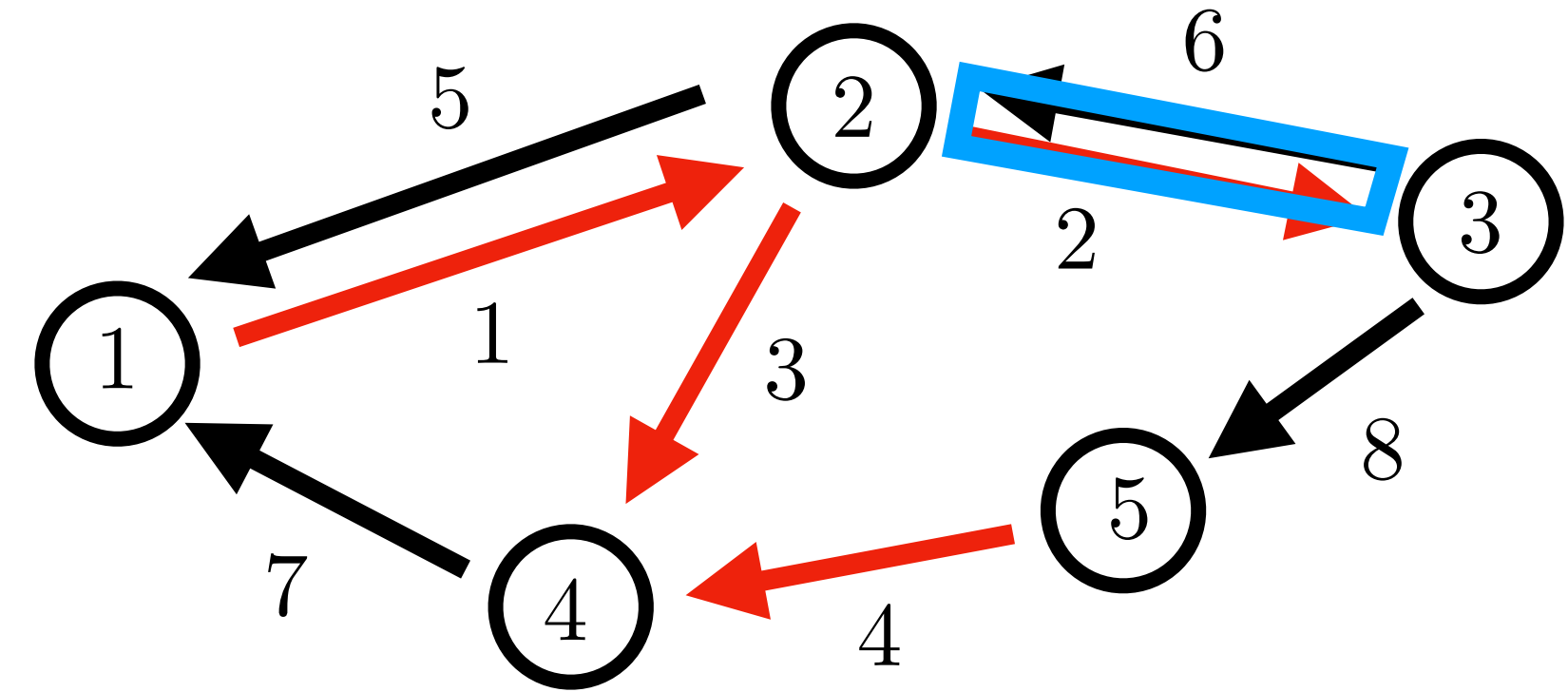
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flow source at ea. node

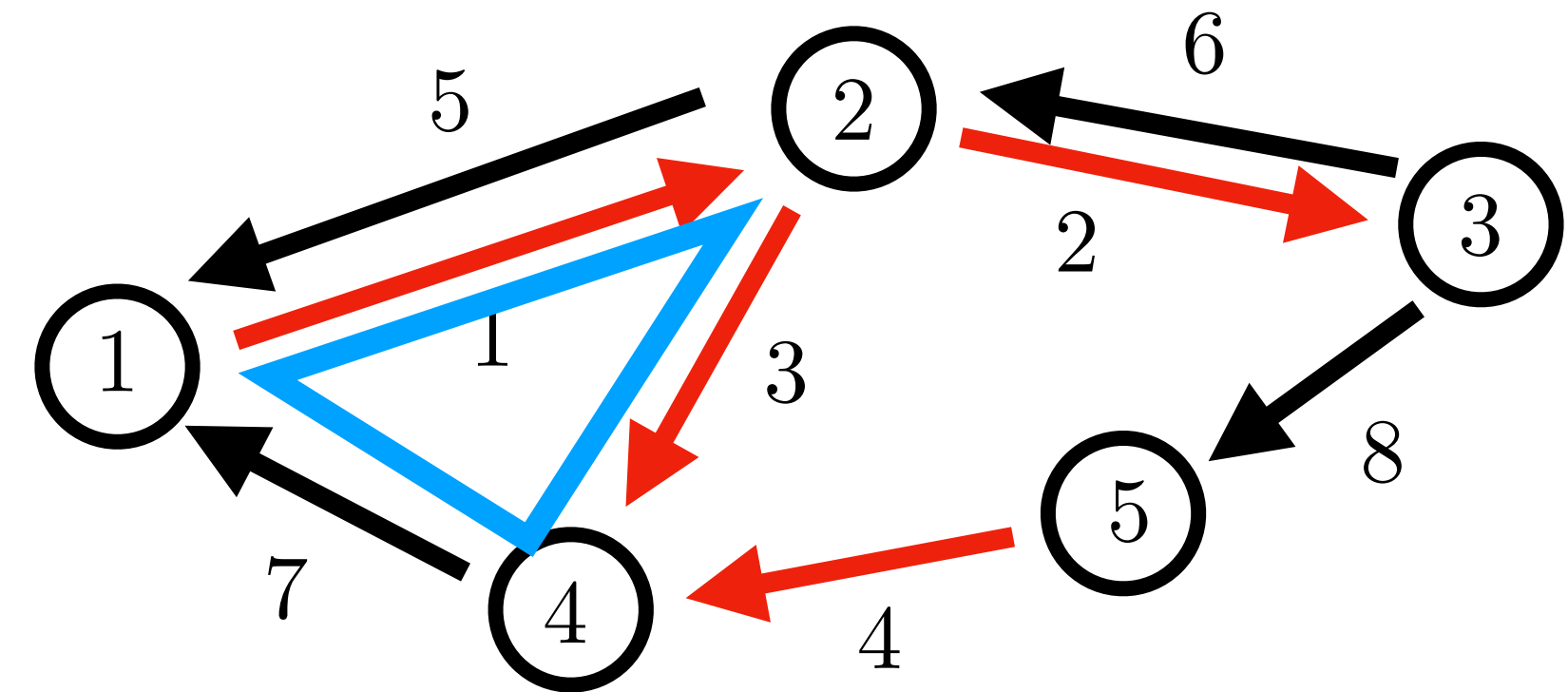
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$$\begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix} = \begin{bmatrix} S_1 \\ S_2 \\ S_3 \\ S_4 \\ S_5 \end{bmatrix}$$

edge mass flows  $\rightarrow$

flow source at ea. node

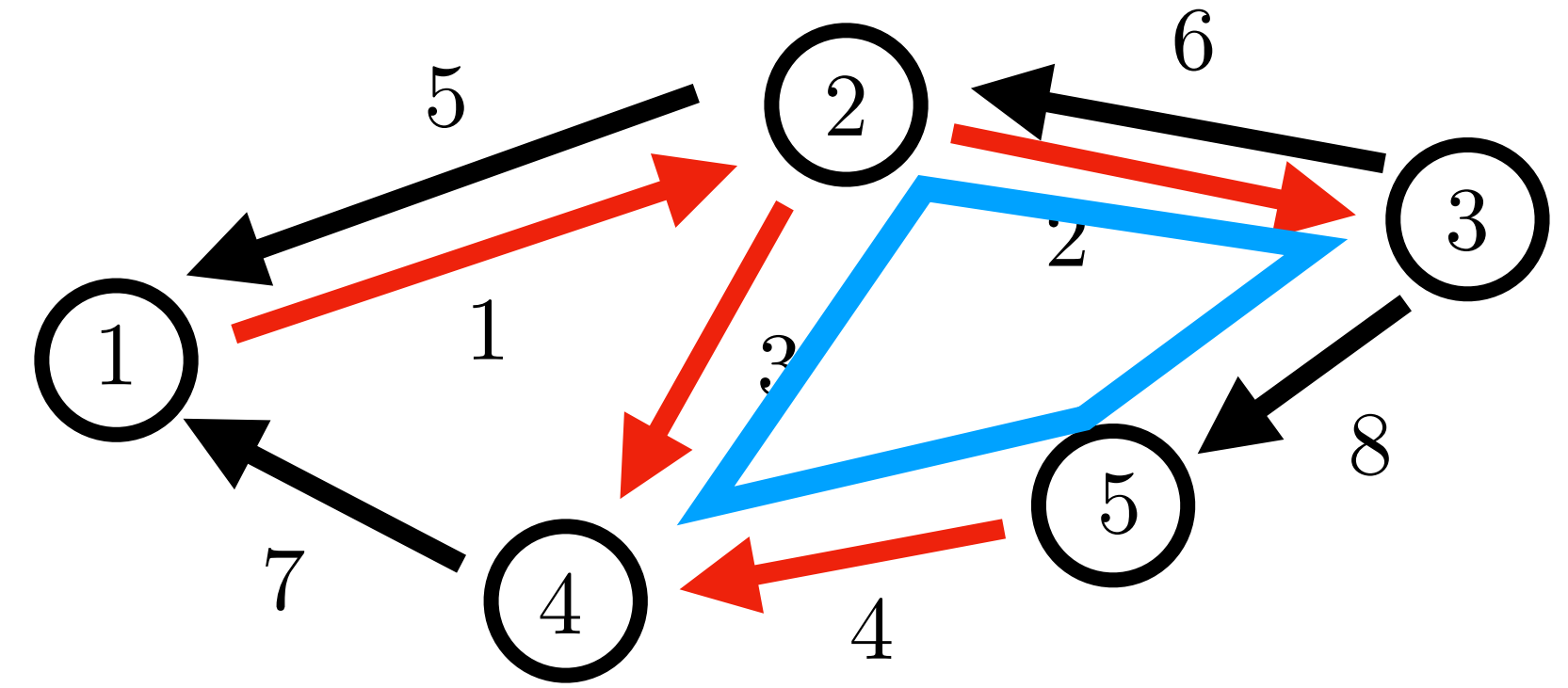
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$$DC = [D' \ D''] \begin{bmatrix} M \\ -I \end{bmatrix} = D'M - D'' = 0$$

# Incidence Matrix - Column Geometry

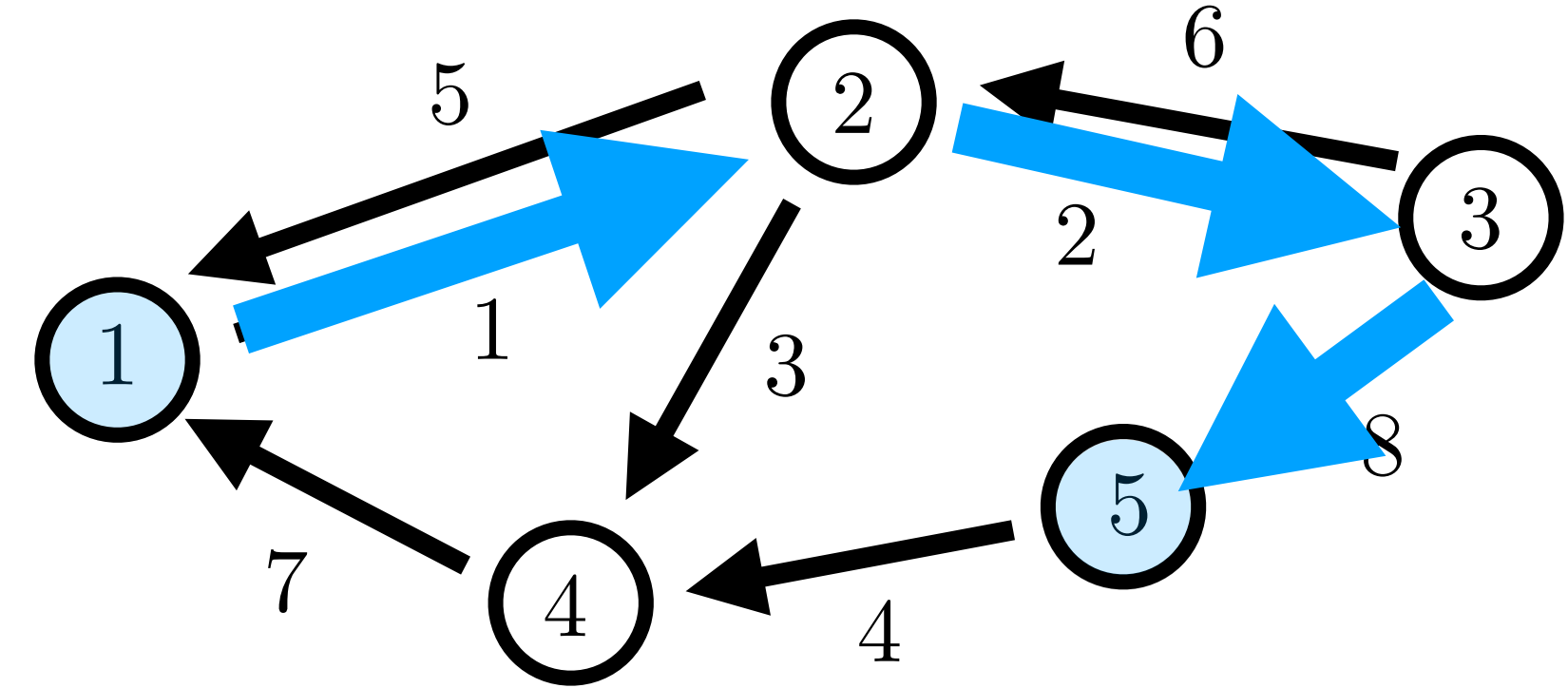
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$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$



## Domain & Co-Domain Interpretation

**Domain:**  $x \in \mathbb{R}^{|\mathcal{E}|}$      ...mass flow on edges

# Incidence Matrix - Column Geometry

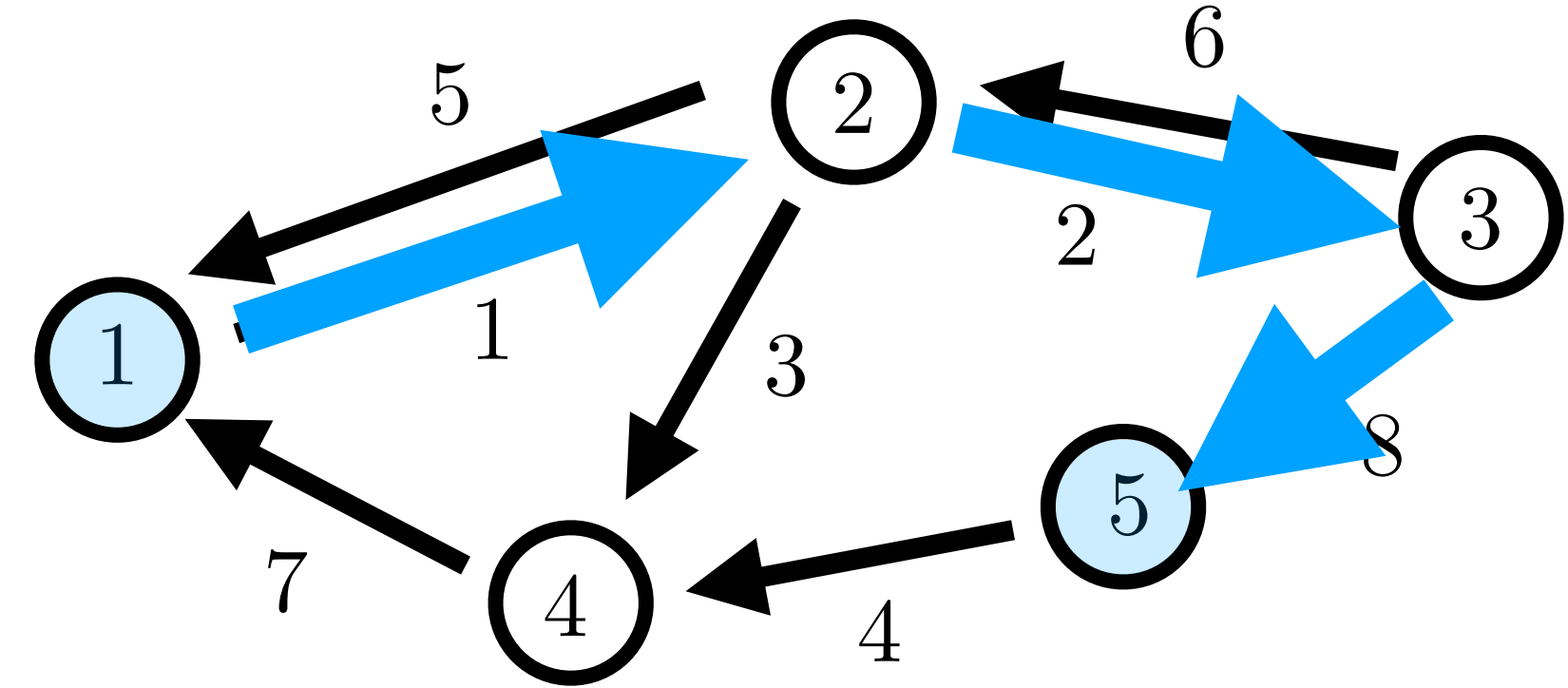
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## Domain & Co-Domain Interpretation

**Domain:**  $x \in \mathbb{R}^{|\mathcal{E}|}$      ...mass flow on edges

Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$S = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow

# Incidence Matrix - Column Geometry

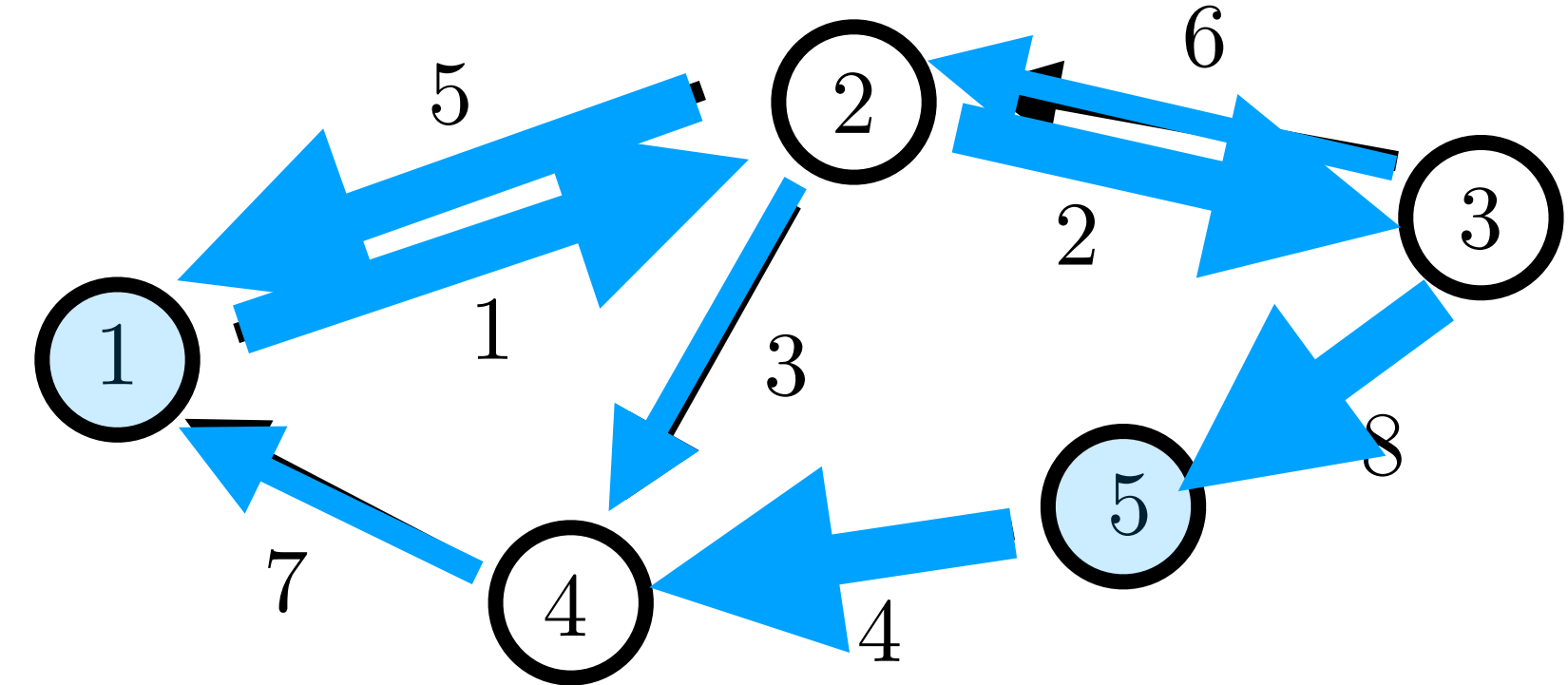
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## Domain & Co-Domain Interpretation

**Domain:**  $x \in \mathbb{R}^{|\mathcal{E}|}$      ...mass flow on edges

Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$S = \begin{bmatrix} -1 \\ 0.5 \\ 2 \\ 0.2 \\ 1 \end{bmatrix}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow

# Incidence Matrix - Column Geometry

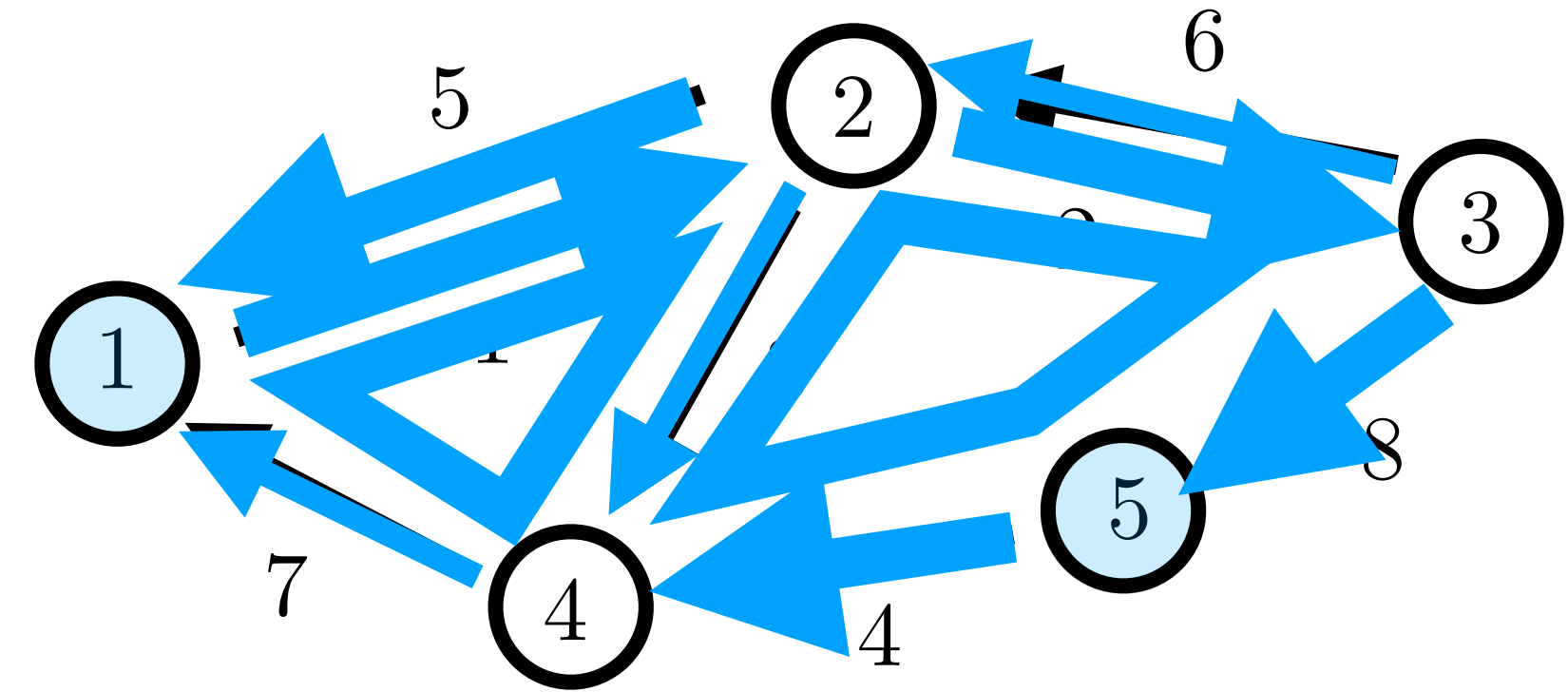
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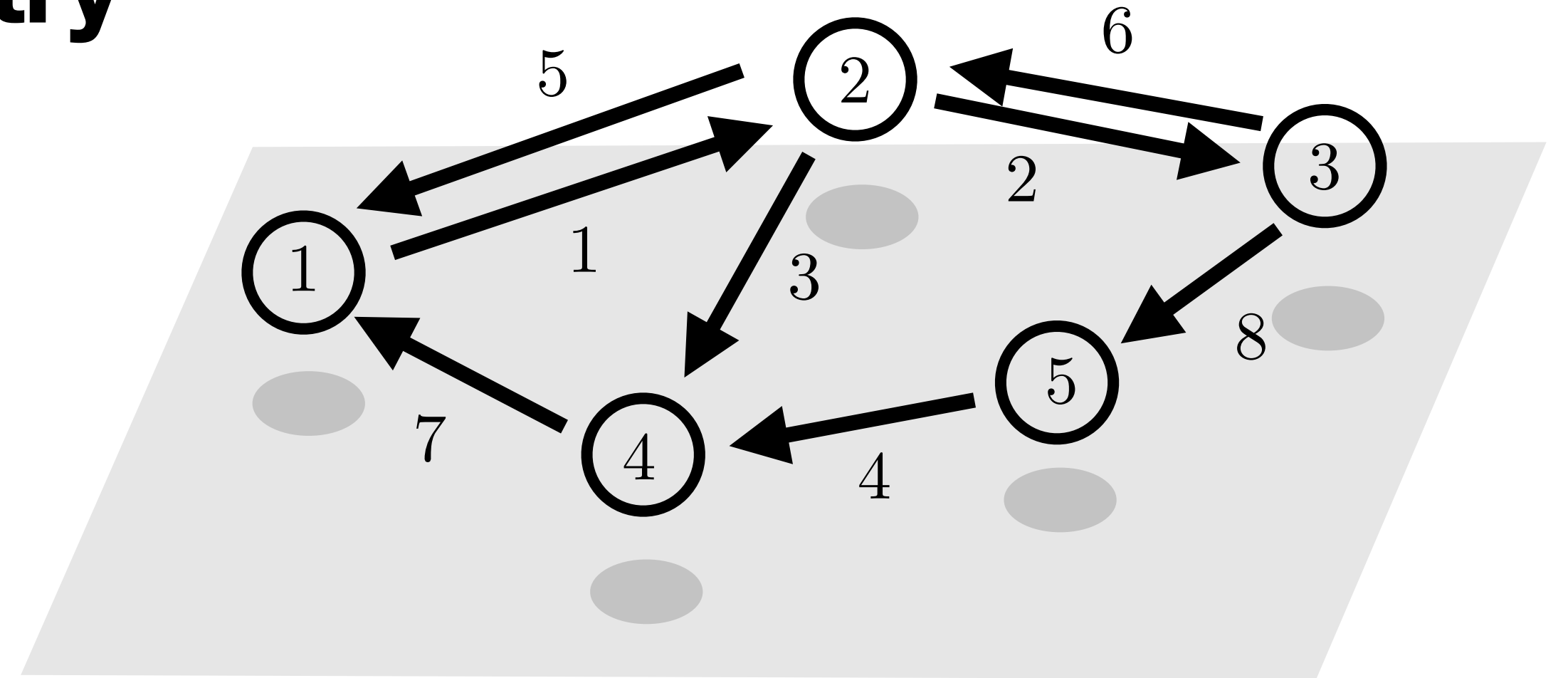
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## Domain & Co-Domain Interpretation

**Domain:**  $x \in \mathbb{R}^{|\mathcal{E}|}$      ...mass flow on edges

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Non-conserved flow

$$S = Dx \quad \text{Edge flow vector}$$

$$x = \bar{x} + Cz$$

Specific Solution

Cyclic Flow

# Incidence Matrix - Column Geometry

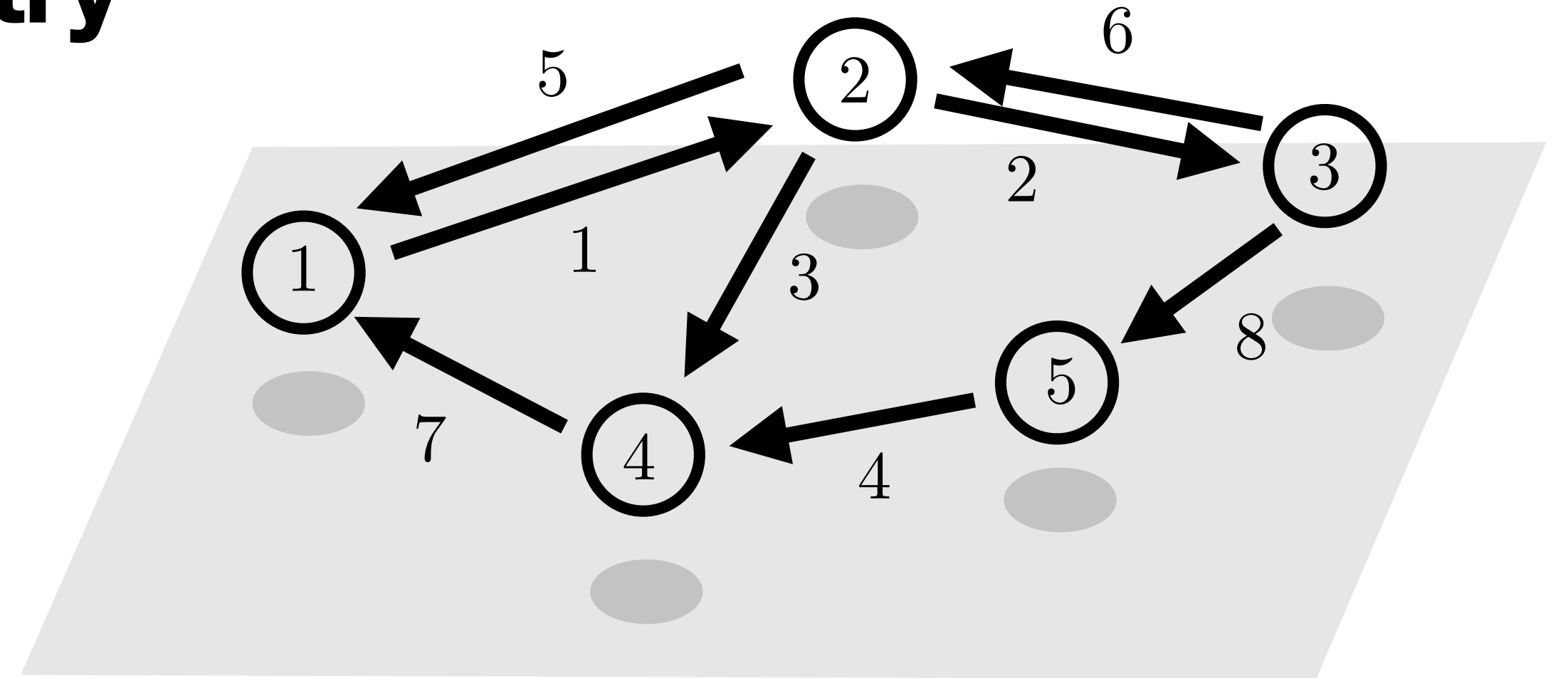
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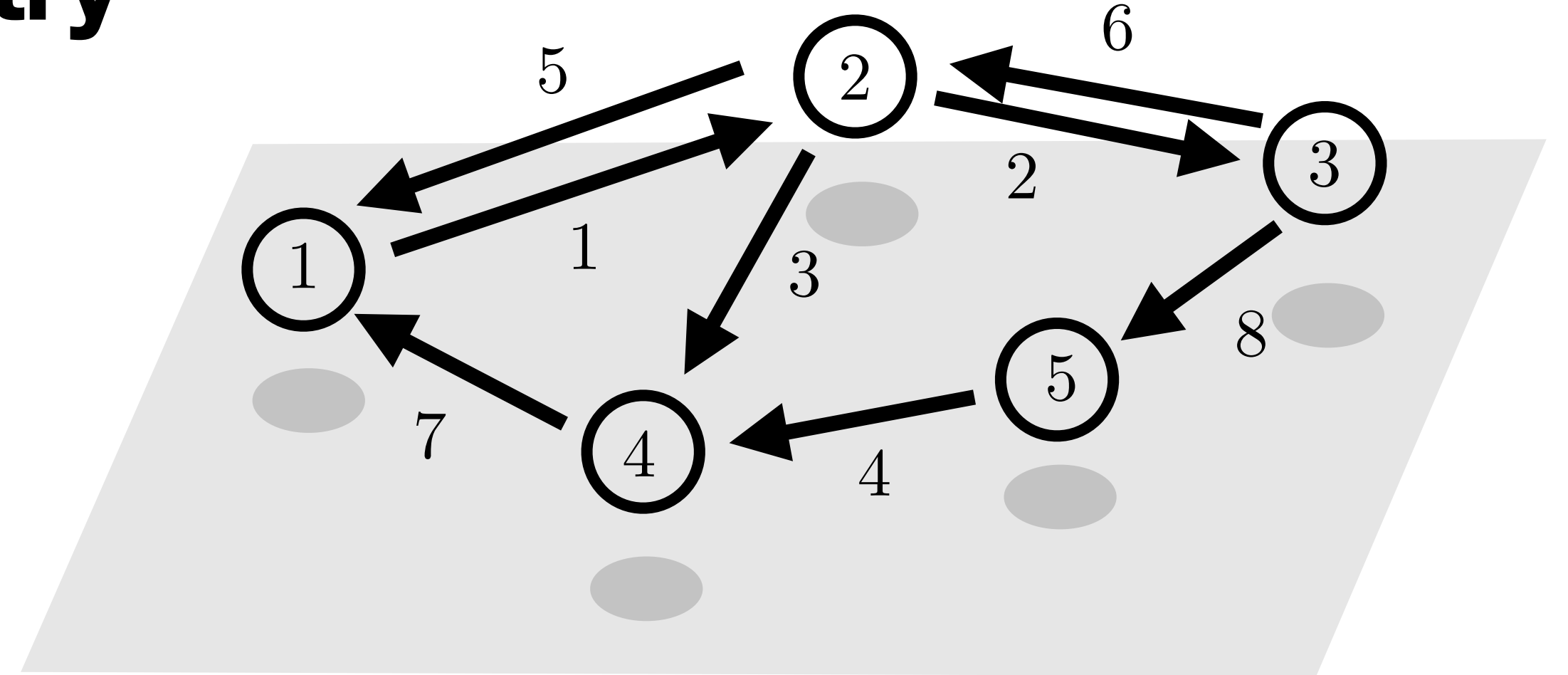
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**Value Function**

Cost-to-go

Potential value

“Height” - gravitational potential

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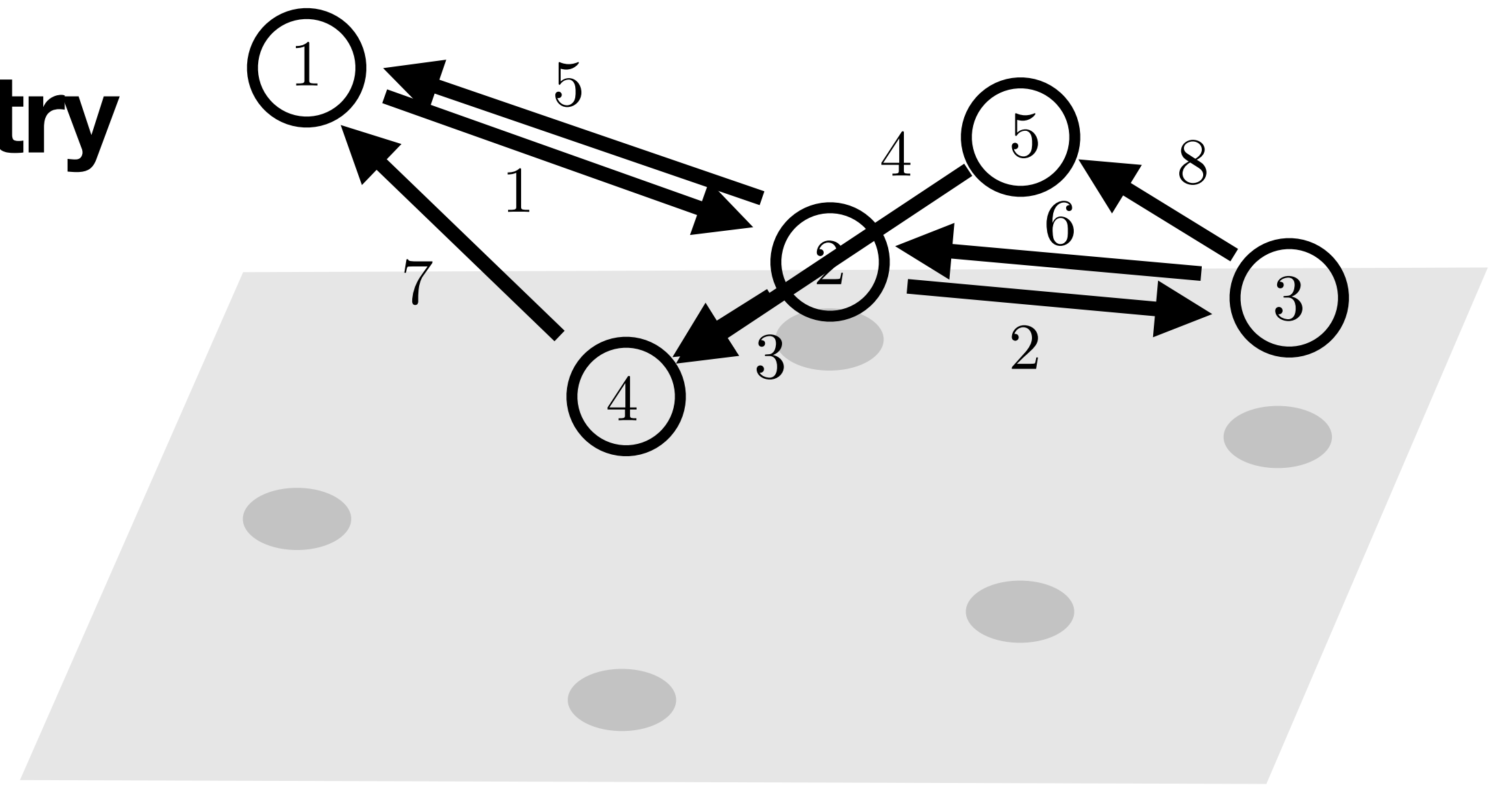
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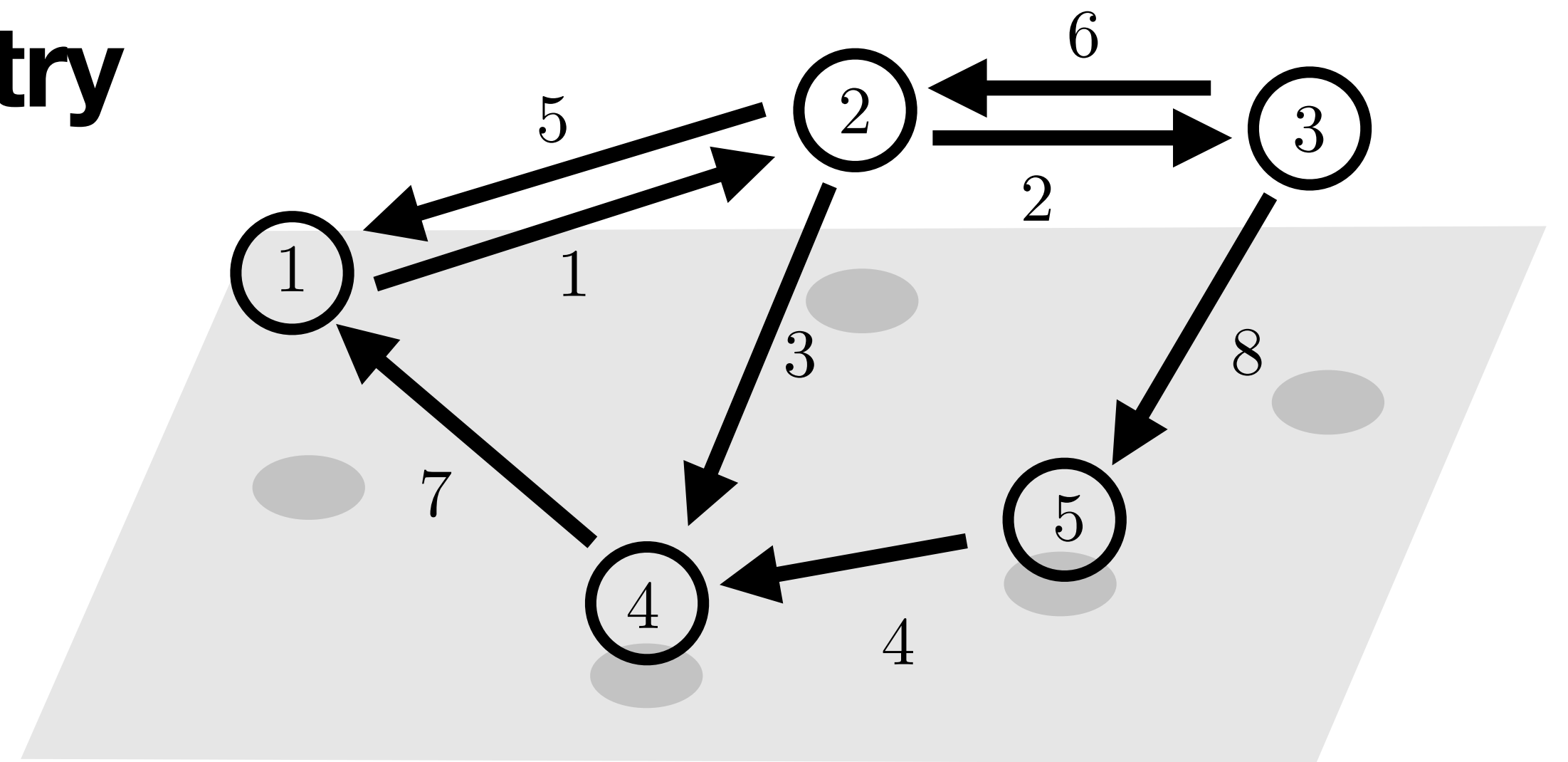
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 Potential value  
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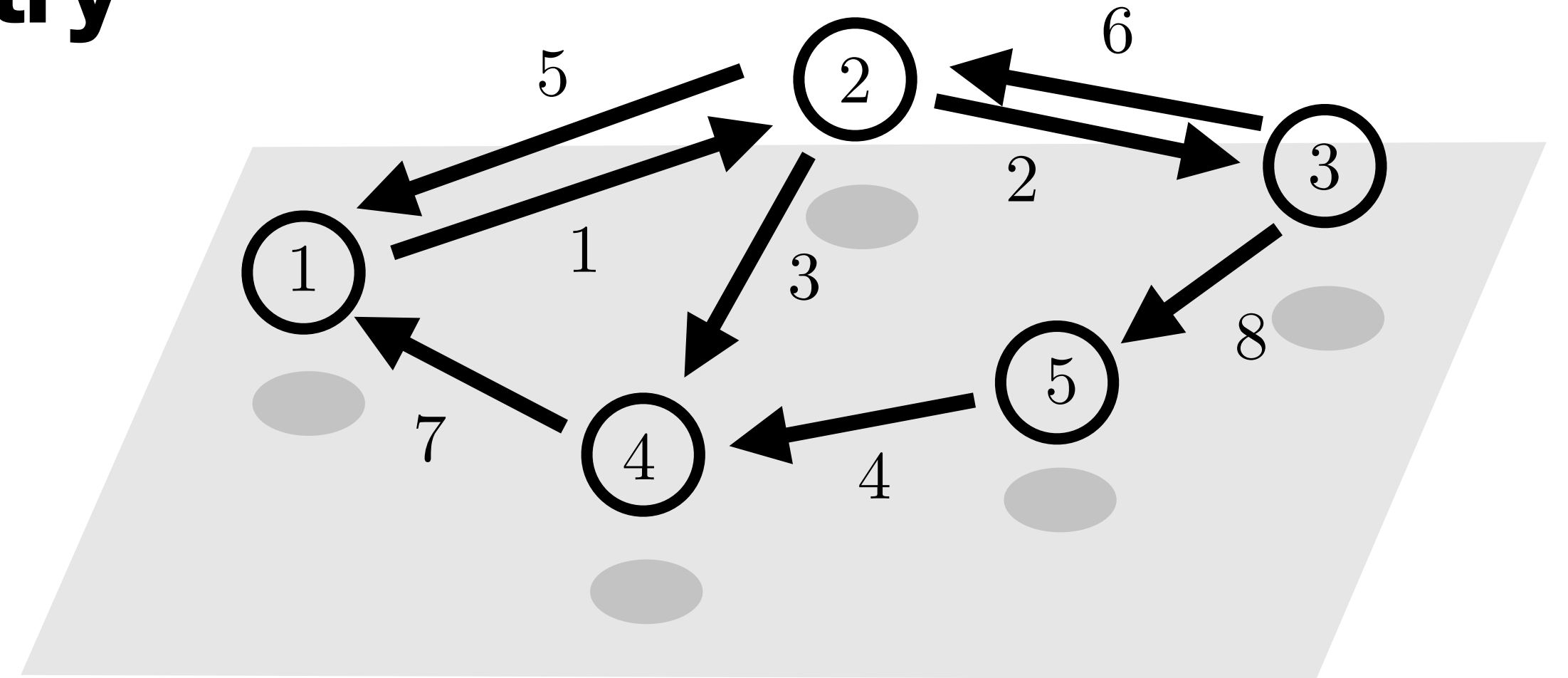
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$$[w^T D]_e = w_i - w_{i'} = \tau_e$$

# Incidence Matrix - Column Geometry

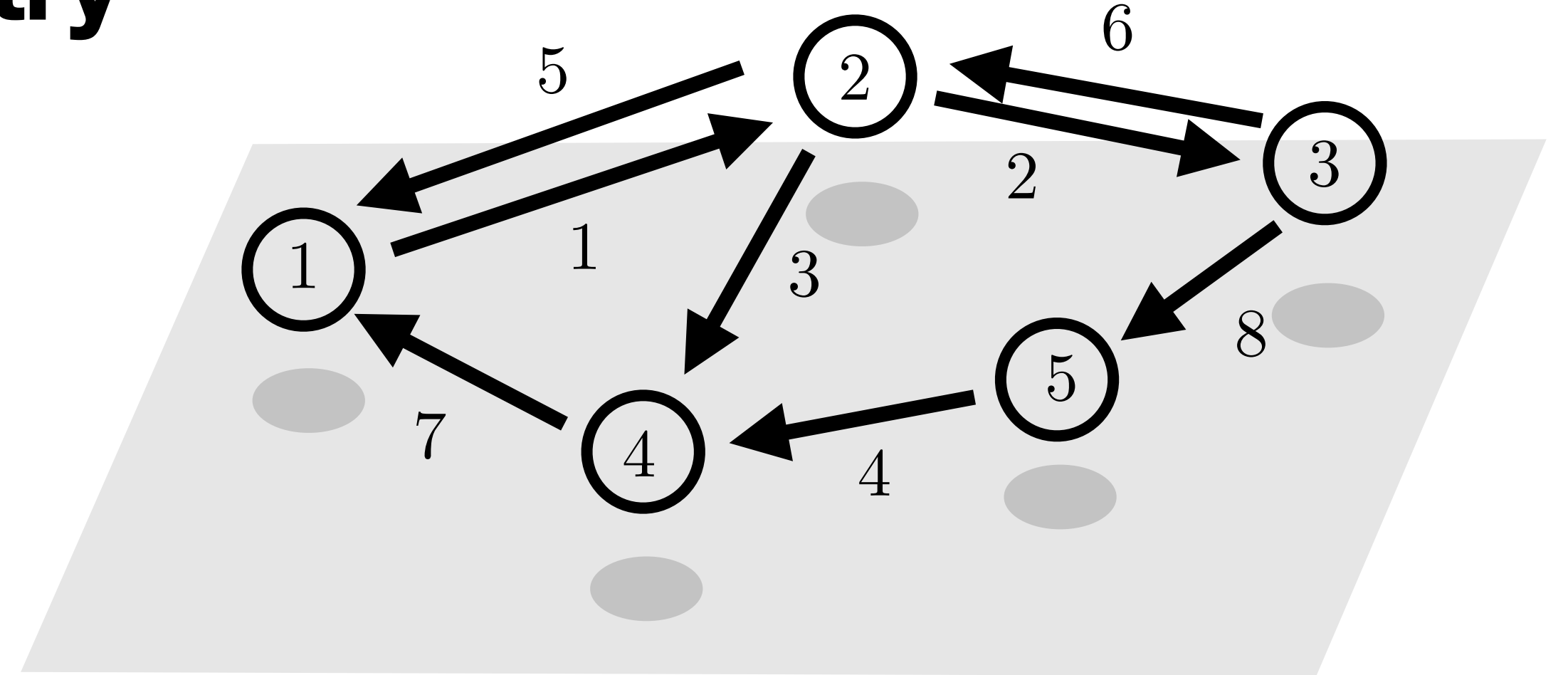
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Constant shift (doesn't change tension)

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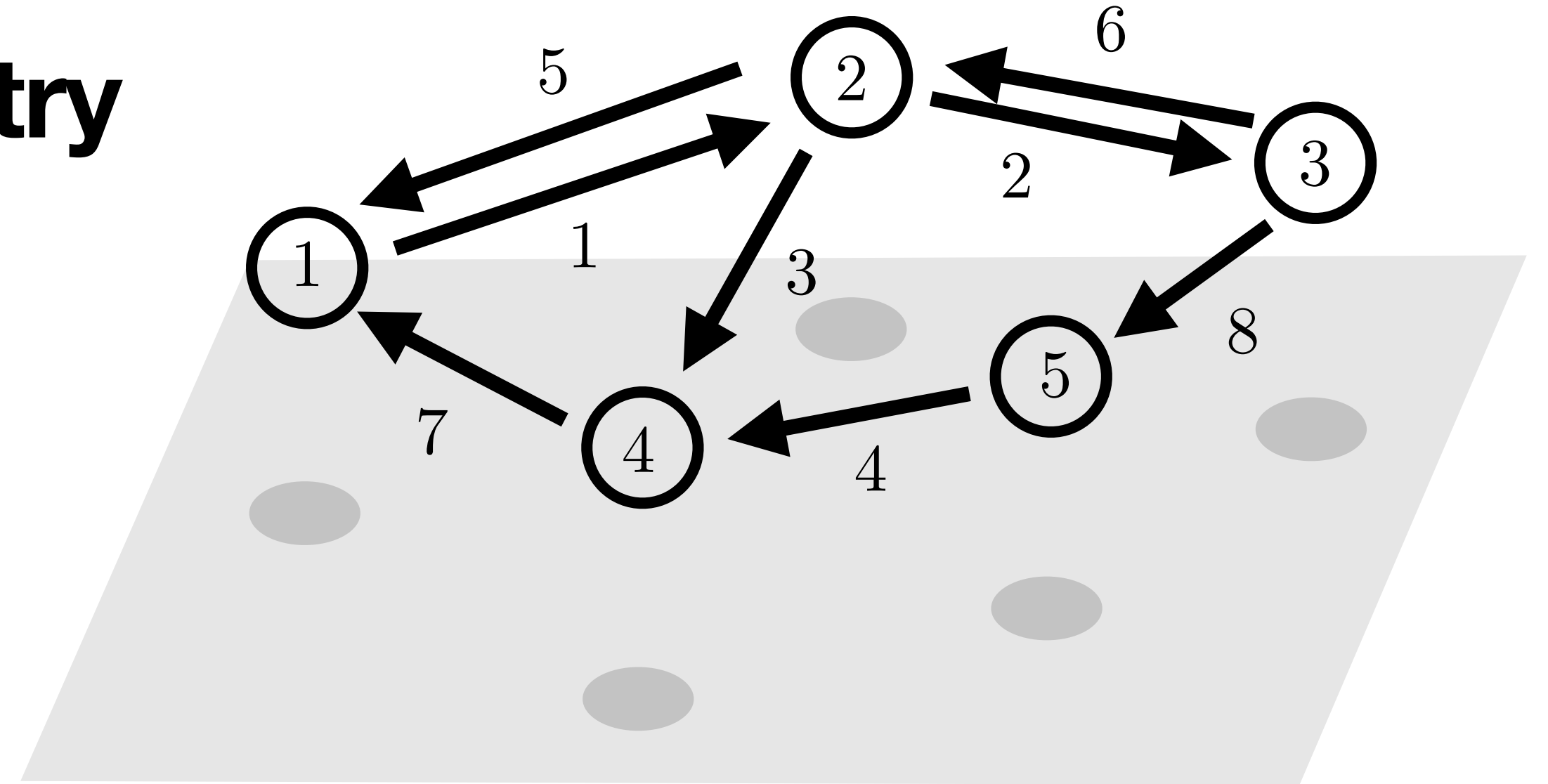
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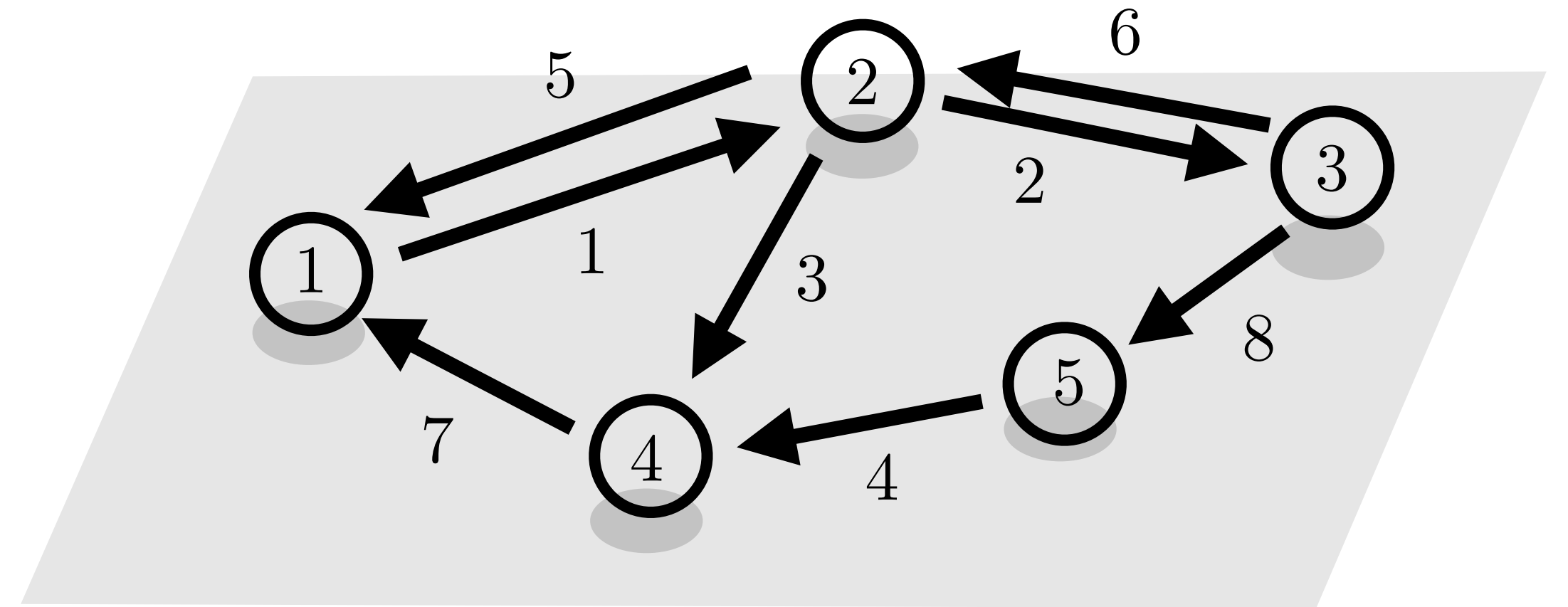
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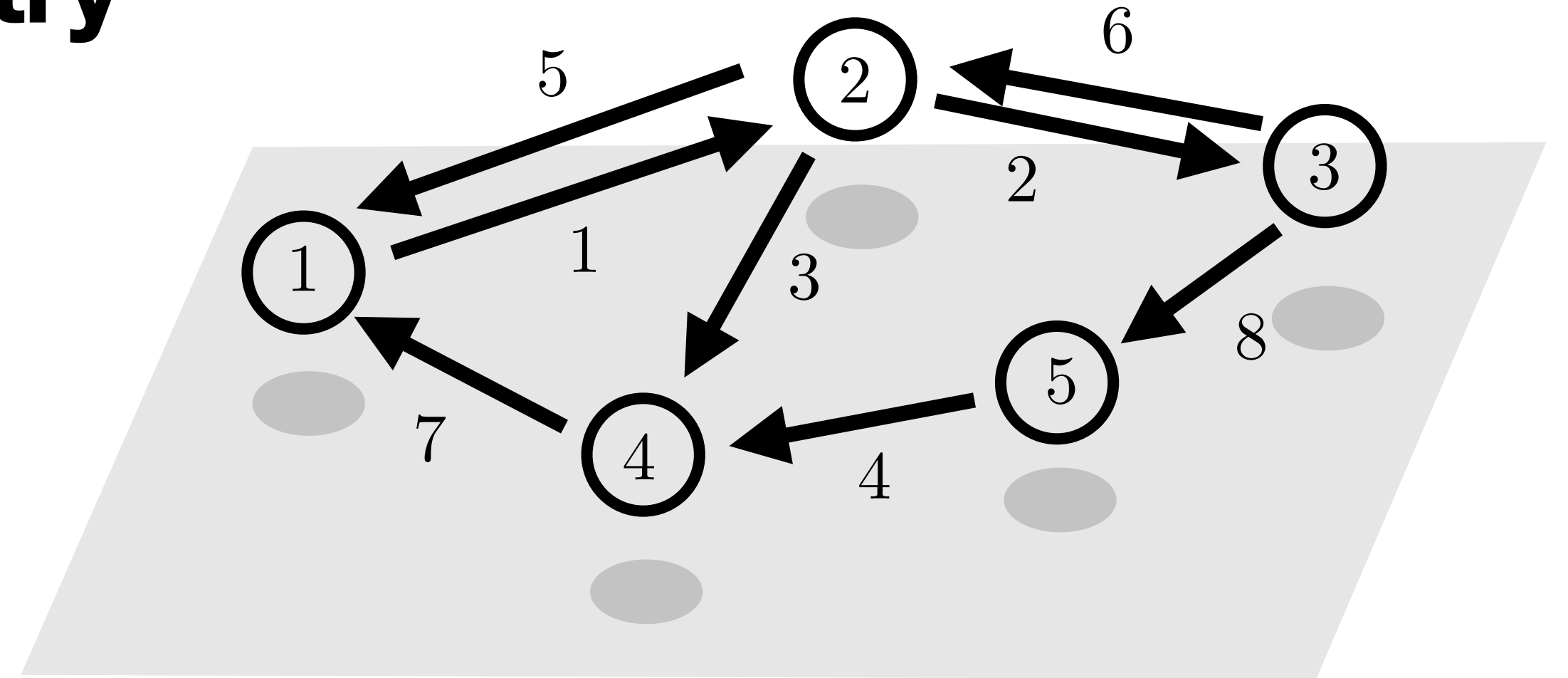
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# Graph Laplacians

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

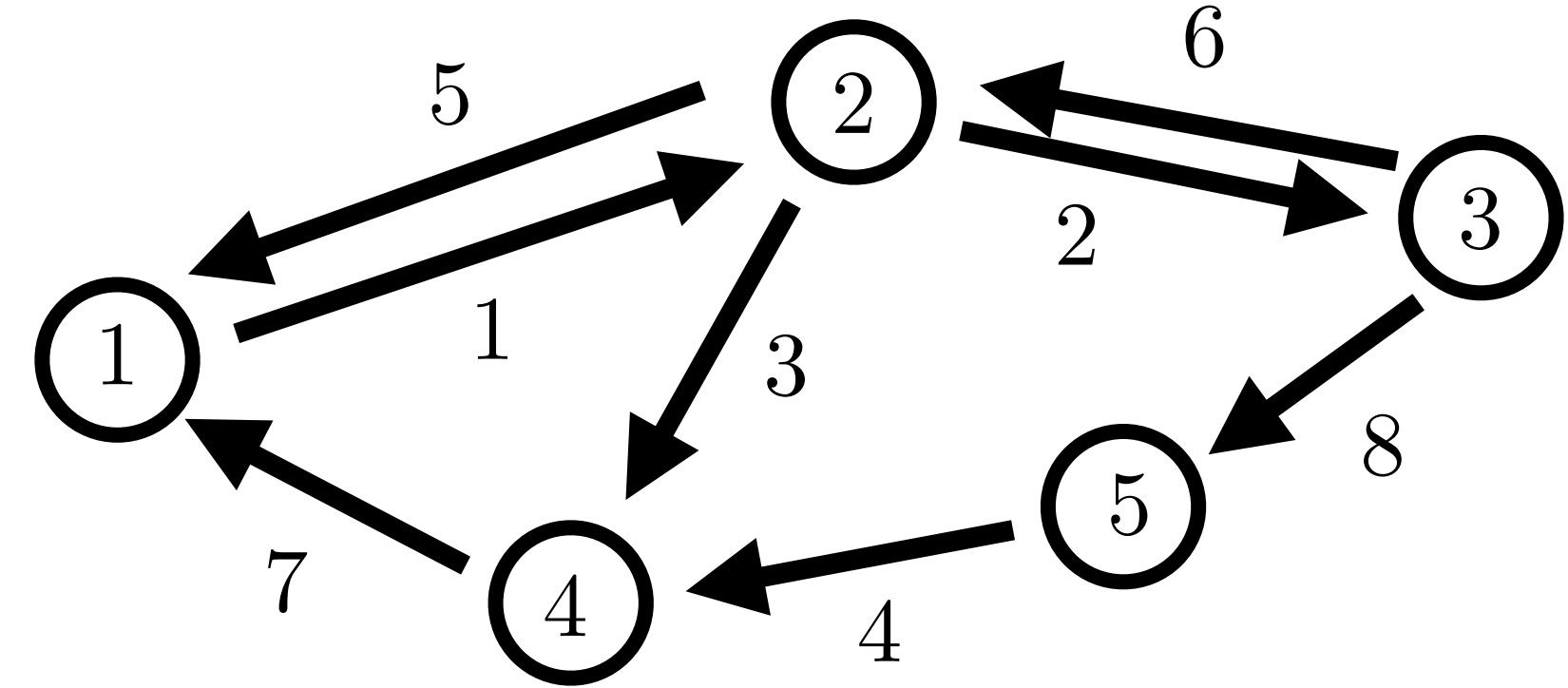
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## Review: Shape Matrices

**General Matrix**  $A \in \mathbb{R}^{m \times n}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

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# Graph Laplacians

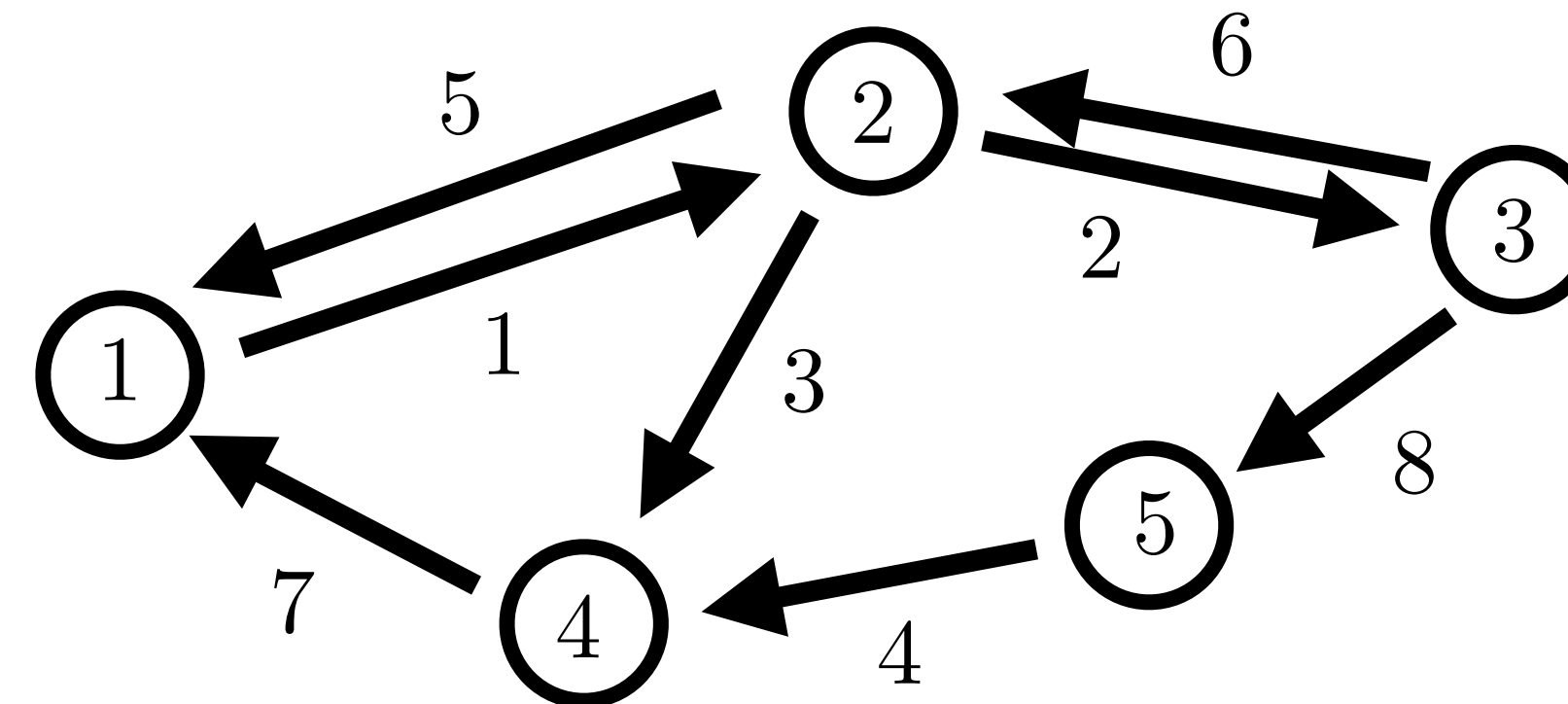
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Inner products  
of columns

“Relative geometry  
of columns”

$$= \begin{bmatrix} - & a_1^T & - \\ \vdots & & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

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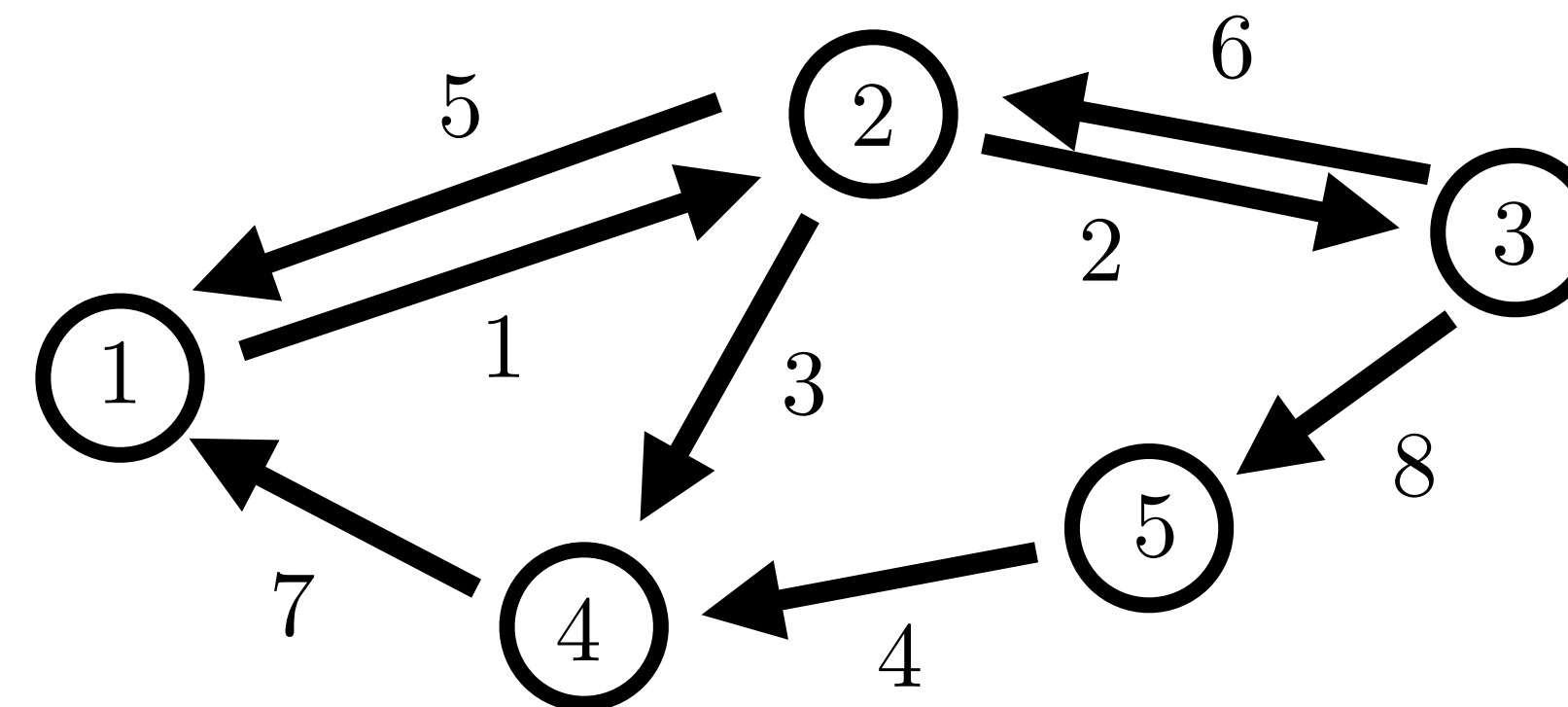
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$RA$  rotate columns of A...  
 ....relative geometry stays the same.

$$(RA)^T (RA) = A^T R^T R A = A^T A$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

$$AA^T = \begin{bmatrix} a_1^T a_1 & \cdots & a_1^T a_m \\ \vdots & & \vdots \\ a_m^T a_1 & \cdots & a_m^T a_m \end{bmatrix}$$

$AR$  rotate rows of A...  
 ....relative geometry stays the same.

$$(AR)(AR)^T = ARR^T A^T = AA^T$$

# Graph Laplacians

**Graph:**

**Vertices**

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$$\mathcal{G} = (\mathcal{V}, \mathcal{E})$$

**Edges**

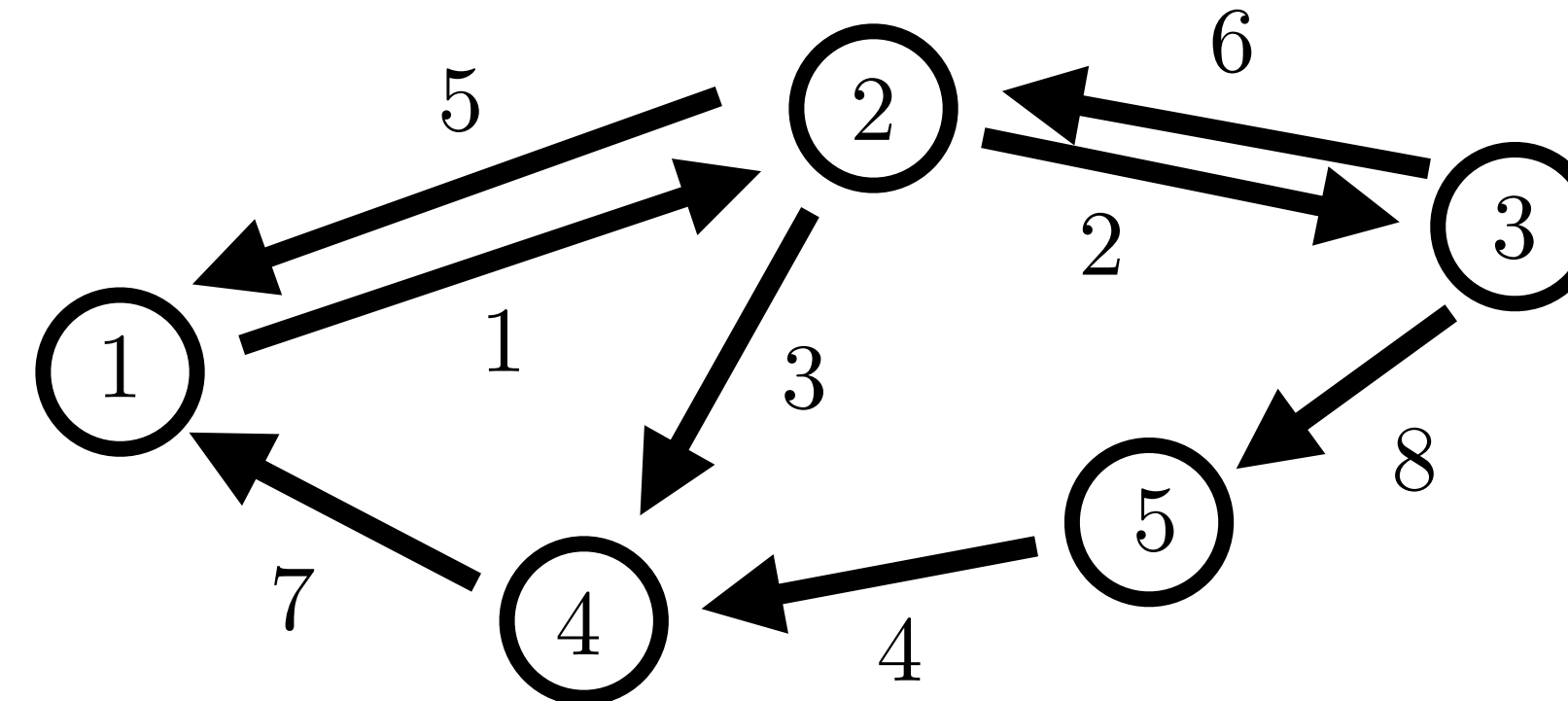
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## Review: Shape Matrices

$$A^T A$$

“Shape” of the columns of A

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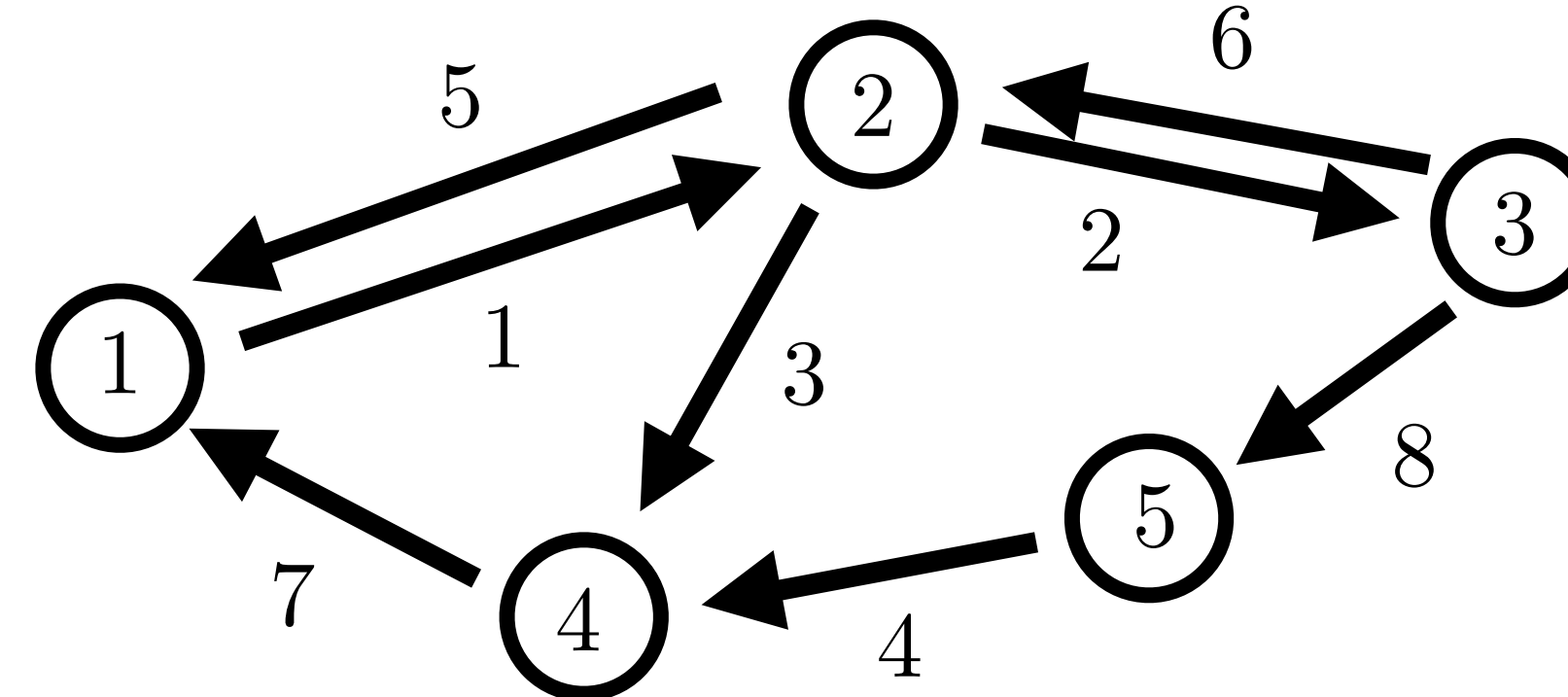
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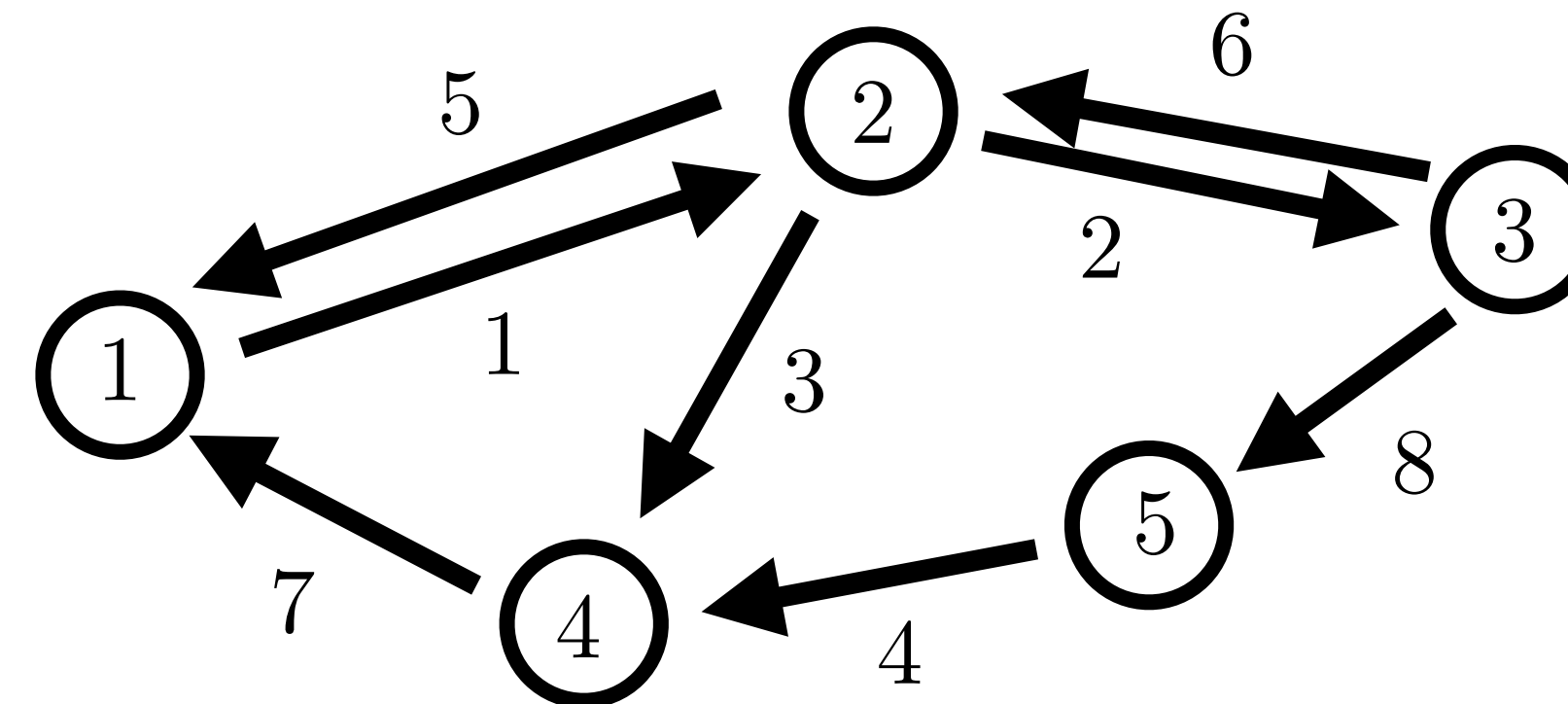
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## Review: Shape Matrices

$(A^T A)^{1/2}$  “Shape” of the columns of A

More Accurate

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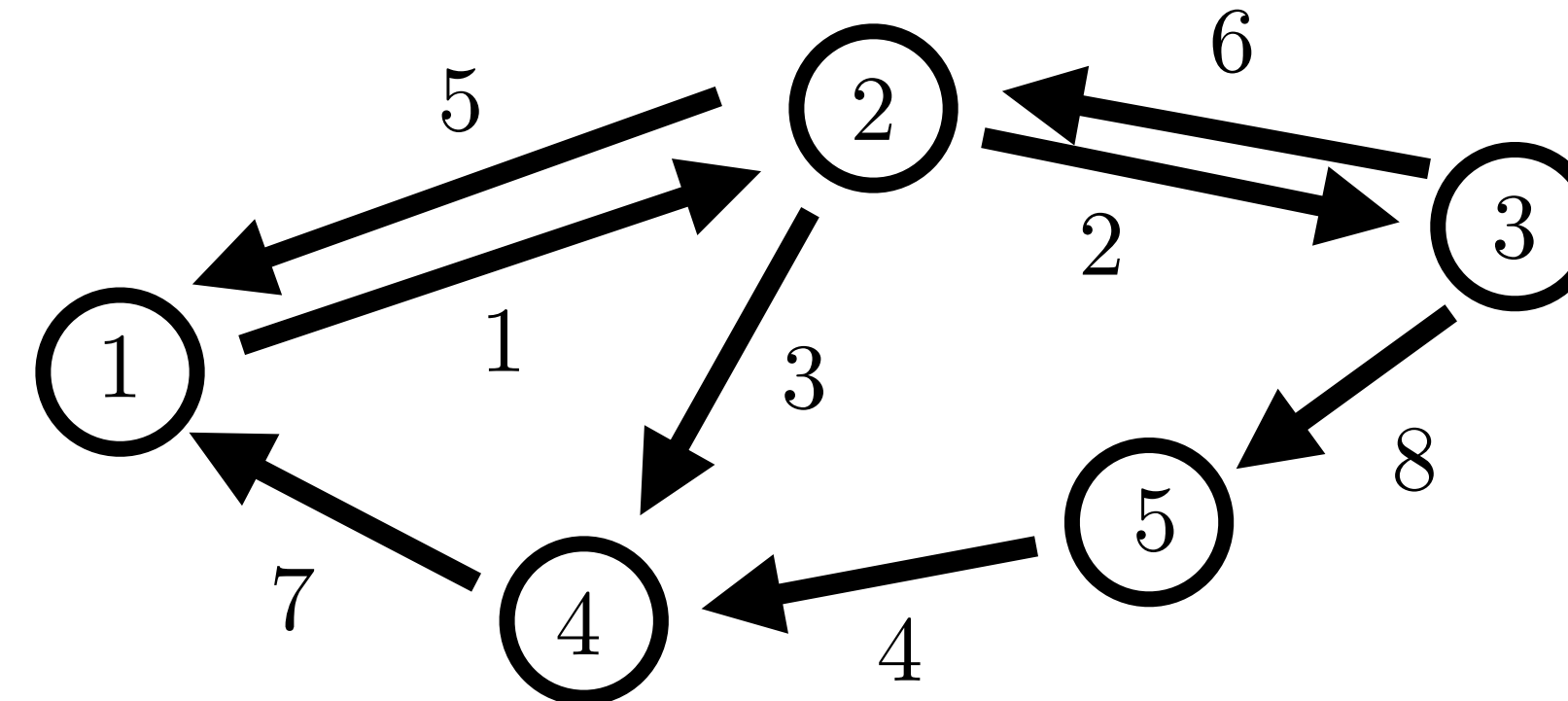
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## Review: Shape Matrices

$$(A^T A)^{1/2}$$

“Shape” of columns

$$(A A^T)^{1/2}$$

“Shape” of rows

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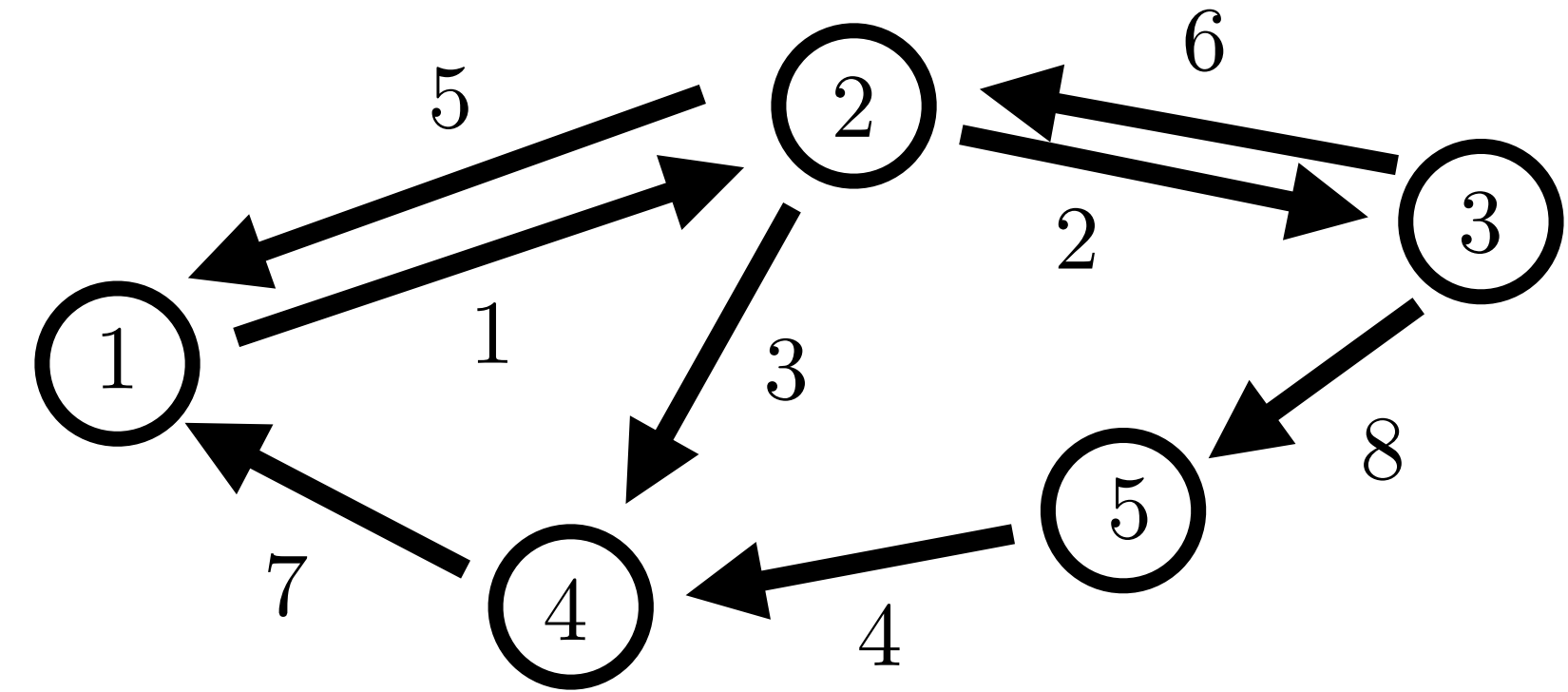
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## Review: Shape Matrices

$(A^T A)^{1/2}$  “Shape” of columns       $(A A^T)^{1/2}$  “Shape” of rows

**General Matrix**  $A \in \mathbb{R}^{m \times n}$

Analogy:  $z \in \mathbb{C}$        $|z| = \sqrt{z^* z}$        $z = |z| e^{i\phi}$

$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

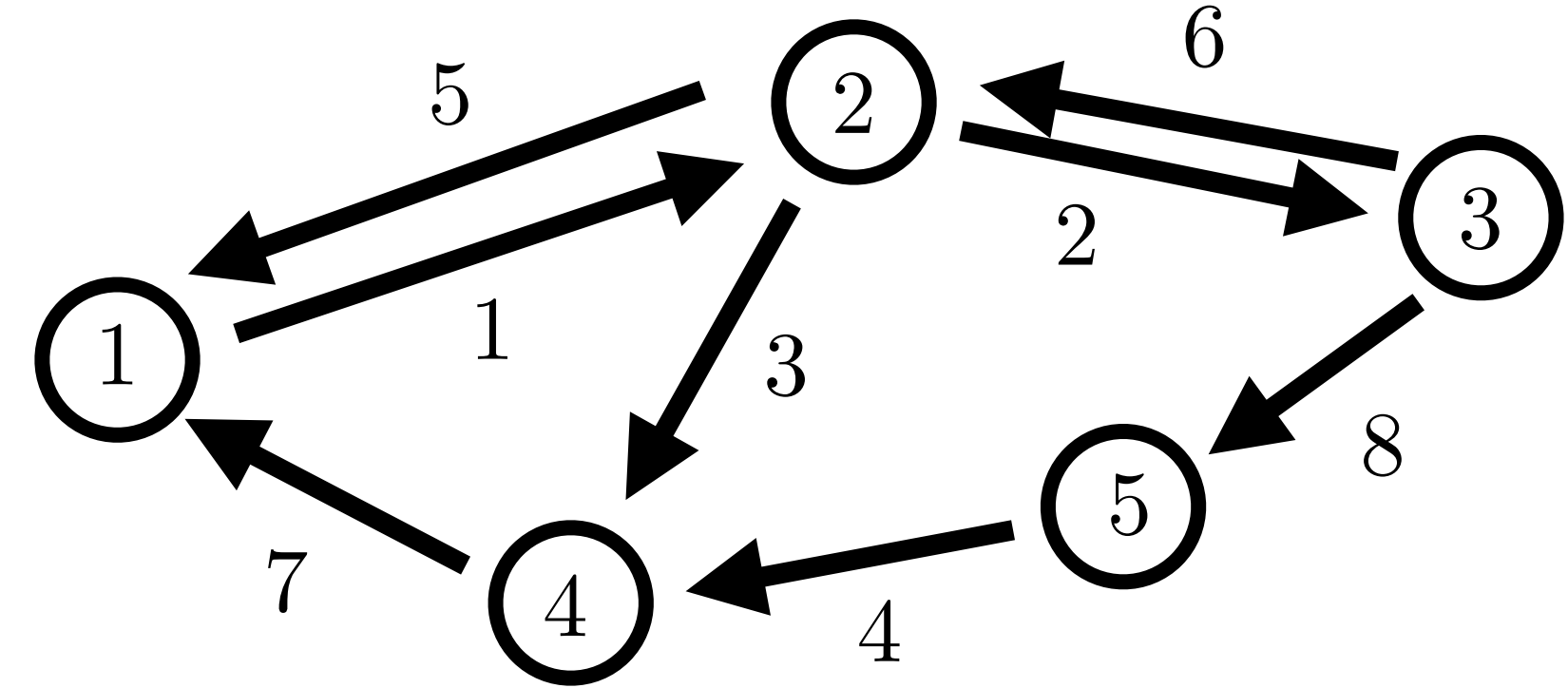
$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$



# Graph Laplacians

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$   
**Vertices**  $v \in \mathcal{V}$   
**Edges**  $e \in \mathcal{E}$

$$e = (v, v')$$



**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

## Review: Shape Matrices

$(A^T A)^{1/2}$  “Shape” of columns       $(A A^T)^{1/2}$  “Shape” of rows

**General Matrix**  $A \in \mathbb{R}^{m \times n}$

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**Polar Decomposition**

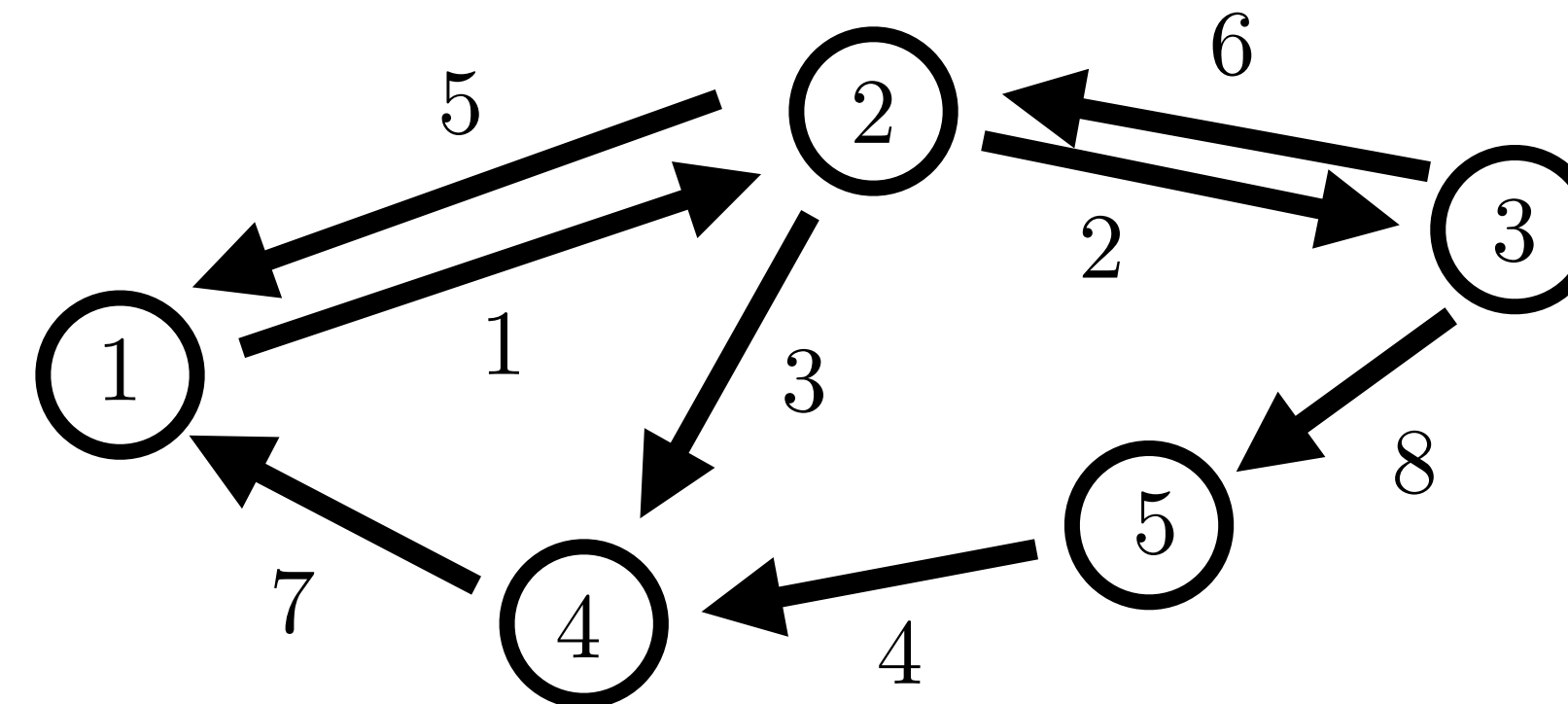
$$A = \underbrace{A(A^T A)^{-1/2}}_{\text{Rotation}} \cdot \underbrace{(A^T A)^{1/2}}_{\text{PSD "shape"}} \quad \text{“Column version”}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

# Graph Laplacians

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## Polar Decomposition

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Rotation      PSD “shape”

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

$$A = (A A^T)^{1/2} \cdot (A A^T)^{-1/2} A \quad \text{“Row version”}$$

PSD “shape”      Rotation

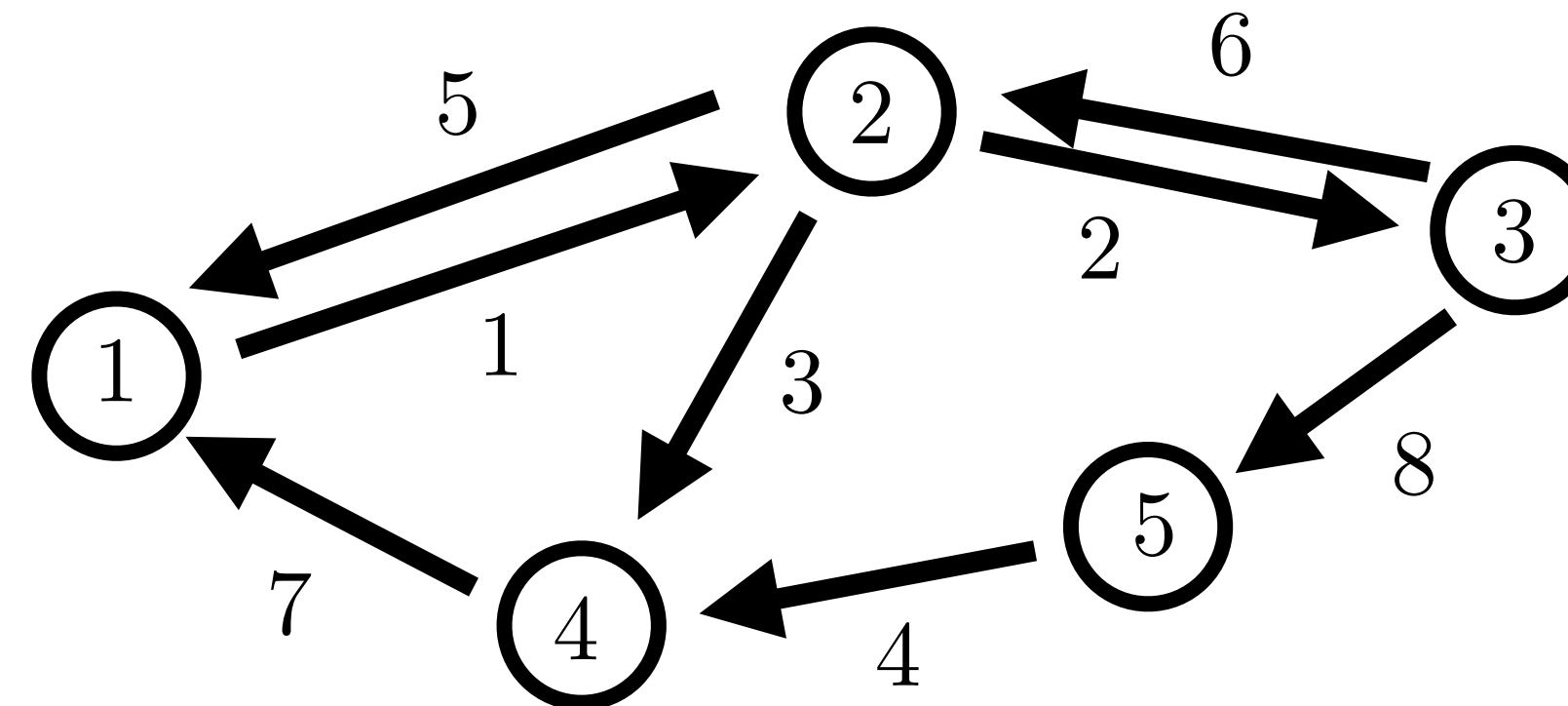
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PSD “shape”                  Rotation

**Checking rotation...**

$$(A^T A)^{-1/2} A^T A (A^T A)^{-1/2} = I$$

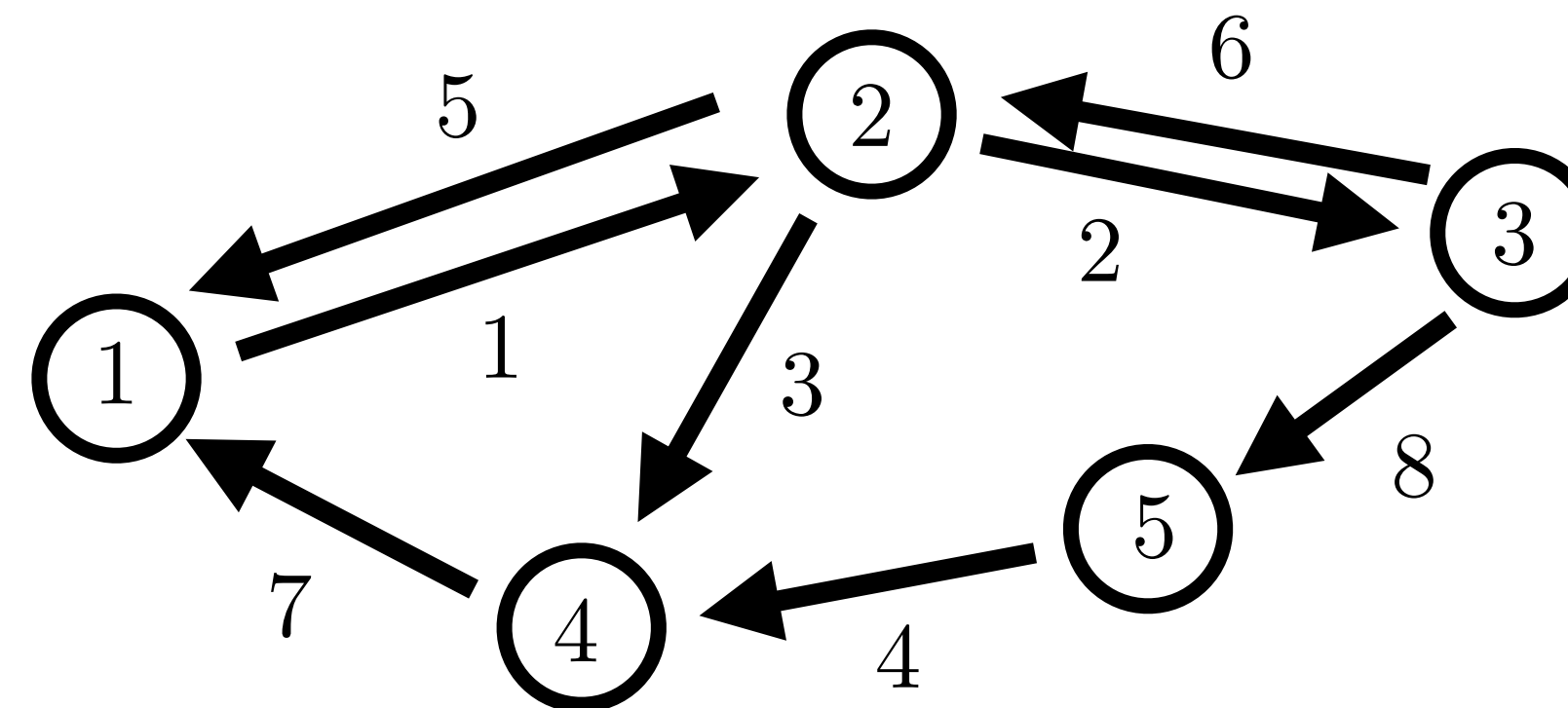
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**EVD of Shapes**

$$(A^T A)^{1/2} = V \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T \quad (A A^T)^{1/2} = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} U^T$$

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**Polar Decomposition**

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$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

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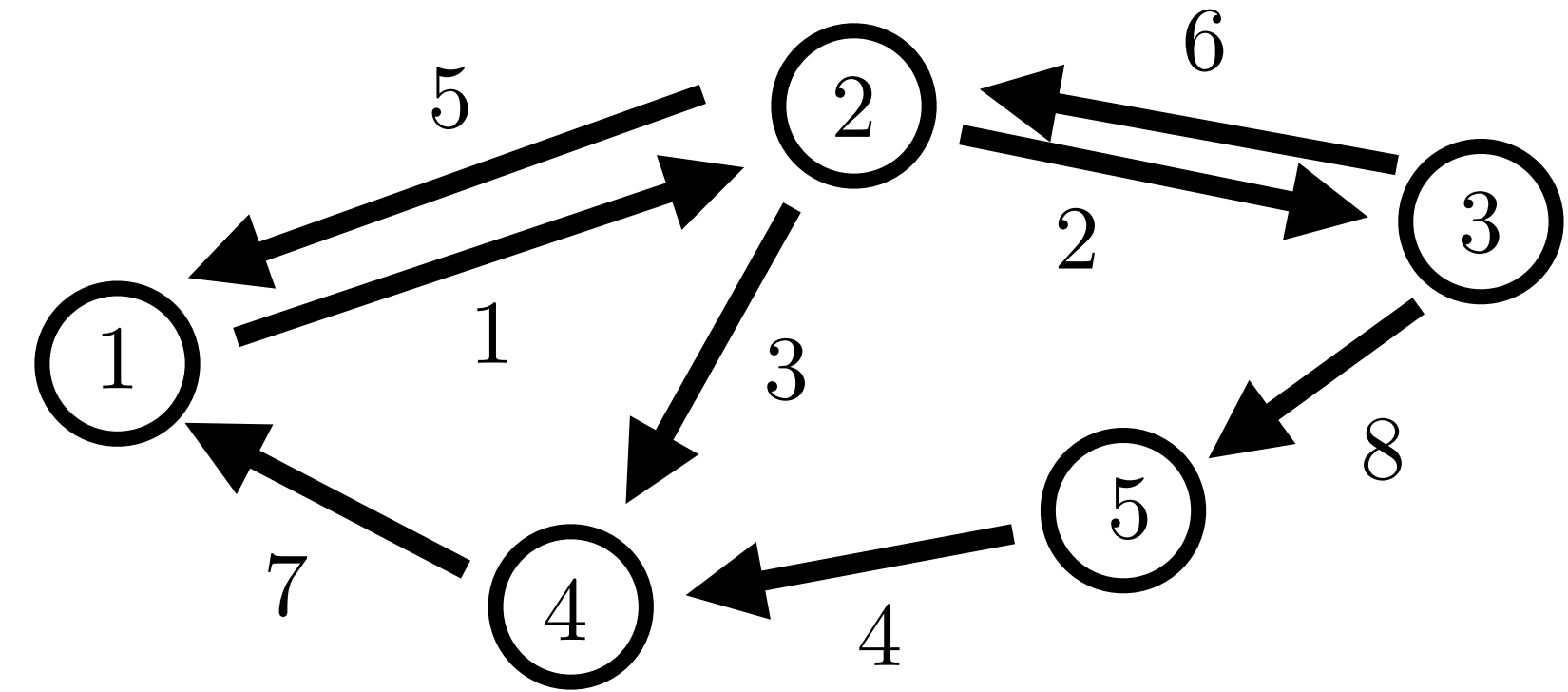
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**Polar Decomposition**

$$A = U V^T \cdot V \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T \quad \text{“Column version”}$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

Rotation

PSD “shape”

$$A = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} U^T \cdot U V^T \quad \text{“Row version”}$$

PSD “shape”

Rotation

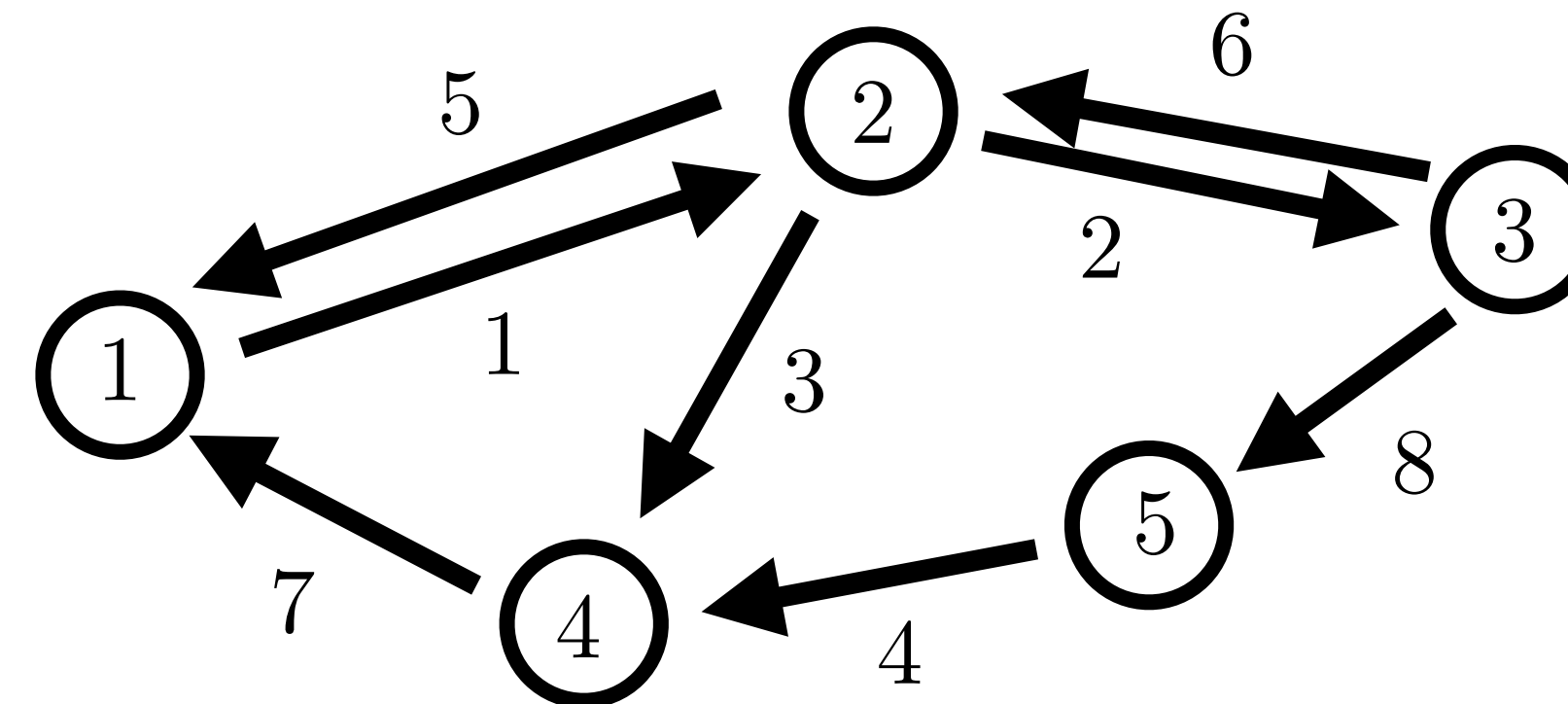
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$$A = \begin{bmatrix} | & & | \\ A_1 & \cdots & A_n \\ | & & | \end{bmatrix} \quad \text{cols...}$$

**Singular Value**

$$A = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$$

$$= \begin{bmatrix} - & a_1^T & - \\ & \vdots & \\ - & a_m^T & - \end{bmatrix} \quad \text{rows...}$$

**Decomposition**

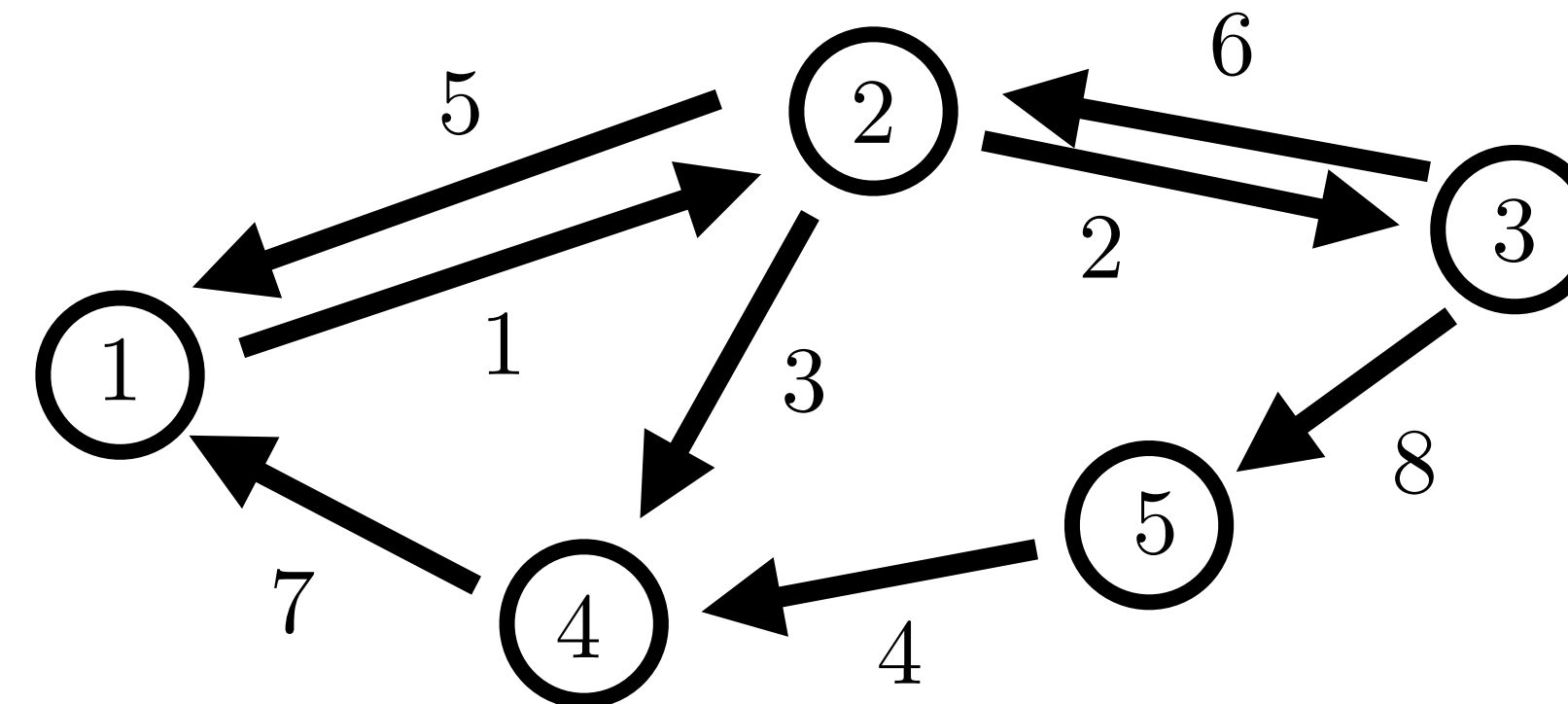
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**Decomposition**

$$U' = A V' \Sigma^{-1} \quad V'^T = \Sigma^{-1} U'^T A$$

for singular vectors w/ non-zero values

# Graph Laplacians

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

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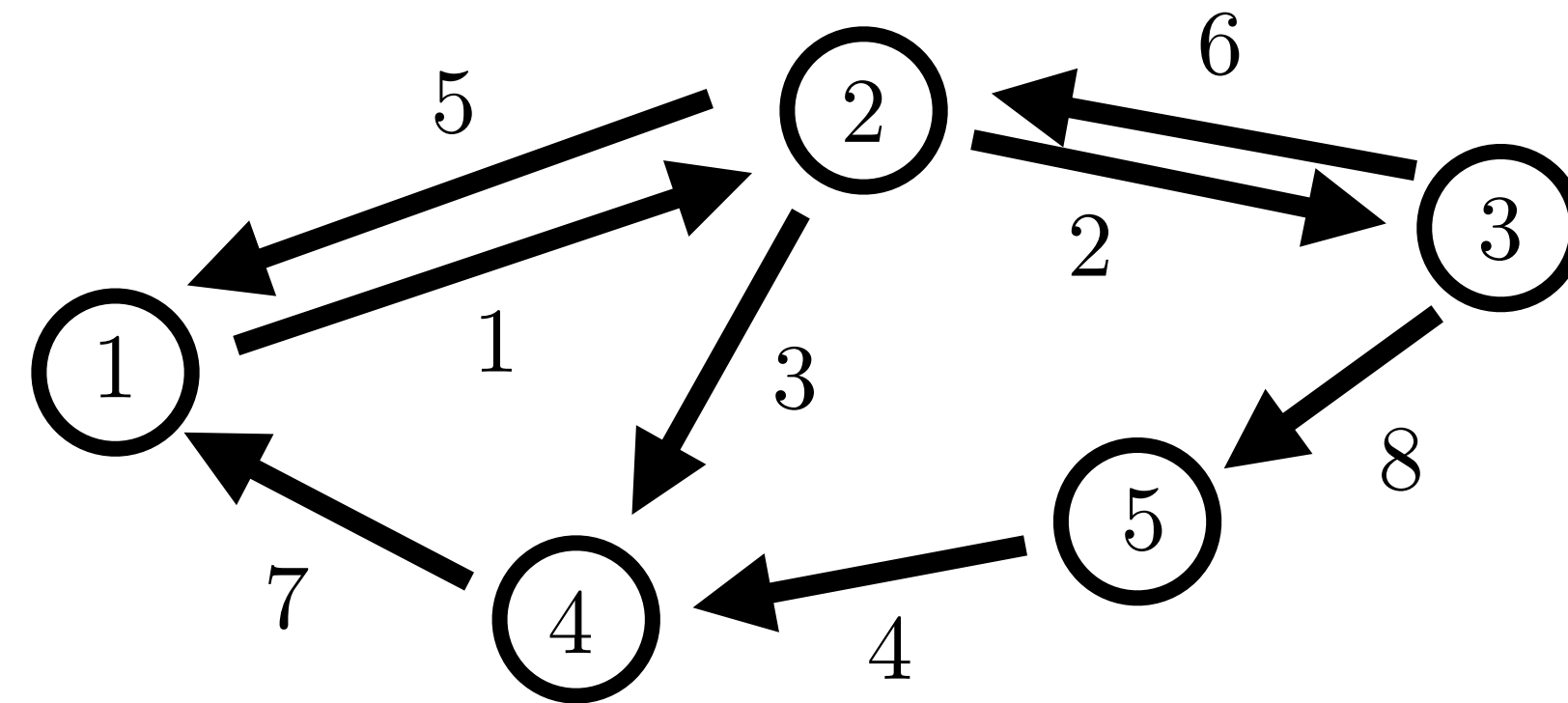
**Incidence SVD**      $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

**Laplacian**     row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

**Edge-Laplacian**     col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$





# Graph Laplacians

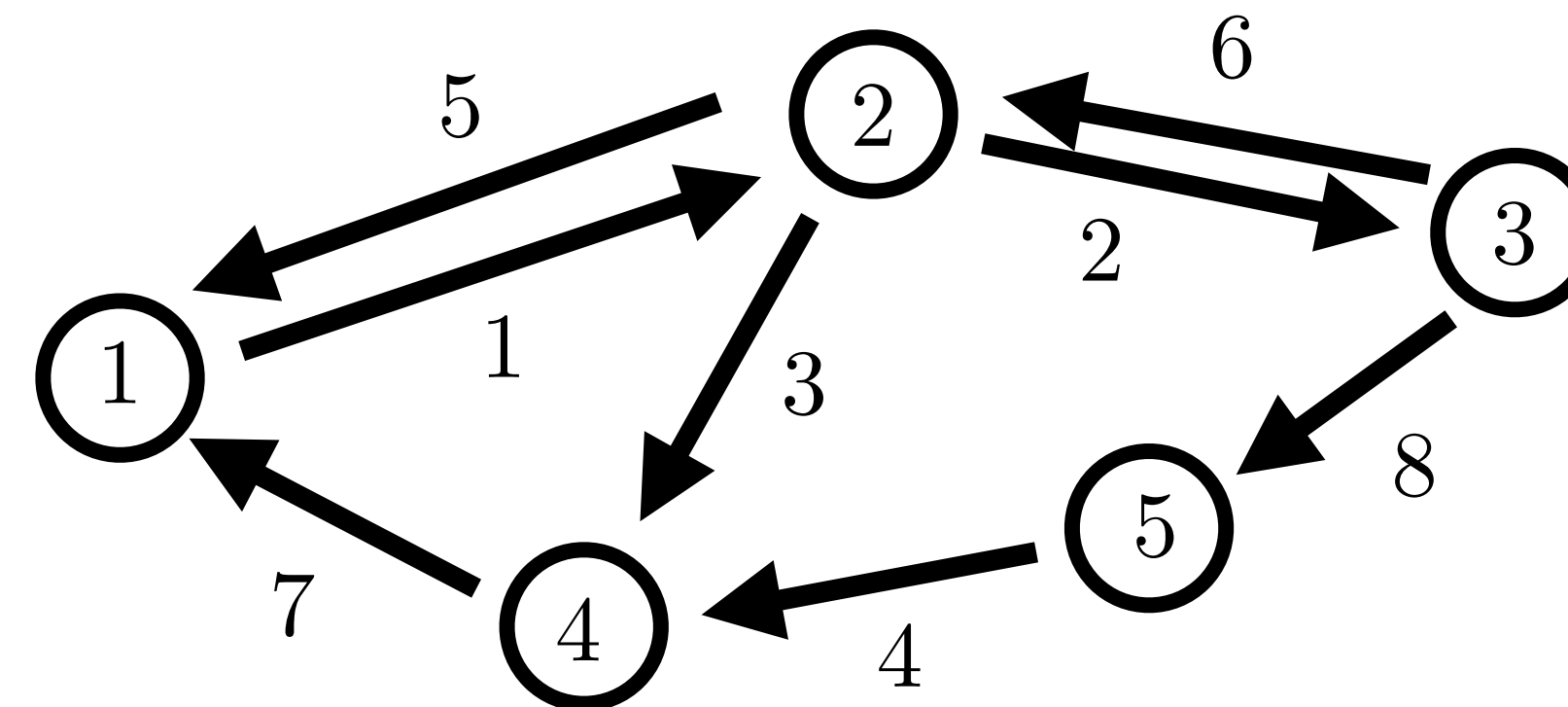
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**Laplacian**  $L = DD^T$

**Incidence SVD**  $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

**Laplacian** row “shape” matrix (squared)

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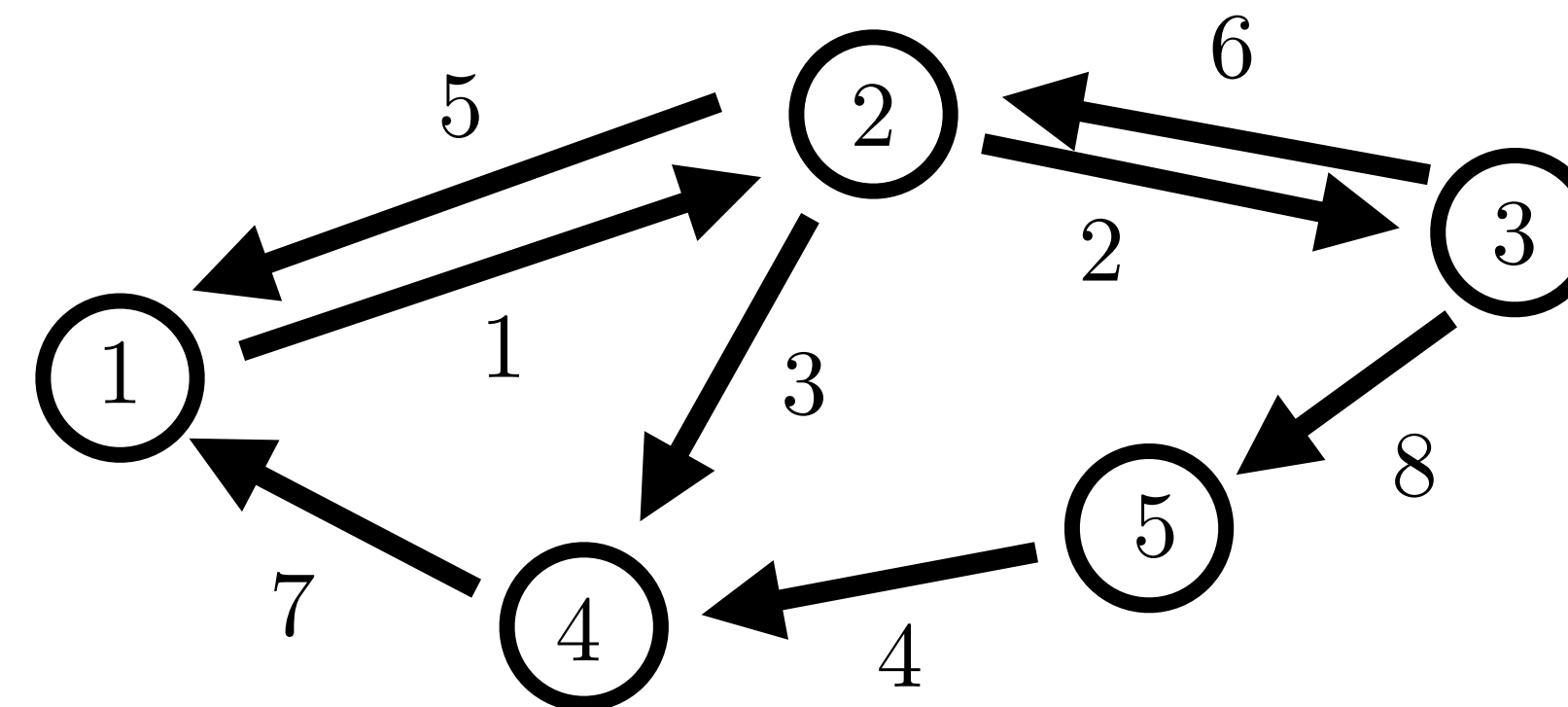
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**Laplacian**      $L = DD^T$

**Action:**  $Lu = \underbrace{\begin{bmatrix} D \end{bmatrix} \underbrace{\begin{bmatrix} D^T \end{bmatrix}}_{\text{...tension created in edges}} \begin{bmatrix} | \\ | \\ u \\ | \\ | \end{bmatrix}}_{\text{... summed resulting tension on nodes}}$      “heights” of nodes

...tension created in edges

... summed resulting tension on nodes

# Graph Laplacians

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

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**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

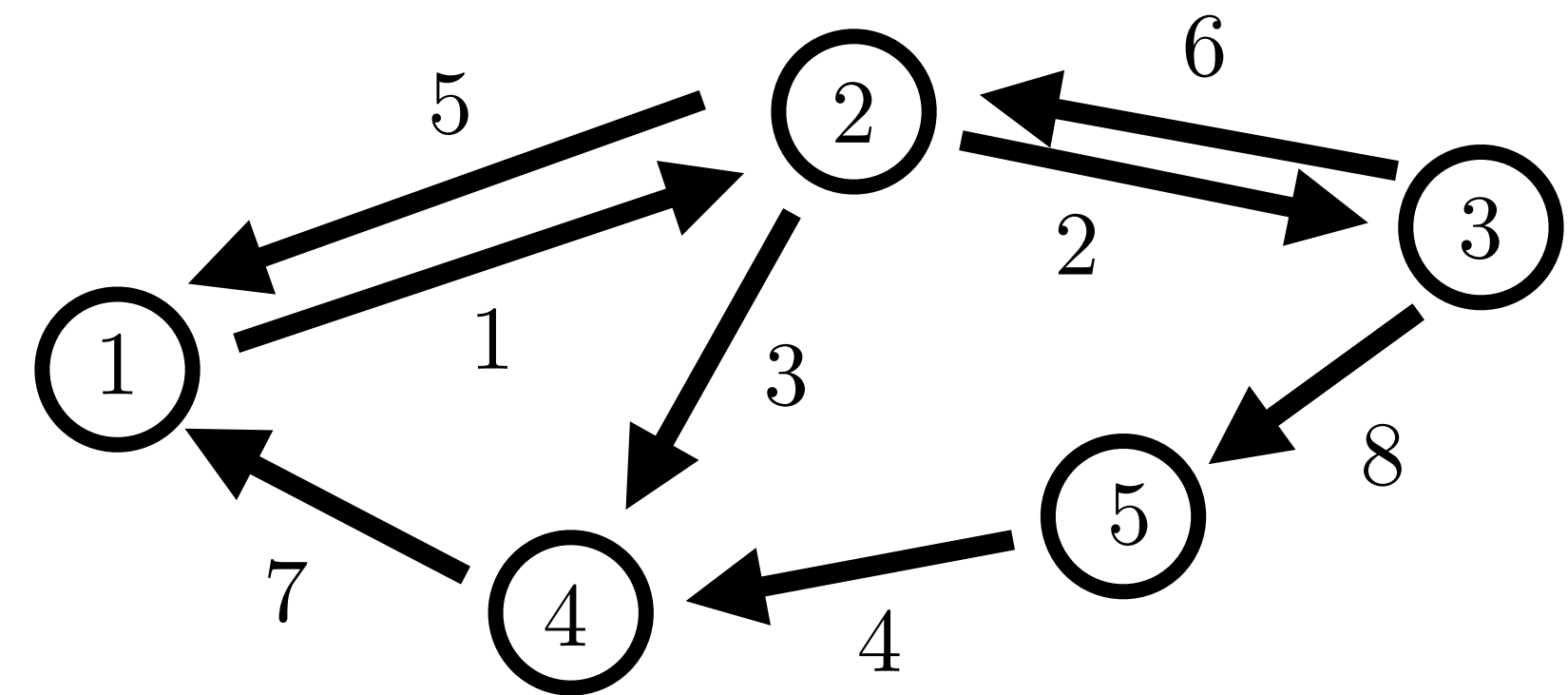
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$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



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**Action:**  $Lu = \underbrace{\begin{bmatrix} D \end{bmatrix} \underbrace{\begin{bmatrix} D^T \end{bmatrix} \begin{bmatrix} | \\ | \\ u \\ | \\ | \end{bmatrix}}_{\text{...tension created in edges}}}_{\text{... summed resulting tension on nodes}}$      “heights” of nodes

... summed resulting tension on nodes

**Linear ODE**

$$\dot{u} = -Lu$$

*Eigenvectors are oscillation modes*

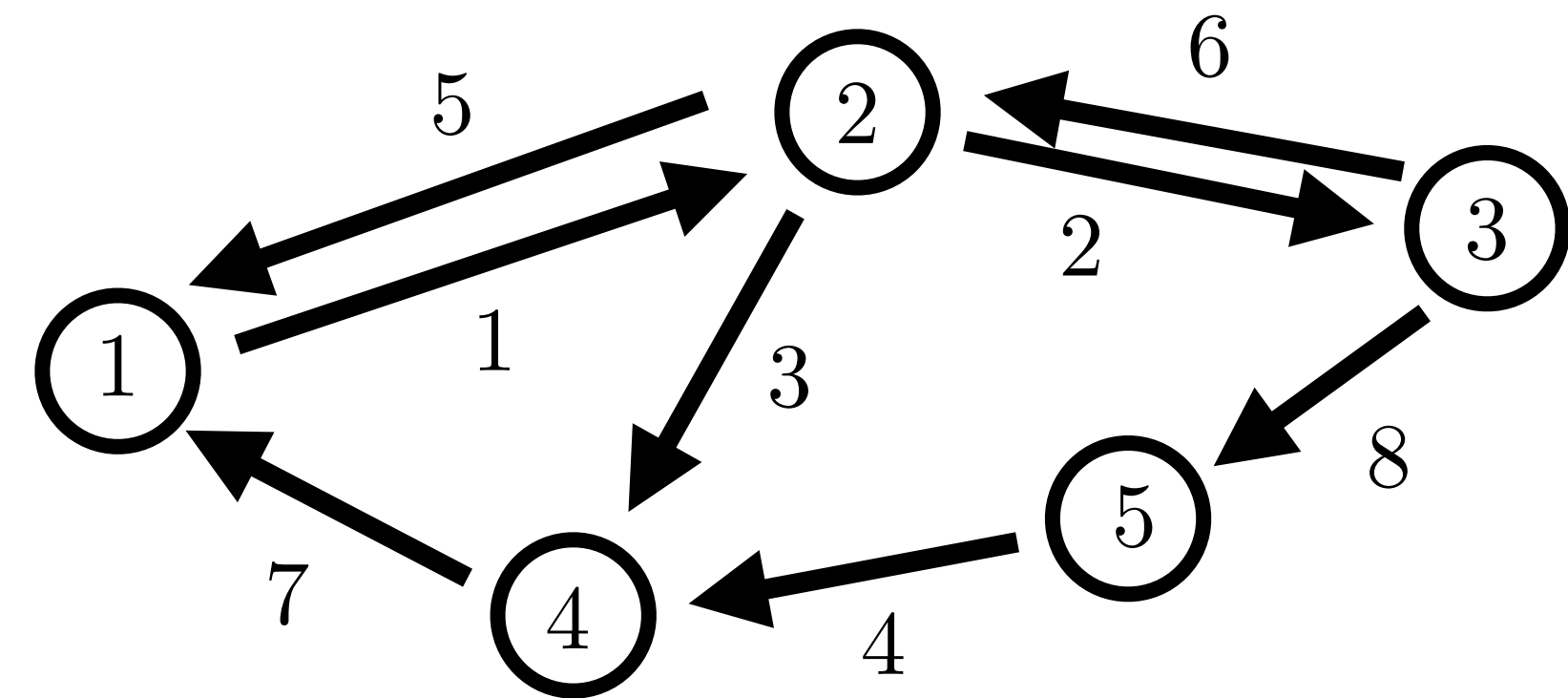
*“Vibration modes” of a graph*

# Graph Laplacians

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**Vertices**  $v \in \mathcal{V}$

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**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

**Laplacian**  $L = DD^T$

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$$L = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

**Laplacian** row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

$$= \begin{bmatrix} | & | \\ U' & \bar{\mathbf{1}} \\ | & | \end{bmatrix} \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} - & U'^T & - \\ - & \bar{\mathbf{1}}^T & - \end{bmatrix} \quad \bar{\mathbf{1}} = \begin{bmatrix} \mathbf{1}_{|\mathcal{V}_1|} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \mathbf{1}_{|\mathcal{V}_k|} \end{bmatrix}$$

Laplacian eigenvectors

(Incidence matrix left singular vectors)

**Edge-Laplacian** col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$

# Graph Laplacians

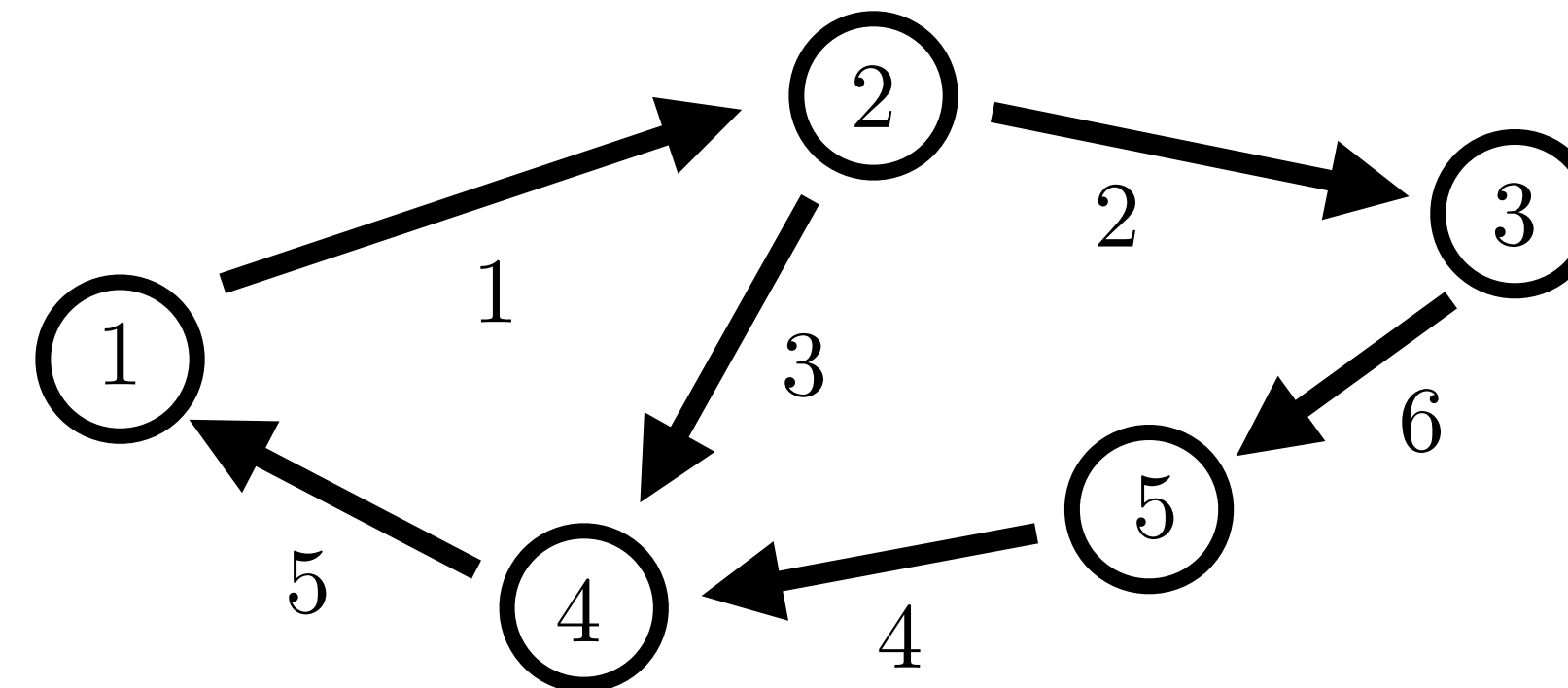
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**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$



**Laplacian**  $L = DD^T$

$$L = \begin{bmatrix} 2 & -1 & 0 & -1 & 0 \\ -1 & 3 & -1 & -1 & 0 \\ 0 & -1 & 2 & 0 & -1 \\ -1 & -1 & 0 & 3 & -1 \\ 0 & 0 & -1 & -1 & 2 \end{bmatrix}$$

**Incidence SVD**  $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

**Laplacian** row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

**Edge-Laplacian** col “shape” matrix (squared)

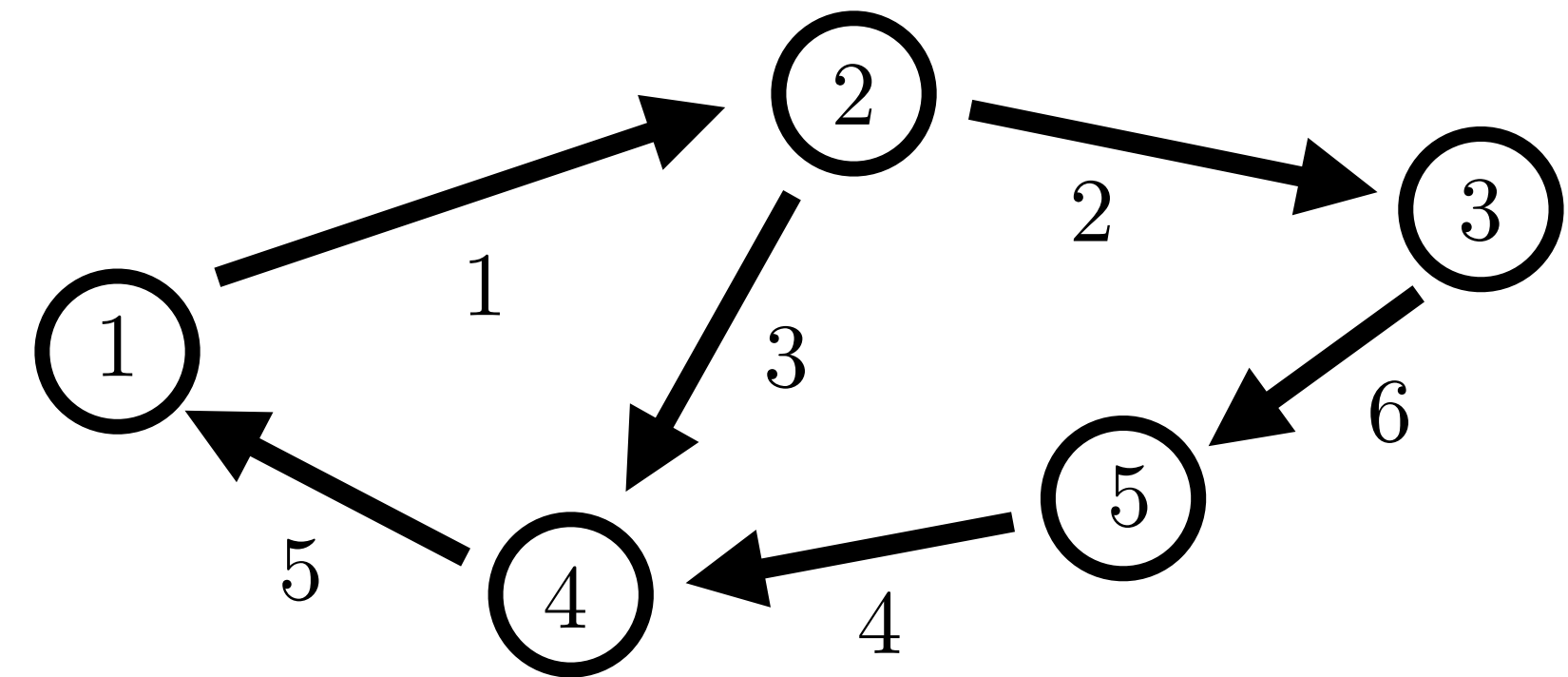
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# Degree & Adjacency Matrix

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$       $e = (v, v')$



**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

**Laplacian**  $L = DD^T$      Independent of edge direction

**Incidence SVD**  $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

$$L = \Delta - A = \begin{bmatrix} 2 & 0 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix} - \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 \end{bmatrix}$$

**Laplacian** row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

**Degree Matrix**  $[\Delta]_{vv} = |\mathcal{N}_v|$      diagonal

**Edge-Laplacian** col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$

**Adjacency Matrix**  $[A]_{vv'} = \begin{cases} 1 & ; \text{ if } e = (v, v') \in \mathcal{E} \\ 0 & ; \text{ otherwise} \end{cases}$

# Adjacency Matrix

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$   
**Vertices**  $v \in \mathcal{V}$   
**Edges**  $e \in \mathcal{E}$   $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

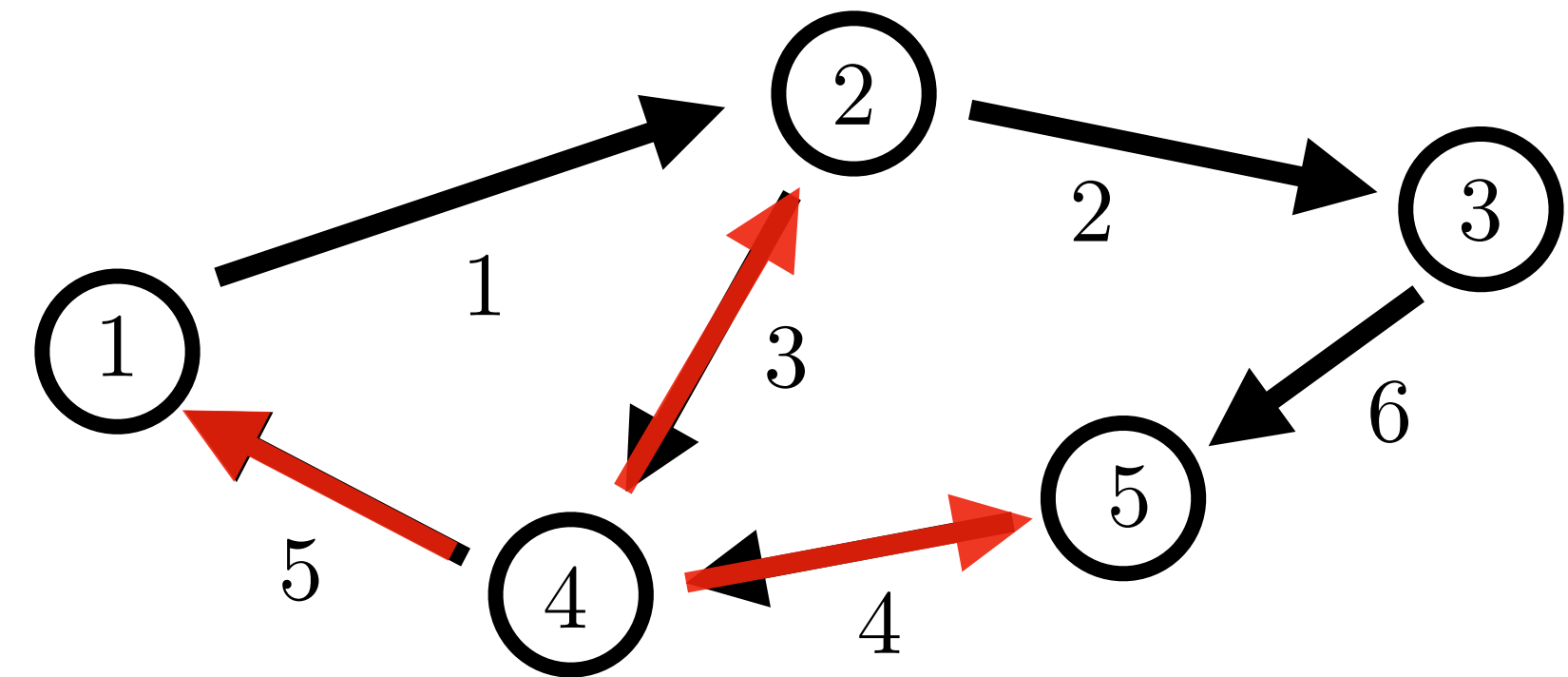
**Incidence SVD**  $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

**Laplacian** row "shape" matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

**Edge-Laplacian** col "shape" matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$

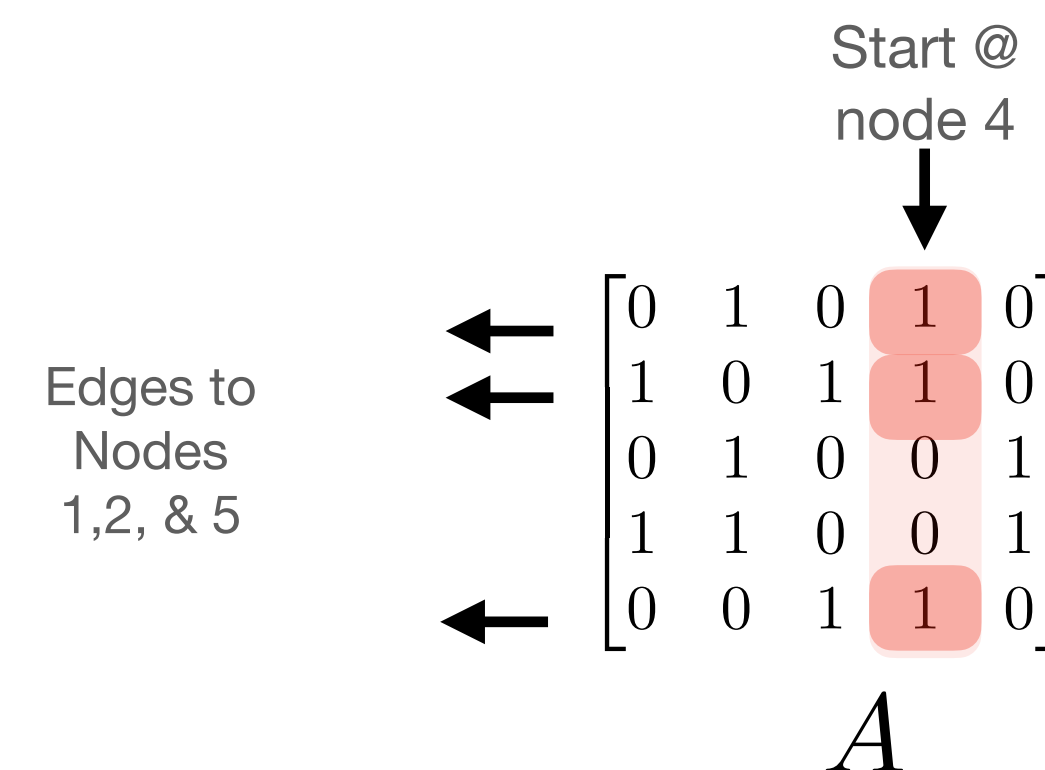


**Laplacian**  $L = DD^T = \Delta - A$

**Degree Matrix**  $[\Delta]_{vv} = |\mathcal{N}_v|$  **diagonal**

**Adjacency Matrix**  $[A]_{vv'} = \begin{cases} 1 & ; \text{if } e = (v, v') \in \mathcal{E} \\ 0 & ; \text{otherwise} \end{cases}$

**Adjacency Matrix**



# Adjacency Matrix

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$   
**Vertices**  $v \in \mathcal{V}$   
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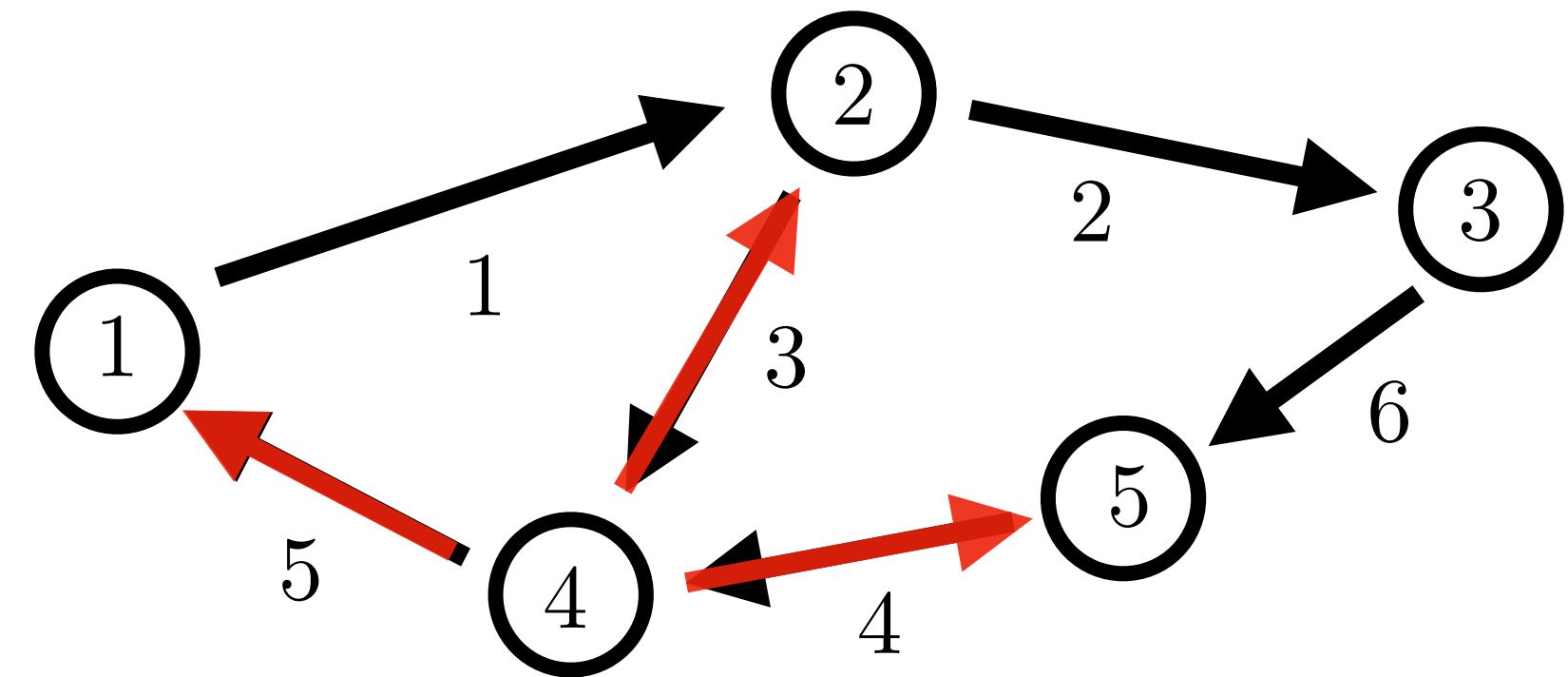
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$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$

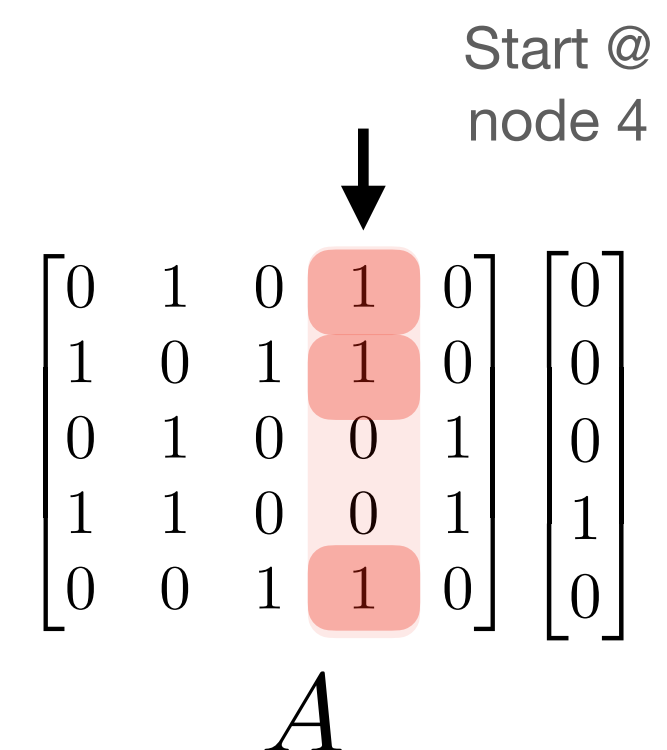


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**Degree Matrix**  $[\Delta]_{vv} = |\mathcal{N}_v|$  **diagonal**

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**Powers of Adjacency**





# Adjacency Matrix

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$   
**Vertices**  $v \in \mathcal{V}$   
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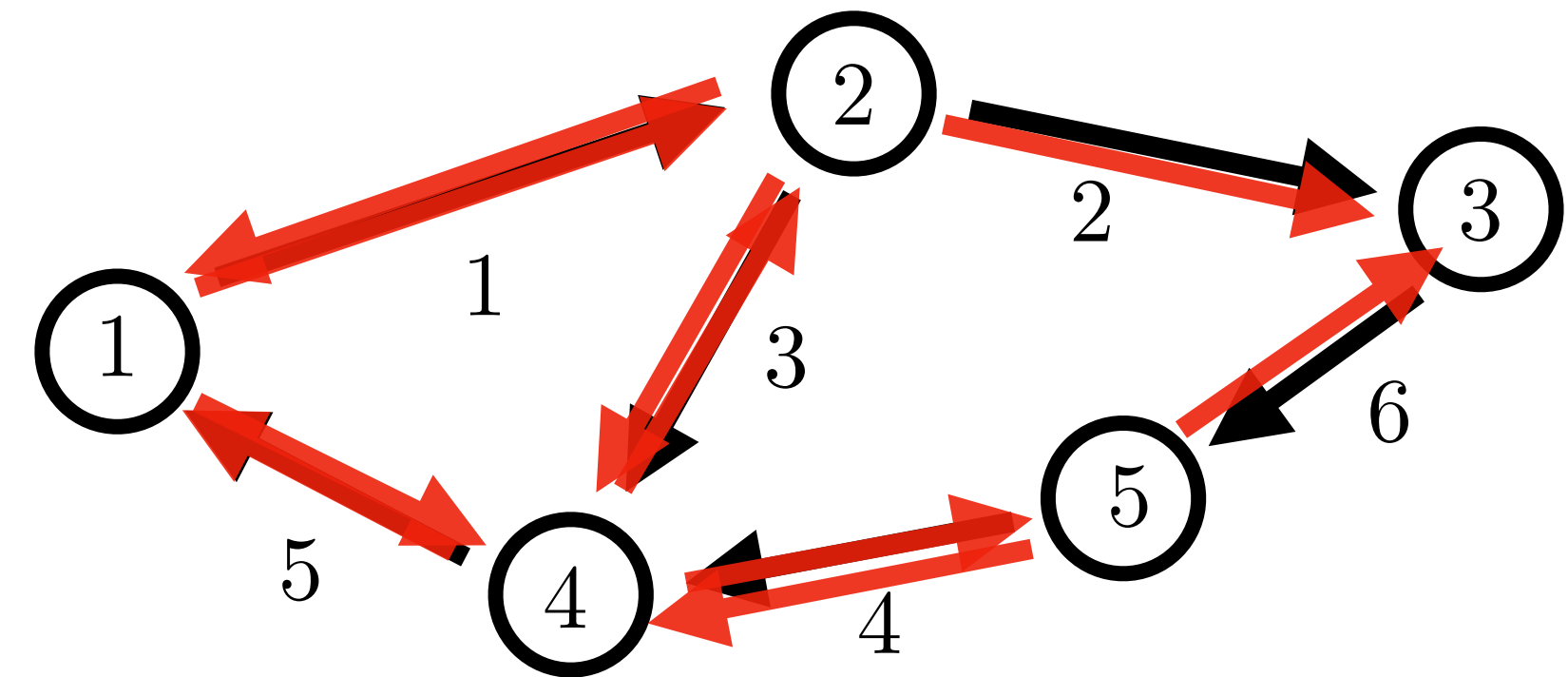
**Incidence SVD**  $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

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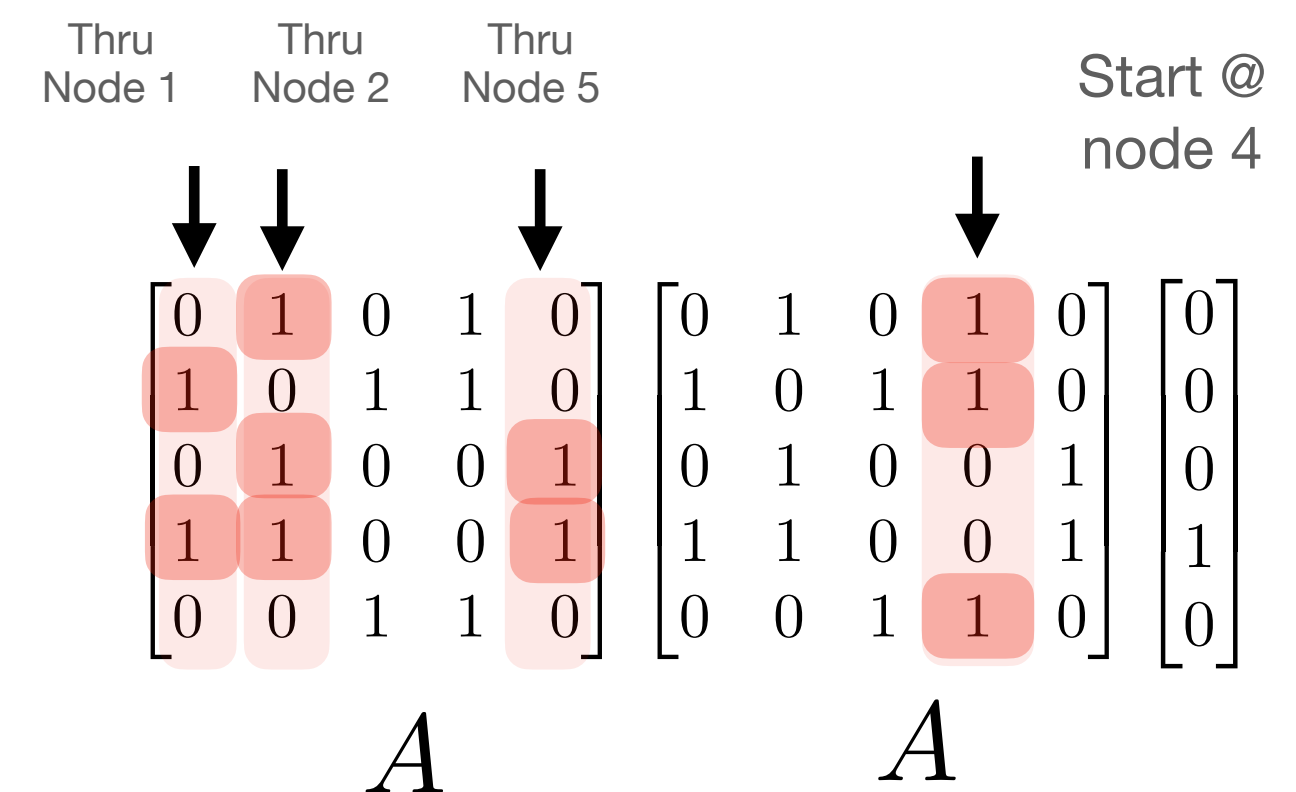


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**Degree Matrix**  $[\Delta]_{vv} = |\mathcal{N}_v|$  **diagonal**

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**Powers of Adjacency**



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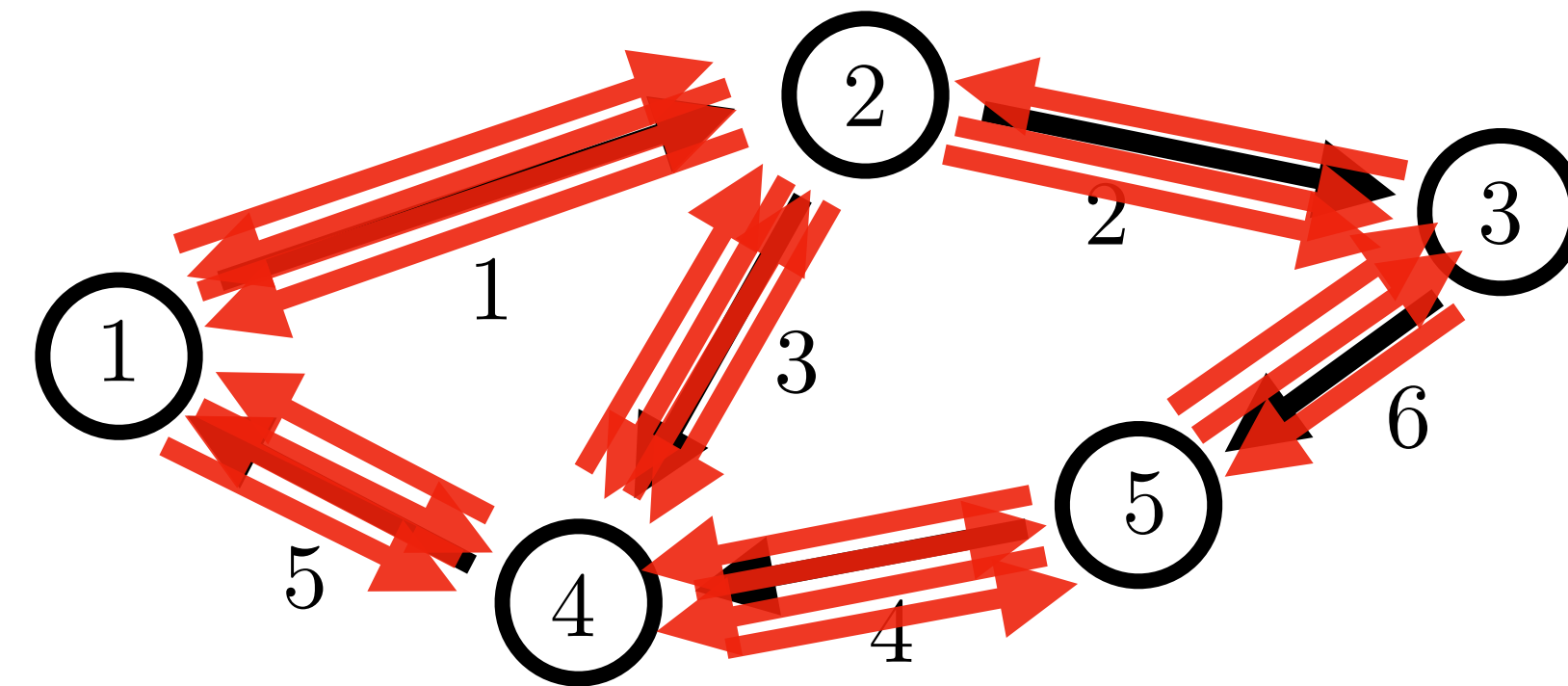
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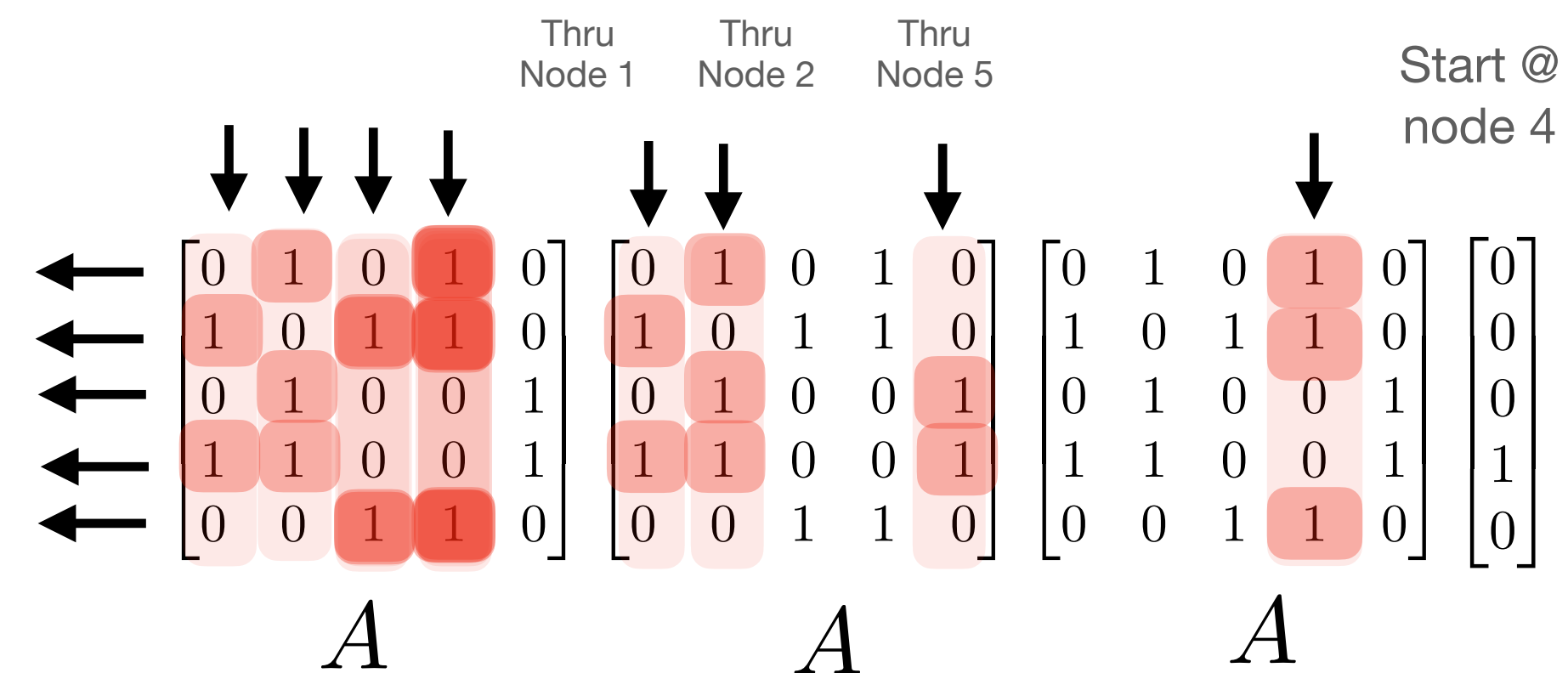


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**Degree Matrix**  $[\Delta]_{vv} = |\mathcal{N}_v|$      **diagonal**

**Adjacency Matrix**  $[A]_{vv'} = \begin{cases} 1 & ; \text{ if } e = (v, v') \in \mathcal{E} \\ 0 & ; \text{ otherwise} \end{cases}$

**Powers of Adjacency**



# Adjacency Matrix

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$   
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$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

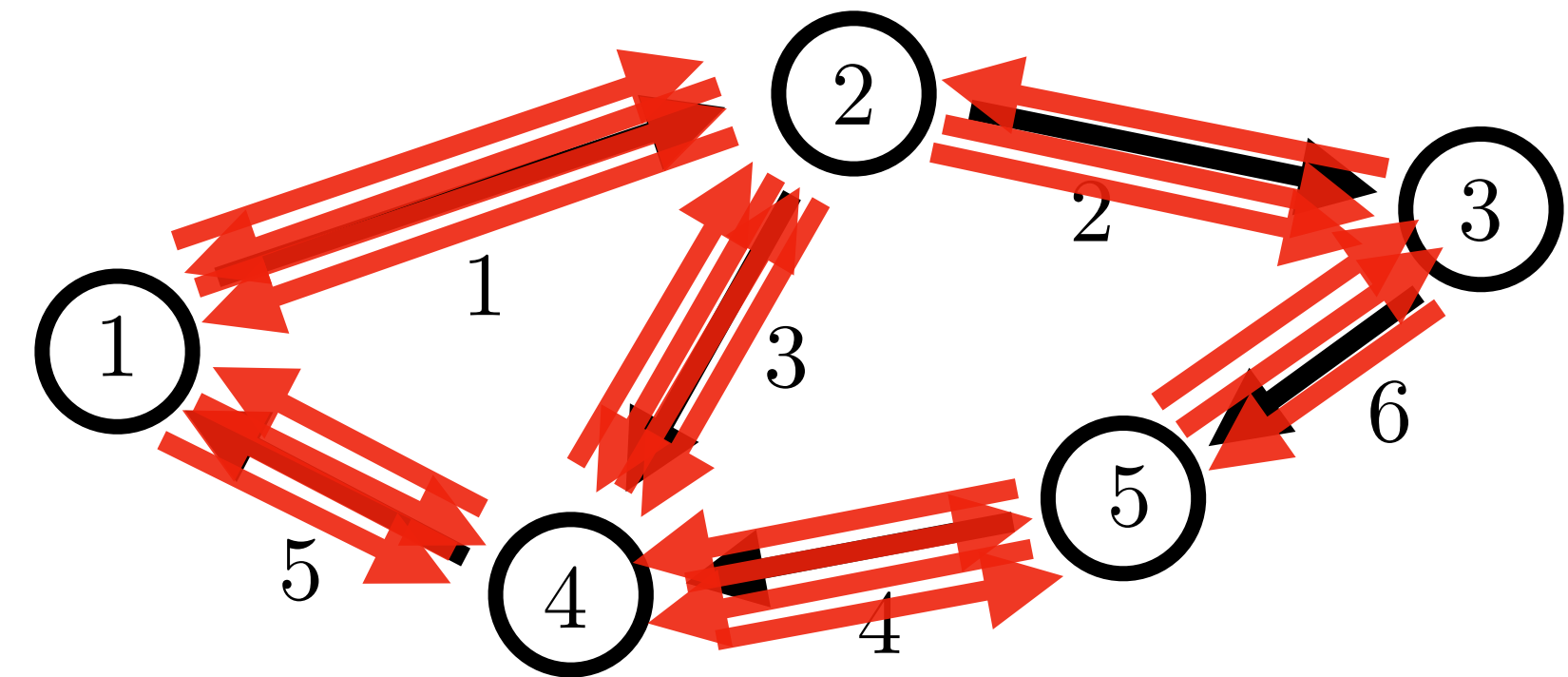
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$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



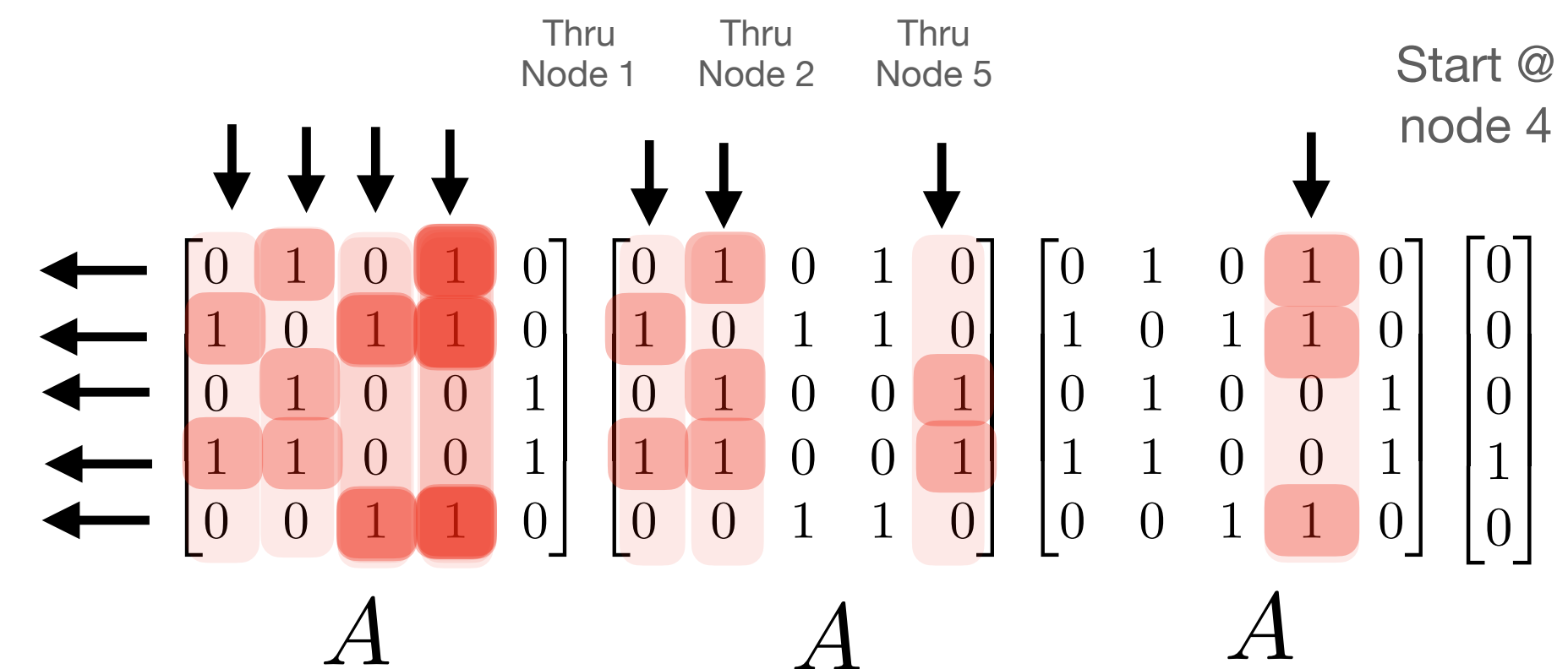
**Laplacian**  $L = DD^T = \Delta - A$

**Degree Matrix**  $[\Delta]_{vv} = |\mathcal{N}_v|$  **diagonal**

**Adjacency Matrix**  $[A]_{vv'} = \begin{cases} 1 & ; \text{ if } e = (v, v') \in \mathcal{E} \\ 0 & ; \text{ otherwise} \end{cases}$

**Powers of Adjacency**

# 3-step paths from node 4 to node 1  
 # 3-step paths from node 4 to node 2  
 ⋮  
 # 3-step paths from node 4 to node 5



# Adjacency Matrix

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$   
**Vertices**  $v \in \mathcal{V}$   
**Edges**  $e \in \mathcal{E}$       $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 \\ 0 & 0 & 1 & 1 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 1 \end{bmatrix}$$

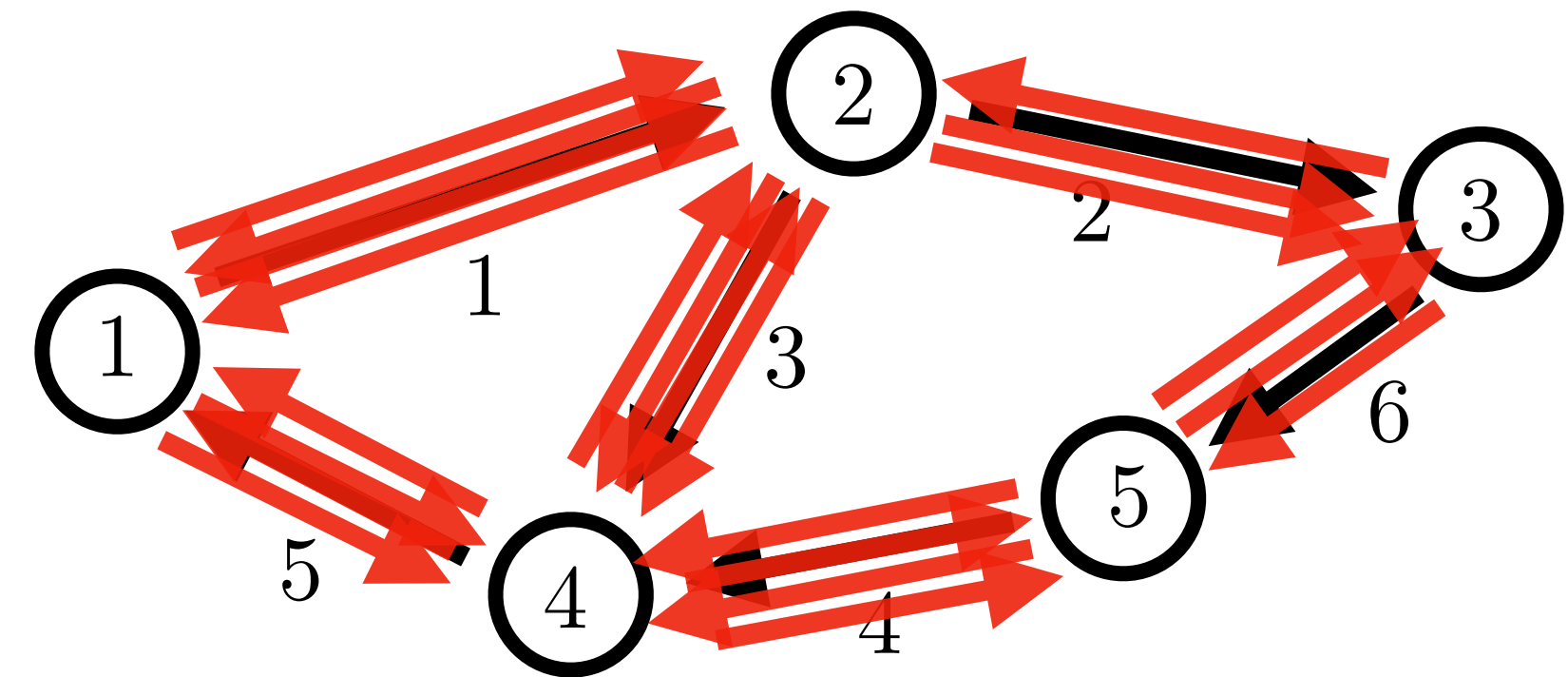
**Incidence SVD**  $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

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$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

**Edge-Laplacian** col "shape" matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



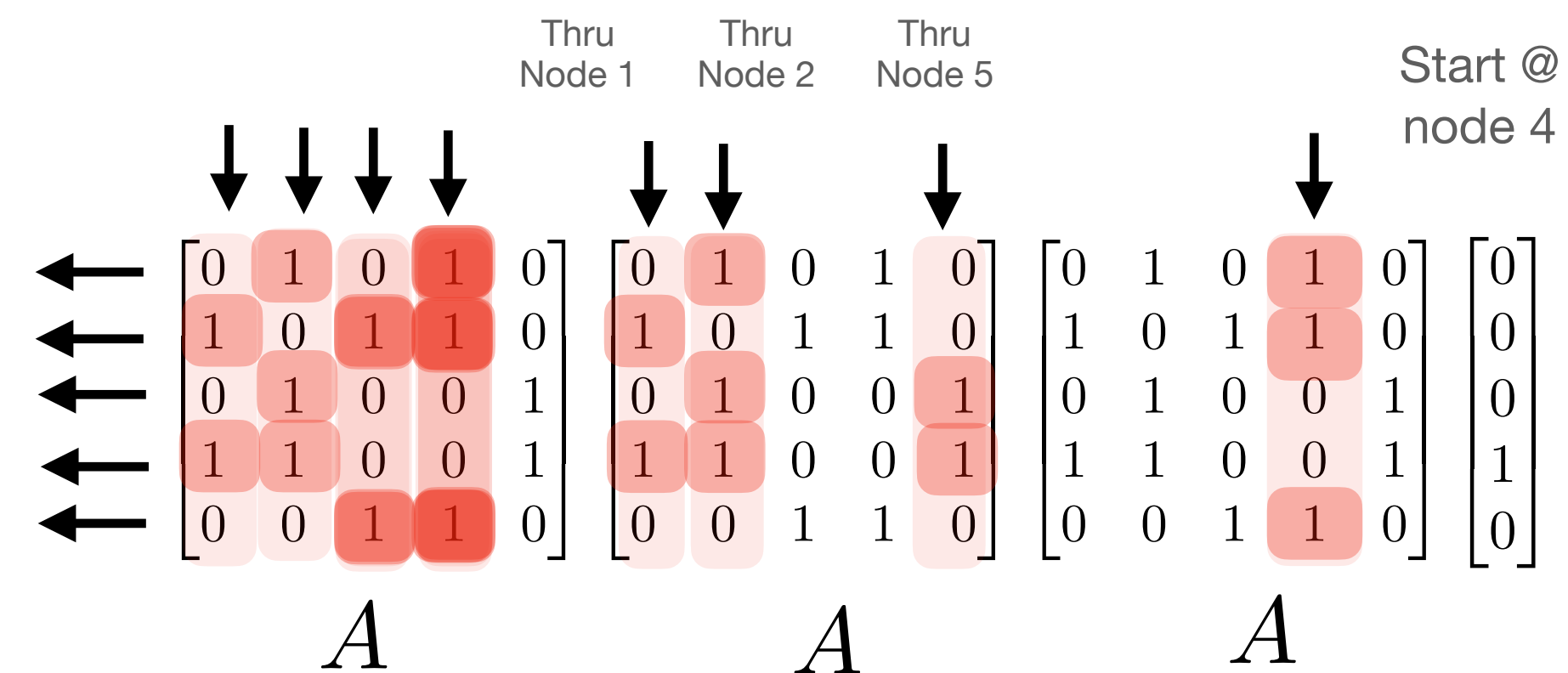
**Laplacian**  $L = DD^T = \Delta - A$

**Degree Matrix**  $[\Delta]_{vv} = |\mathcal{N}_v|$      **diagonal**

**Adjacency Matrix**  $[A]_{vv'} = \begin{cases} 1 & ; \text{ if } e = (v, v') \in \mathcal{E} \\ 0 & ; \text{ otherwise} \end{cases}$

**Powers of Adjacency**

$[A^k]_{vv'}$   
 # k-step paths from node v to node v'

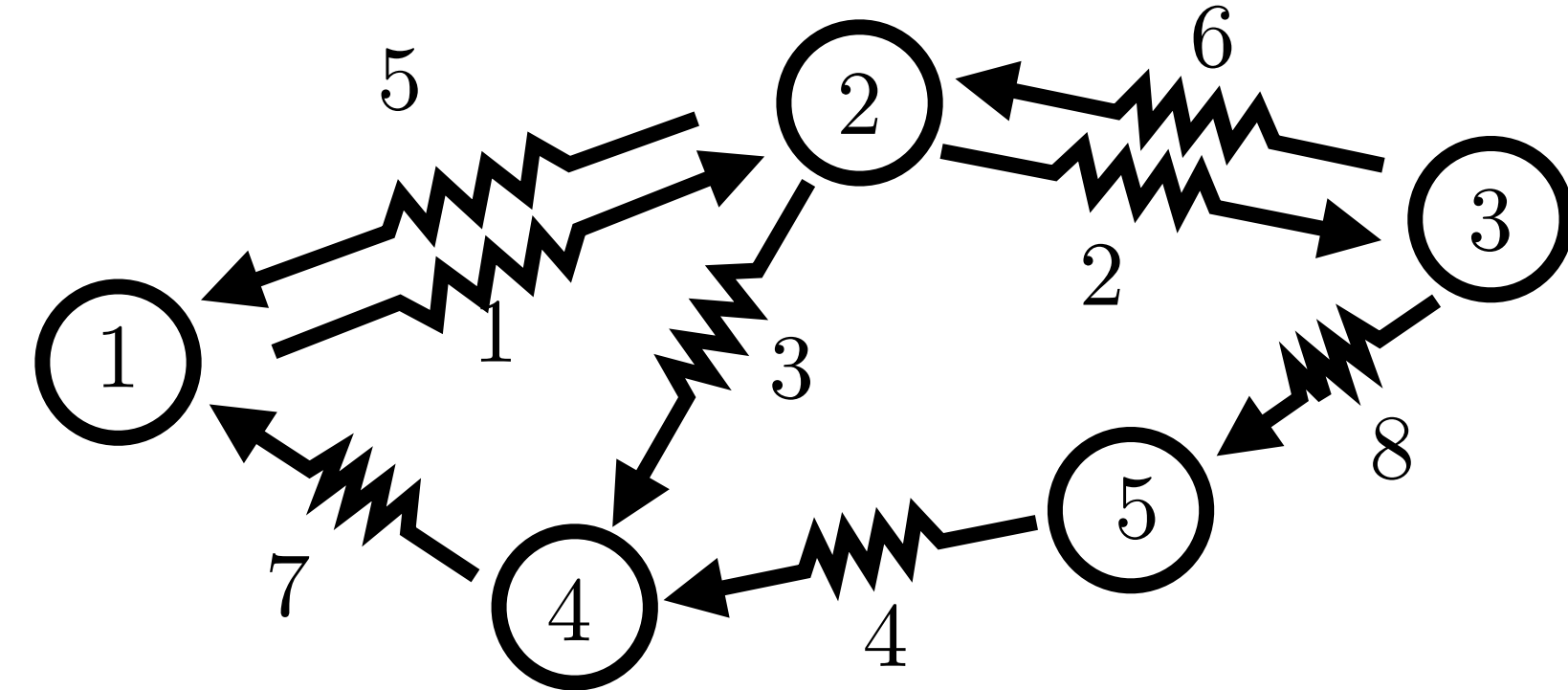


# Graph Laplacians

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$       $e = (v, v')$



**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

**Weighted Laplacian**  $L_W = DW D^T$

**Incidence SVD**  $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

$$L_W = DW D^T = U_W \begin{bmatrix} \Sigma_W^2 & 0 \\ 0 & 0 \end{bmatrix} U_W^T$$

**Laplacian** row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

$$= \begin{bmatrix} | & | \\ U'_W & \bar{\mathbf{1}} \\ | & | \end{bmatrix} \begin{bmatrix} \Sigma_W^2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} - & U'^T_W & - \\ - & \bar{\mathbf{1}}^T & - \end{bmatrix}^T \quad \bar{\mathbf{1}} = \begin{bmatrix} \mathbf{1}_{|\mathcal{V}_1|} & \cdots & 0 \\ \vdots & \cdots & \vdots \\ 0 & \cdots & \mathbf{1}_{|\mathcal{V}_k|} \end{bmatrix}$$

**Edge-Laplacian** col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$

# Graph Laplacians

**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$       $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$

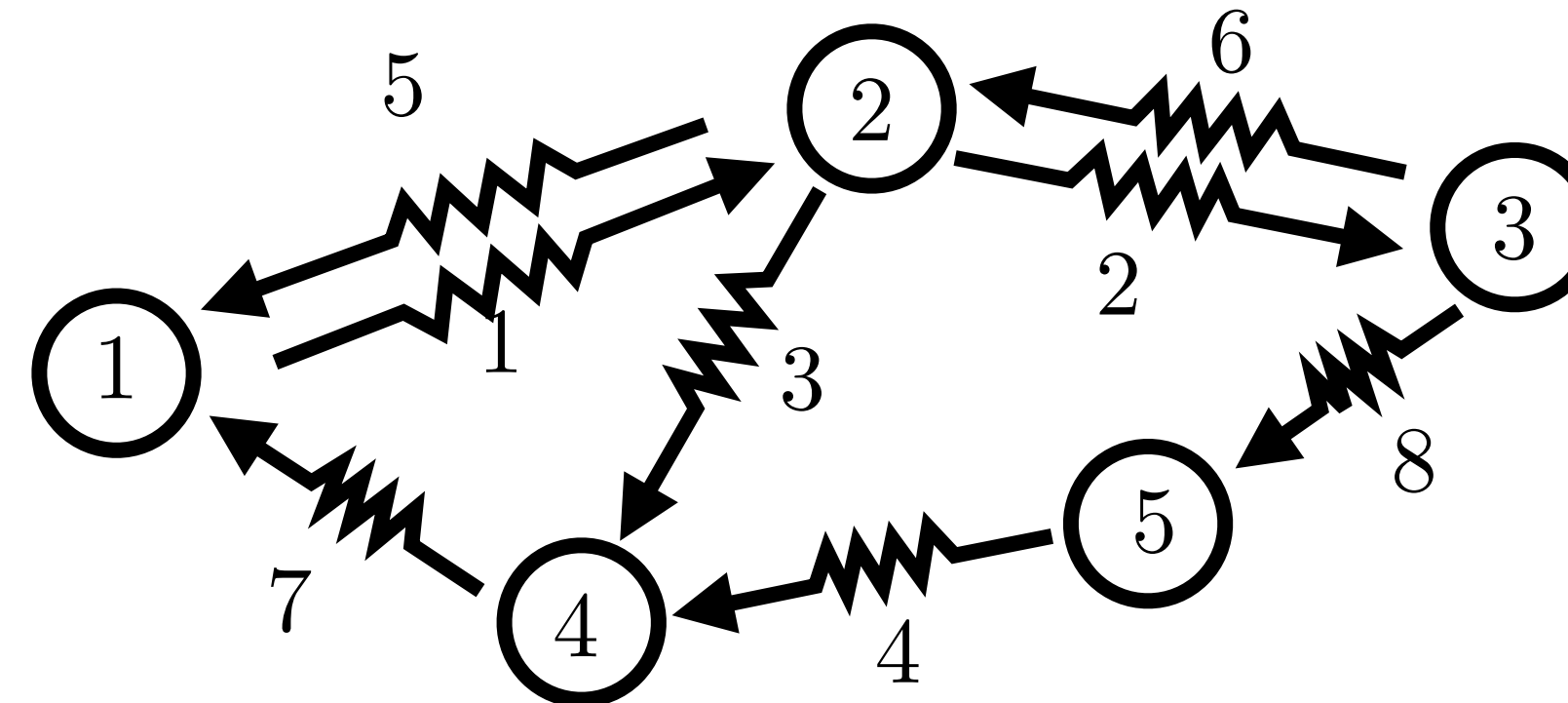
**Incidence SVD**      $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

**Laplacian**     row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

**Edge-Laplacian**     col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



**Weighted Laplacian**      $L_W = DD^T W$

**Action:**  $L_W u = \underbrace{\left[ D \right] \left[ W \right] \left[ D^T \right]}_{\text{...tension created in edges scaled by weights}} \begin{bmatrix} | \\ u \\ | \end{bmatrix}$      “heights” of nodes

...tension created in edges scaled by weights

... summed resulting tension on nodes

# Graph Laplacians

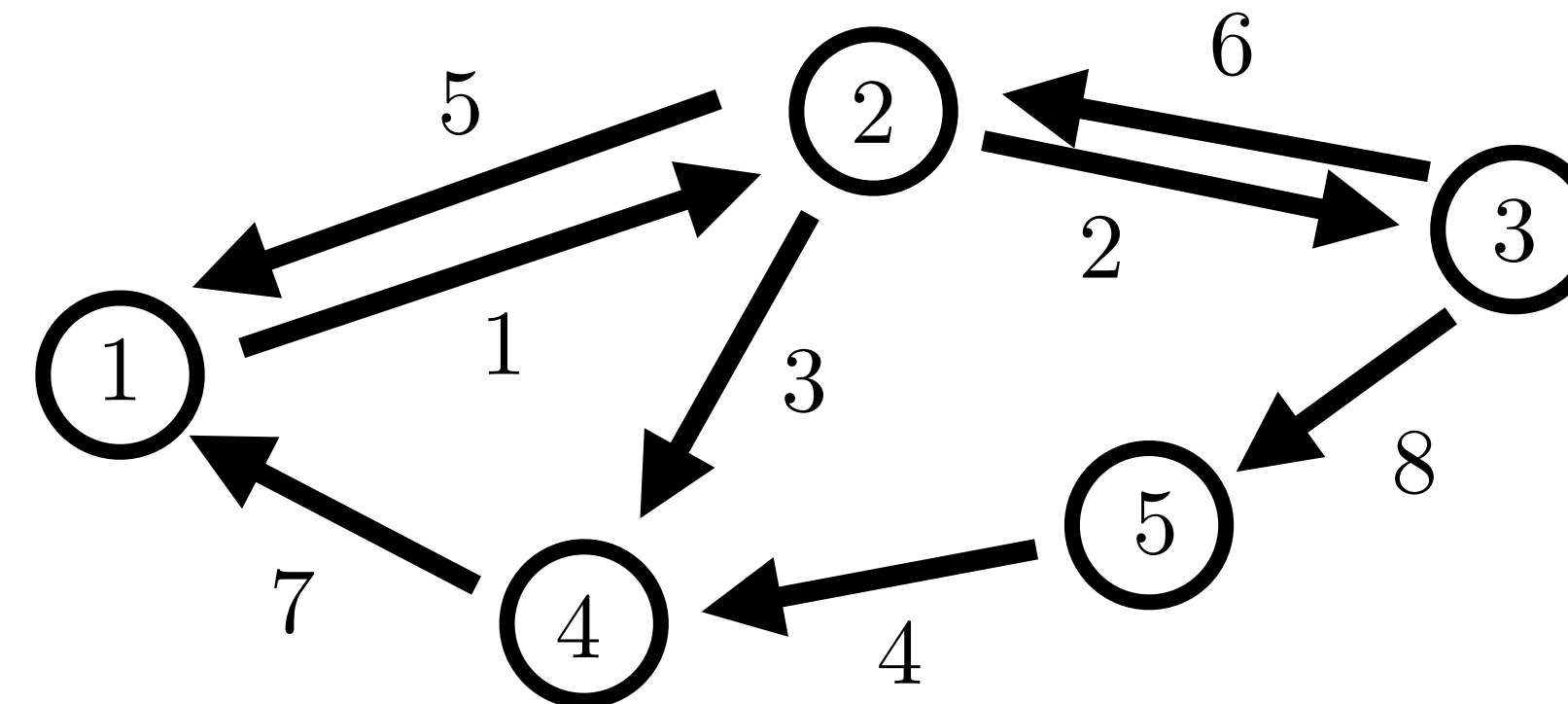
**Graph:**  $\mathcal{G} = (\mathcal{V}, \mathcal{E})$

**Vertices**  $v \in \mathcal{V}$

**Edges**  $e \in \mathcal{E}$       $e = (v, v')$

**Incidence Matrix:**  $D \in \mathbb{R}^{|\mathcal{V}| \times |\mathcal{E}|}$

$$D = \begin{bmatrix} -1 & 0 & 0 & 0 & 1 & 0 & 1 & 0 \\ 1 & -1 & -1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & -1 & 0 & -1 \\ 0 & 0 & 1 & 1 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 \end{bmatrix}$$



**Edge Laplacian**  $L_e = D^T D$

**Incidence SVD**  $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

**Laplacian** row “shape” matrix (squared)

$$L = DD^T = U \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} U^T$$

**Edge-Laplacian** col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$

# Graph Laplacians

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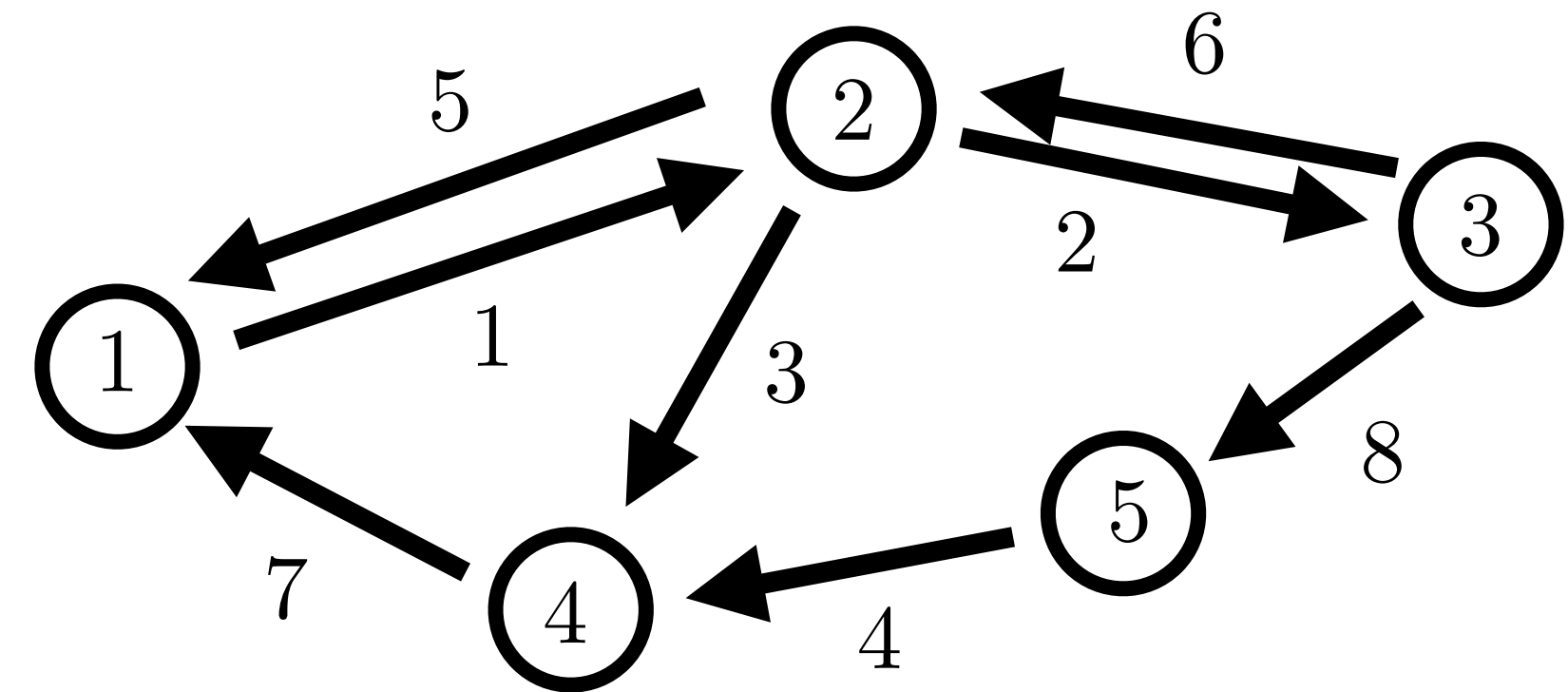
**Incidence SVD**      $D = U \begin{bmatrix} \Sigma & 0 \\ 0 & 0 \end{bmatrix} V^T$

**Laplacian**     row “shape” matrix (squared)

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**Edge-Laplacian**     col “shape” matrix (squared)

$$L_e = D^T D = V \begin{bmatrix} \Sigma^2 & 0 \\ 0 & 0 \end{bmatrix} V^T$$



**Edge Laplacian**      $L_e = D^T D$

**Action:**  $L_e \tau = \underbrace{\begin{bmatrix} D^T \end{bmatrix} \begin{bmatrix} D \end{bmatrix}}_{\text{...summed tension on nodes}} \begin{bmatrix} | \\ \tau \\ | \end{bmatrix}$  “Tension” in edges

...summed tension on nodes

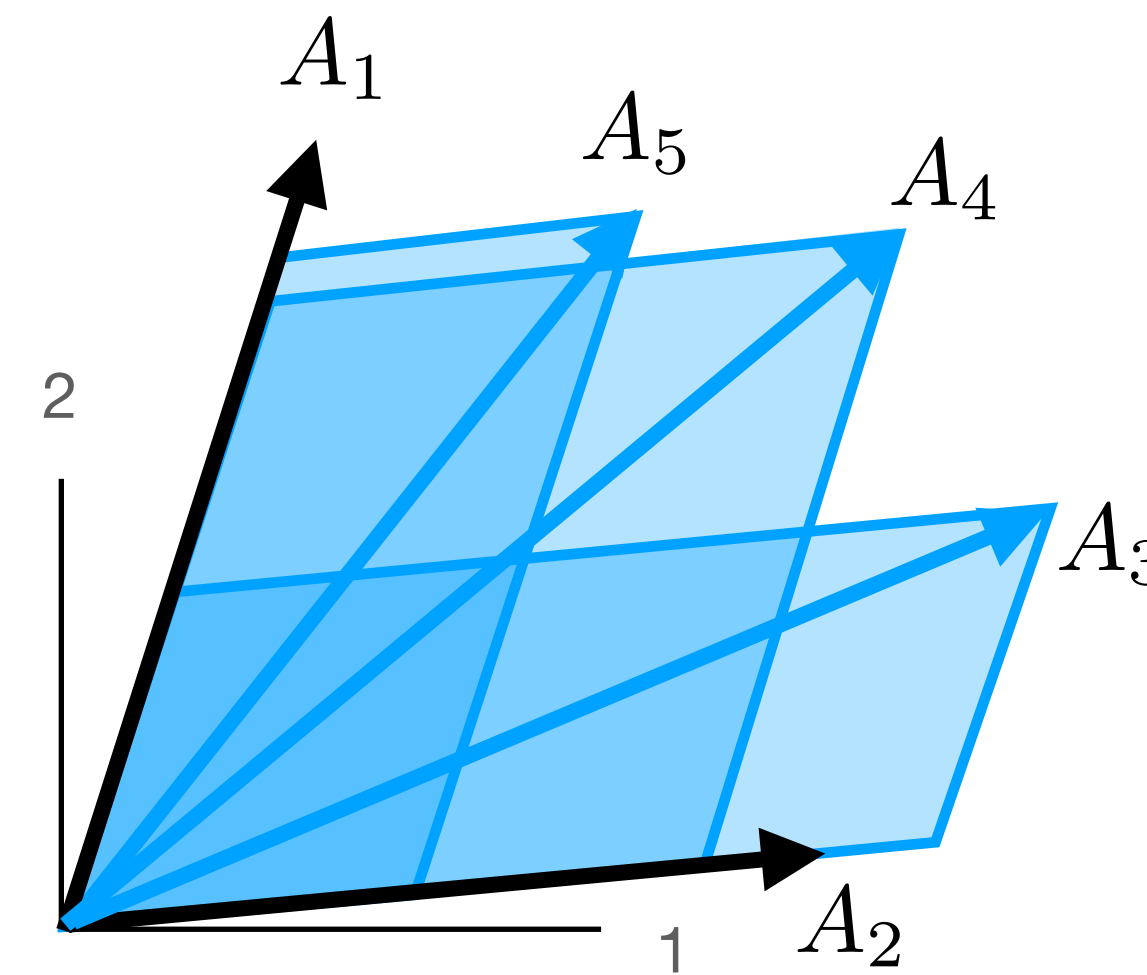
... differential in tension along edges



# REVIEW: Nullspace - Column Geometry (Computation)

$$A = \begin{bmatrix} A' & A'' \end{bmatrix} = \begin{bmatrix} | & | & | & | & | \\ A_1 & A_2 & A_3 & A_4 & A_5 \\ | & | & | & | & | \end{bmatrix}$$

$A'$  Linear independent columns       $A''$  Linear dependent columns



Coordinates of linear dependent columns:

$$B = \begin{bmatrix} B_{13} & B_{14} & B_{15} \\ B_{23} & B_{24} & B_{25} \end{bmatrix} \quad A'' = A' B$$

$$A = \begin{bmatrix} A' & A' B \end{bmatrix} = A' \begin{bmatrix} I & B \end{bmatrix}$$

$$\begin{bmatrix} | & | & | \\ A_3 & A_4 & A_5 \\ | & | & | \end{bmatrix} = \begin{bmatrix} | & | & | & | & | \\ A_1 B_{13} + A_2 B_{23} & A_1 B_{14} + A_2 B_{24} & A_1 B_{15} + A_2 B_{25} \\ | & | & | & | & | \end{bmatrix}$$

Nullspace basis:

$$AN = 0 \quad N = \begin{bmatrix} B \\ -I \end{bmatrix} = \begin{bmatrix} B_{13} & B_{14} & B_{15} \\ B_{23} & B_{24} & B_{25} \\ -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

**PROOF:**

**Lin ind:**  $\begin{bmatrix} 0 \\ 0 \end{bmatrix} = Nz = \begin{bmatrix} B \\ -I \end{bmatrix} z = \begin{bmatrix} Bz \\ -z \end{bmatrix} \Rightarrow z = 0$

**Span:**  $x \in \mathcal{N}(A)$   $A'$  lin. ind.

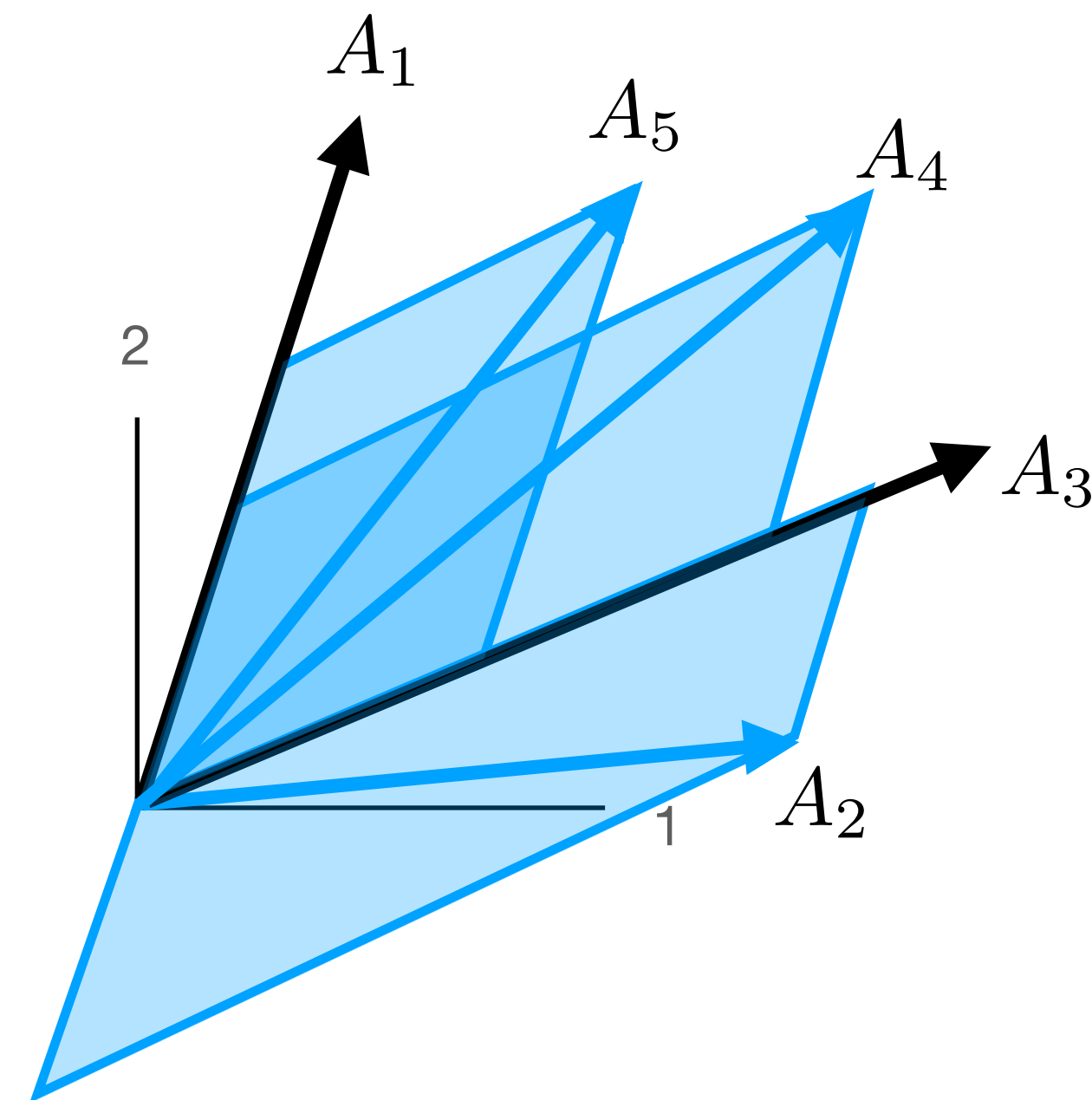
$$Ax = \begin{bmatrix} I & B \end{bmatrix} \begin{bmatrix} x' \\ x'' \end{bmatrix} = A'(x' + Bx'') \Rightarrow x' + Bx'' = 0$$

$$\Rightarrow x = \begin{bmatrix} x' \\ x'' \end{bmatrix} = \begin{bmatrix} B \\ -I \end{bmatrix} (-x'')$$

# REVIEW: Nullspace - Column Geometry (Computation)

$$A = \begin{bmatrix} A' & A'' \end{bmatrix} = \begin{bmatrix} | & | & | & | & | \\ A_1 & A_2 & A_3 & A_4 & A_5 \\ | & | & | & | & | \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{A' \text{ Linear independent columns}} \quad \underbrace{\hspace{10em}}_{A'' \text{ Linear dependent columns}}$



Coordinates of linear dependent columns:

$$B = \begin{bmatrix} B_{13} & B_{14} & B_{15} \\ B_{33} & B_{34} & B_{35} \end{bmatrix} \quad A'' = A' B$$

$$A = \begin{bmatrix} A' & A' B \end{bmatrix} P = A' \begin{bmatrix} I & B \end{bmatrix} P$$

$$\begin{bmatrix} | & | & | \\ A_2 & A_4 & A_5 \\ | & | & | \end{bmatrix} = \begin{bmatrix} | & | & | & | & | \\ A_1 B_{12} + A_3 B_{32} & A_1 B_{14} + A_3 B_{34} & A_1 B_{15} + A_3 B_{35} \\ | & | & | & | & | \end{bmatrix}$$

Nullspace basis:

$$AN = 0 \quad N = P^{-1} \begin{bmatrix} B \\ -I \end{bmatrix} = \begin{bmatrix} B_{13} & B_{14} & B_{15} \\ -1 & 0 & 0 \\ B_{33} & B_{34} & B_{35} \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

**PROOF:**

Lin ind:  $\begin{bmatrix} 0 \\ 0 \end{bmatrix} = Nz = \begin{bmatrix} B \\ -I \end{bmatrix} z = \begin{bmatrix} Bz \\ -z \end{bmatrix} \Rightarrow z = 0$

Span:  $x \in \mathcal{N}(A)$

$$Ax = \begin{bmatrix} I & B \end{bmatrix} \begin{bmatrix} x' \\ x'' \end{bmatrix} = A'(x' + Bx'') \xRightarrow{A' \text{ lin. ind.}} x' + Bx'' = 0$$

$$\Rightarrow x = \begin{bmatrix} x' \\ x'' \end{bmatrix} = \begin{bmatrix} B \\ -I \end{bmatrix} (-x'')$$

# REVIEW: Nullspace - Column Geometry (Computation)

$$A = \begin{bmatrix} A' & A'' \end{bmatrix} = \begin{bmatrix} | & | & | & | & | \\ A_1 & A_2 & A_3 & A_4 & A_5 \\ | & | & | & | & | \end{bmatrix}$$

$\underbrace{\hspace{10em}}_{A' \text{ Linear independent columns}} \quad \underbrace{\hspace{10em}}_{A'' \text{ Linear dependent columns}}$

Coordinates of linear dependent columns:

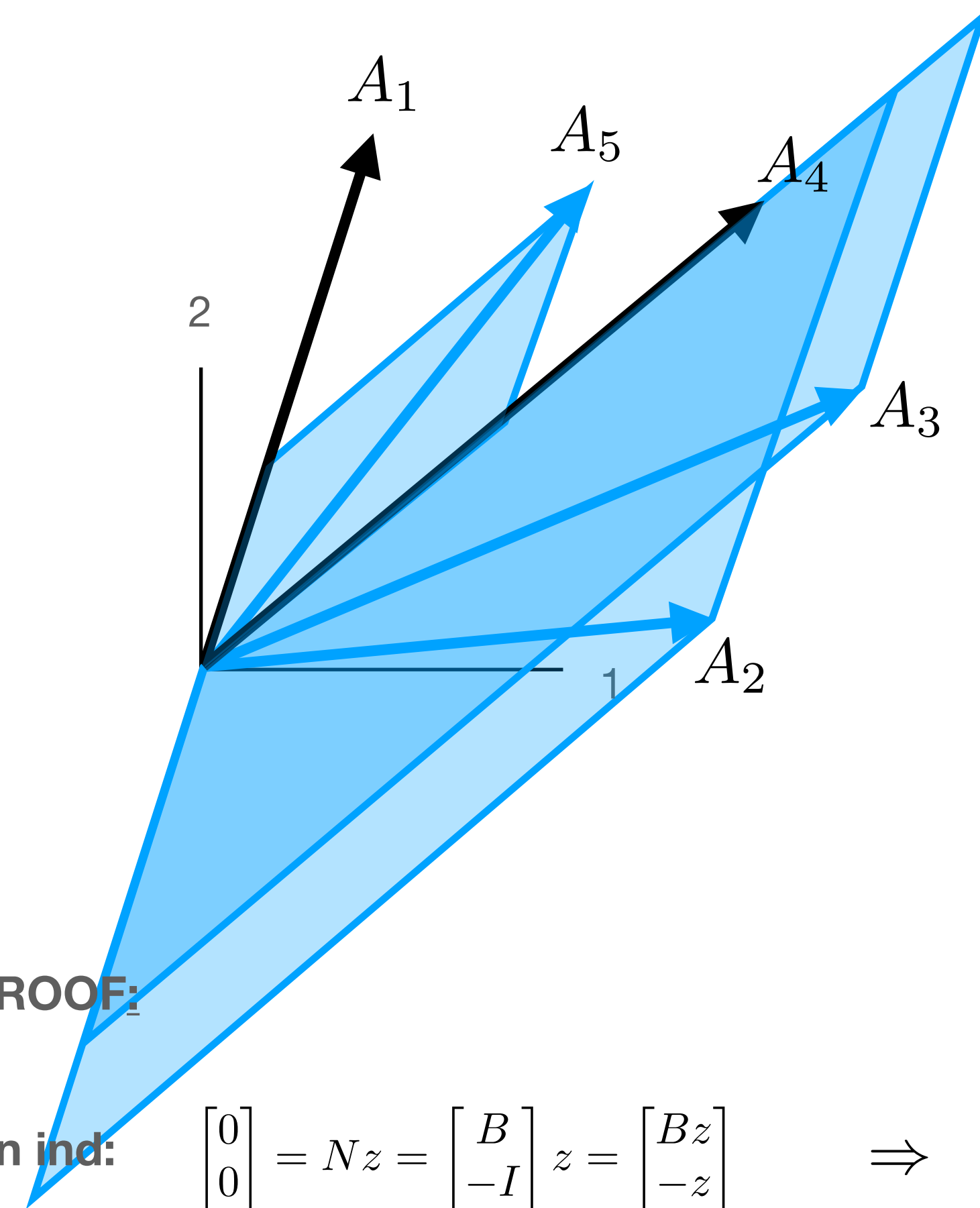
$$B = \begin{bmatrix} B_{12} & B_{13} & B_{15} \\ B_{42} & B_{43} & B_{45} \end{bmatrix} \quad A'' = A' B$$

$$A = \begin{bmatrix} A' & A' B \end{bmatrix} P = A' \begin{bmatrix} I & B \end{bmatrix} P$$

$$\begin{bmatrix} | & | & | \\ A_2 & A_3 & A_5 \\ | & | & | \end{bmatrix} = \begin{bmatrix} | & | & | & | & | \\ A_1 B_{12} + A_4 B_{42} & A_1 B_{13} + A_4 B_{43} & A_1 B_{15} + A_4 B_{45} \\ | & | & | & | & | \end{bmatrix}$$

Nullspace basis:

$$AN = 0 \quad N = P^{-1} \begin{bmatrix} B \\ -I \end{bmatrix} = \begin{bmatrix} B_{13} & B_{14} & B_{15} \\ -1 & 0 & 0 \\ 0 & -1 & 0 \\ B_{43} & B_{44} & B_{45} \\ 0 & 0 & -1 \end{bmatrix}$$



**PROOF:**

**Lin ind:**  $\begin{bmatrix} 0 \\ 0 \end{bmatrix} = Nz = \begin{bmatrix} B \\ -I \end{bmatrix} z = \begin{bmatrix} Bz \\ -z \end{bmatrix} \Rightarrow z = 0$

**Span:**  $x \in \mathcal{N}(A)$   $A'$  lin. ind.

$$Ax = \begin{bmatrix} I & B \end{bmatrix} \begin{bmatrix} x' \\ x'' \end{bmatrix} = A'(x' + Bx'') \Rightarrow x' + Bx'' = 0$$

$$\Rightarrow x = \begin{bmatrix} x' \\ x'' \end{bmatrix} = \begin{bmatrix} B \\ -I \end{bmatrix} (-x'')$$